Regularity Properties of the Euler Equations in Lagrangian Variables

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The Euler equations

 We consider the Cauchy problem for the ideal incompressible homogeneous Euler equations

 $\begin{cases} u_t + u \cdot \nabla u + \nabla p = 0 \\ \nabla \cdot u = 0 \\ u(x, 0) = u_0(x) \end{cases}$

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where $(x, t) \in \mathbb{R}^d \times [0, \infty)$ or $\mathbb{T}^d \times [0, \infty)$ and $d \in \{2, 3\}$.

► This *Eulerian formulation* (E) is due to Euler [1757].

Well-posedness

If u₀ ∈ H^s with s > d/2 + 1, or u₀ ∈ L² ∩ C^{1,γ} for some γ ∈ (0, 1), there exists a T > 0 and a unique solution u bounded in the same class as the datum on [0, T).

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- ▶ *d* = 2: Wolibner ['33], Hölder ['33]. Kato ['67].
- d = 3: Lichstenstein ['30]. Kato ['72].

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- d = 2: Wolibner ['33], Hölder ['33]. Kato ['67].
- d = 3: Lichstenstein ['30]. Kato ['72].
- ▶ d = 2: $T = \infty$, even for $\omega_0 \in L^1 \cap L^\infty$; Yudovich ['63].
- d = 3: the classical solution may be extended past time T iff

$$\int_0^T \|\omega(t)\|_{L^\infty} dt < \infty$$

where $\omega = \nabla \times u$ is the vorticity; Beale-Kato-Majda ['84].

The local existence theorems are in classes which guarantee

u is Lipschitz continuous

up to logarithms, as long as the solution exists.

Lagrangian paths

Given a Lipschitz velocity field u(x, t) the Lagrangian path starting at "label" a is given by the solution of the ODE

 $\frac{dX}{dt}(a,t)=u(X(a,t),t), \qquad X(a,0)=a.$

Conservation of momentum becomes

 $\partial_t^2 X(a,t) + (\nabla_x p)(X(a,t),t) = 0.$

Conservation of mass becomes

 $\det(\nabla_a X) = 1$

i.e., the map $a \mapsto X(a, t)$ is volume preserving.

- Lagrangian description of ideal fluids is also due to Euler [1757].
- When u ∈ C^{1,γ} ∩ L² the two formulations are equivalent, and local existence and uniqueness results are "the same".

Any difference between Lagrangian and Eulerian?

- Consider u_0 that is in $L^2 \cap C^{1,\gamma}$.
- If we view the Eulerian solution as a function of time with values in C^{1,γ}, then this function is everywhere discontinuous for generic initial data: Cheskidov-Shvydkoy ['10], Misiolek-Yoneda ['12-'14].

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- See also Masmoudi-Elgindi ['14], Bourgain-Li ['14] for ill-posedness in critical spaces.
- On the other hand, the Lagrangian paths, viewed as functions of time with values in C^{1,γ} are real-analytic (wrt t).

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"Smooth" Sea



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"Rough" Sea



Eulerian regularity



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A Lagrangian path



Lagrangian analyticity for 3D Euler

- Chemin ['92], Gamblin ['94], Serfati ['95], Sueur ['11], Glass-Sueur-Takahashi ['12]: commutators, Littlewood-Paley.
- Shnirelman ['12]: Complexification of geodesic exponential map in SDiff.
- Frisch-Zheligovsky ['12-'13] "A Very Smooth Ride in a Rough Sea": Cauchy invariant gives local elliptic system in label variables. Special structure of 3D Euler.
- Nadirashvili ['13]: 2D elliptic theory yields that nondegenerate level sets of stream function in steady 2D Euler are analytic.
- Quantifying the distinct degrees of regularity for weak solutions of 3D Euler with respect to Eulerian and Lagrangian derivatives is crucial for the recent works on the Onsager conjecture: Isett ['12-'13], Buckmaster-DeLellis-Szekelyhidi ['13-'14].

Lagrangian analyticity in hydrodynamic systems

Question: is there anything robust about these results, or are all the results due to the special structure of the Euler equations?

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Theorem (Constantin-V.-Wu ('14))

Consider a well-posed hydrodynamic equation (such as 2D/3D Euler, 2D Boussinesq, 2D SQG, 2D IPM, etc...) on a time interval [0, T) when the Eulerian velocities are $C^{1,\gamma}$, for some $\gamma \in (0, 1)$.

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$$\lambda(t) = \exp\left(\int_0^t \|\nabla u(\tau)\|_{L^\infty_x} d\tau\right).$$

▶ Recall: as long as $u \in L^1_t \operatorname{Lip}_x$, we have the chord-arc condition

$$\lambda(t)^{-1} \leq \frac{|\boldsymbol{a} - \boldsymbol{b}|}{|\boldsymbol{X}(\boldsymbol{a}, t) - \boldsymbol{X}(\boldsymbol{b}, t)|} \leq \lambda(t).$$

Proof also applies to smooth 2D vortex patches. In contrast, for generic vorticity in the Yudovich class, only Gevrey-3 regularity in time appears to be known: Gamblin ['94], Sueur ['11].

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Reformulation as closed Lagrangian system. The Lagrangian path, X, obeys

$$\frac{dX}{dt}(a,t)=\frac{1}{4\pi}\int\frac{X(a,t)-X(b,t)}{|X(a,t)-X(b,t)|^3}\times (\nabla_b X(b,t)\omega_0(b))db.$$

and

$$\frac{d(\nabla_a X)}{dt}(a,t) = (\nabla_a X)(a,t) \int K(X(a,t) - X(b,t)) (\nabla_b X(b,t)\omega_0(b)) db$$
$$+ \frac{1}{2} (\nabla_a X(a,t)\omega_0(a)) \times (\nabla_a X)(a,t).$$

with kernel K is given by

$$(\mathcal{K}(\mathbf{x})\mathbf{y})_{ij} = \frac{3}{8\pi} \frac{(\mathbf{x} \times \mathbf{y})_i \, \mathbf{x}_j + (\mathbf{x} \times \mathbf{y})_j \, \mathbf{x}_i}{|\mathbf{x}|^5}.$$

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with kernel *K* is given by

$$(\mathcal{K}(x)y)_{ij} = \frac{3}{8\pi} \frac{(x \times y)_i x_j + (x \times y)_j x_i}{|x|^5}.$$

Key observations: initial datum just appears as a parameter; and the equations are closed ODEs with values in C^{1,γ}.

▶ Recall: If *K* is real-analytic and $X \in C^0$ is a solution of

$$\frac{dX}{dt} = K(X)$$

then in fact X is real-analytic with respect to t.

Proof: keep track of proper Cauchy inequalities

$$|\partial_t^n X| \le (-1)^{n-1} {\binom{1/2}{n}} \frac{(2C)^n}{R^{n-1}} n!$$

by means of the Faá di Bruno formula (or method of majorants).

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Instead, for a large class of inviscid hydrodynamical models:

$$\frac{d}{dt} [X, \nabla X] (a)$$

$$= \mathcal{P}_1(X(a), \nabla X(a))$$

$$\times p.v. \int \mathcal{K}(X(a) - X(b)) \mathcal{P}_2(X(b), \nabla X(b)) \mathcal{P}_3(u_0(b), \nabla u_0(b)) db$$

where $\mathcal{P}_{\textit{i}}$ are polynomials, and \mathcal{K} are Calderon-Zygmund kernels.

► C-Z operators remain OK after composition with $C^{1,\gamma}$ maps.

Fully Lagrangian formulation of the Euler equations

► The Lagrangian velocity *v* and the pressure *q* are obtained by composing with *X*

 $v(a,t) = u(X(a,t),t), \quad q(a,t) = p(X(a,t),t).$

> Denote the matrix inverse of the Jacobian of the particle map as

 $Y(a,t)=(\nabla_a X(a,t))^{-1}.$

The Lagrangian formulation of Euler is given in components by

$$\begin{aligned} \partial_t \mathbf{v}^i + \mathbf{Y}^j_i \partial_j \mathbf{q} &= \mathbf{0} \\ \mathbf{Y}^k_i \partial_k \mathbf{v}^i &= \mathbf{0} \\ \partial_t \mathbf{Y}^k_i &= -\mathbf{Y}^k_i (\nabla \mathbf{v})^i_j \mathbf{Y}^j_i \end{aligned}$$
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used summation convention on repeated indices, and $\partial_k = \partial_{a_k}$.

- ▶ The evolution of *Y* follows from det(∇X) = 1 and $\nabla_a(\partial_t X = v)$.
- The closed system for (v, q, Y) is supplemented with initial datum

 $v(a,0) = v_0(a) = u_0(a), \quad Y(a,0) = I.$

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- Consider *u*₀ that is real-analytic wrt *x*.
- Then as long as the smooth solution exists (i.e. does not blow up in L¹_tLip_x), it remains real-analytic wrt x.

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Any difference between Lagrangian and Eulerian?

- Consider u_0 that is real-analytic wrt x.
- Then as long as the smooth solution exists (i.e. does not blow up in L¹_tLip_x), it remains real-analytic wrt x.
- Bardos-Benachour-Zerner ['76], Bardos-Benachour ['77], Alinhac-Metivier ['86], Levermore-Oliver ['97], Kukavica-V. ['09-'11], Zheligovsky ['11], Sueur ['11], Glass-Sueur-Takahashi ['12], Sawada ['13].
- Best lower bounds on the uniform spatial analyticity radius τ(t) are given explicitly in terms of the chord-arc parameter

$$\tau(t) \geq \frac{\tau_0}{\lambda(t)} = \tau_0 \exp\left(-\int_0^t \|\nabla u(s)\|_{L^{\infty}} ds\right)$$

- Analyticity with respect to label a follows (with possibly different convergence radius) due to composition of real-analytic functions, and Cauchy-Kowalevski.
- Analyticity in time in this case follows directly from the equations: $\partial_t u$ = real-analytic function.

Constantin-Kukavica-V. ('15)

In the Lagrangian formulation, one may solve the equations locally in time, at fixed analyticity radius.

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- ► In Eulerian variables, it may deteriorate instantaneously.
- The Lagrangian formulation allows solvability in highly anisotropic classes, e.g. functions which have analyticity in one variable, but are not analytic in the others.
- In the Eulerian formulation, the equations are ill-posed in such functions spaces.

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Norms for real-analytic and Gevrey functions

- Fix r > d/2, so that $H^r(\mathbb{R}^d)$ is an algebra.
- For a Gevrey-index s ≥ 1 and Gevrey-radius δ > 0, we denote the isotropic Gevrey norm by

$$\|f\|_{G_{s,\delta}} = \sum_{\beta \ge 0} \frac{\delta^{|\beta|}}{|\beta|!s} \|\partial^{\beta} f\|_{H^{r}} = \sum_{m \ge 0} \frac{\delta^{m}}{m!s} \left(\sum_{|\beta|=m} \|\partial^{\beta} f\|_{H^{r}} \right)$$

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where $\beta \in \mathbb{N}_0^d$ is a multi-index.

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where $\beta \in \mathbb{N}_0^d$ is a multi-index.

When s = 1 this norm corresponds to the space of real-analytic functions, and δ represents the uniform radius of analyticity of f.

- The l^1 norm in *m* is essential \rightarrow Wiener algebra.
- See Oliver-Titi ['01] for an equivalent Fourier description.

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- When s = 1 this norm corresponds to the space of real-analytic functions, and δ represents the uniform radius of analyticity of f.
- The ℓ^1 norm in *m* is essential \rightarrow Wiener algebra.
- See Oliver-Titi ['01] for an equivalent Fourier description.
- Similarly, given a coordinate *j* ∈ {1,..., *d*}, we define the anisotropic *s*-Gevrey norm with radius δ > 0 by

$$\|f\|_{\mathcal{G}_{s,\delta}^{(j)}}=\sum_{m\geq 0}\frac{\delta^m}{m!^s}\|\partial_j^m f\|_{H^r}.$$

Persistence of Lagrangian analyticity radius

Theorem (Constantin-Kukavica-V. ('15)) Assume that $v_0 \in L^2$ and

$$abla v_0 \in G_{s,\delta}$$

for some Gevrey-index $s \ge 1$ and a Gevrey-radius $\delta > 0$. Then there exists T > 0 and a unique solution $v \in C([0, T]; H^{r+1})$, $Y \in C([0, T], H^r)$ of the Lagrangian Euler system (L), which moreover satisfies

 $\nabla v, Y \in L^{\infty}([0, T], G_{s, \delta}).$

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Instantaneous decay of Eulerian analyticity radius

Theorem (Constantin-Kukavica-V. ('15))

There exist smooth periodic functions f, g such that

 $\|\textit{\textbf{U}}_0\|_{\textit{G}_{1,1}} < \infty$

and such that the unique solution u of the Euler equations (E) measured in the Eulerian variables obeys

 $\|u(t)\|_{G_{1,1}}=\infty$

as soon as t > 0.



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• Let f, g be two 2π -periodic functions. The function

 $u(x_1, x_2, x_3, t) = (f(x_2), 0, g(x_1 - tf(x_2)))$

is an exact solution of the Euler equations (E) on \mathbb{T}^3 , with datum

 $u_0(x_1, x_2, x_3) = (f(x_2), 0, g(x_1)).$

and vanishing pressure. Di Perna-Majda ['87]; Bardos-Titi ['10].

Simply letting

$$f(y) = \sin(y)$$
 and $g(y) = \frac{1}{\sinh(1)^2 + \sin(y)^2}$

does not work, since then $u_0 \notin G_{1,1}$ (ℓ^1 vs ℓ^{∞} in derivative order).

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Instead, start with 1/(1 + y²); integrate four times (so that the holomorphic extension is C² up to Im(z) = 1); cut off in Gaussian way at infinity; periodize.

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- Instead, start with 1/(1 + y²); integrate four times (so that the holomorphic extension is C² up to Im(z) = 1); cut off in Gaussian way at infinity; periodize.
- As soon as we turn on time, the holomorphic extension of the function

$$\partial_{x_1}^3 u_3(x_1, x_2, x_3, t) = \partial_{x_1}^3 (g(x_1 - tf(x_2)))$$

has a singularity in the complex plane at

$$z_1 = 0 - (1 - t)i$$

 $z_2 = 0 + i \log 2.$

• Thus, $u(t) \notin G_{1,\delta(t)}$, for any $\delta(t) > 1 - t$.



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Solvability in anisotropic Lagrangian Gevrey classes

Theorem (Constantin-Kukavica-V. ('14)) Fix a direction $j \in \{1, ..., d\}$, assume that $v_0 \in H^{r+1}$ and that

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for some index $s \ge 1$ and radius $\delta > 0$. Then there exists T > 0 and a unique solution $v \in C([0, T], H^{r+1})$, $Y \in C([0, T], H^r)$ of the Lagrangian Euler system (L), which moreover satisfies

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$$\nabla \mathbf{v}, \mathbf{Y} \in L^{\infty}([0, T], G_{s,\delta}^{(j)}).$$

At low regularity, i.e. Hölder classes, the equivalent question is the propagation of smoothness along vector fields transported by the Euler flow: "striated regularity". Bae-Kelliher ['15], following earlier works of Chemin ['93], Gamblin-Saint Raymond ['95], Danchin ['99], in spaces with negative degrees of smoothness.

Ill-posedness for anisotropic Eulerian real-analyticity

Theorem (Constantin-Kukavica-V. ('15))

There exists T > 0 and an initial datum $u_0 \in C^{\infty}(\mathbb{R}^2)$ for which u_0 and ω_0 are real-analytic in x_1 , uniformly with respect to x_2 , such that the unique $C([0, T]; H^r)$ solution $\omega(t)$ of the Cauchy problem for the Euler equations (E) is not real-analytic in x_1 , for any $t \in (0, T]$.

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- The fact that the Eulerian version of the theorem does not hold should not be so surprising: isotropy and time-reversibility of the Euler equations.
- By contrast, the fact that the Lagrangian formulation keeps the memory of initial anisotropy is a bit more puzzling.

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► Navier-Stokes ≈ Euler + Prandtl?



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The Lagrangian vorticity in 2D

For d = 2 the Lagrangian scalar vorticity

 $\zeta(\boldsymbol{a},t) = \omega(\boldsymbol{X}(\boldsymbol{a},t),t)$

is conserved in time

$$\zeta(a,t) = \omega_0(a)$$

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for $t \ge 0$.

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is conserved in time

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for $t \ge 0$.

The Lagrangian velocity ν can then be computed from the Lagrangian vorticity ζ using the elliptic curl-div system

$$\varepsilon_{ij} Y_i^k \partial_k v^j = Y_1^k \partial_k v^2 - Y_2^k \partial_k v^1 = \zeta = \omega_0$$

$$Y_i^k \partial_k v^i = Y_1^k \partial_k v^1 + Y_2^k \partial_k v^2 = 0$$

where ε_{ij} is the sign of the permutation $(1, 2) \mapsto (i, j)$.

The Cauchy identities for Lagrangian vorticity in 3D

For d = 3 the vorticity vector is not conserved along particle trajectories, and instead we have the vorticity transport formula

 $\zeta^{i}(\boldsymbol{a},t)=\partial_{k}\boldsymbol{X}^{i}(\boldsymbol{a},t)\omega_{0}^{k}(\boldsymbol{a}).$



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 $\zeta^{i}(\boldsymbol{a},t)=\partial_{k}\boldsymbol{X}^{i}(\boldsymbol{a},t)\omega_{0}^{k}(\boldsymbol{a}).$

Thus, in three dimensions, the elliptic curl-div system becomes

$$\varepsilon_{ijk} Y_j^l \partial_l v^k = \zeta^i = \partial_k X^i \omega_0^k$$
$$Y_i^k \partial_k v^i = 0$$

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 $\zeta^{i}(\boldsymbol{a},t)=\partial_{k}\boldsymbol{X}^{i}(\boldsymbol{a},t)\omega_{0}^{k}(\boldsymbol{a}).$

> Thus, in three dimensions, the elliptic curl-div system becomes

$$\varepsilon_{ijk} Y_j^l \partial_l v^k = \zeta^i = \partial_k X^i \omega_0^k$$
$$Y_i^k \partial_k v^i = 0$$

- In order to make use of the above identity, we need to reformulate it so that the right side is time-independent, as in 2D.
- Multiplying the equation for the Lagrangian curl with Y^m_i and summing in *i*, we get

$$\varepsilon_{ijk} Y_i^m Y_j^l \partial_l v^k = \omega_0^m$$

which is the form of the Cauchy [1827] identity containing only Y.

Proof of Lagrangian persistence

Fix $s \ge 1$ and $\delta > 0$ so that $\|\nabla v_0\|_{G_{s,\delta}} \le M$, that is

$$\Omega_m := \sum_{|\alpha|=m} \|\partial^{\alpha} \nabla v_0\|_{H'}$$

obeys



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Proof of Lagrangian persistence

Fix $s \ge 1$ and $\delta > 0$ so that $\|\nabla v_0\|_{G_{s,\delta}} \le M$, that is

$$\Omega_m := \sum_{|\alpha|=m} \|\partial^{\alpha} \nabla \mathbf{v}_0\|_{H^r}$$

obeys

$$\sum_{m\geq 0}\Omega_m\frac{\delta^m}{m!^s}\leq M$$

Fix T > 0, to be chosen later sufficiently small in terms of M and s, and for m ≥ 0 define

$$V_{m} = V_{m}(T) = \sup_{t \in [0,T]} \sum_{|\alpha|=m} \|\partial^{\alpha} \nabla v(t)\|_{H^{r}},$$

$$Z_{m} = Z_{m}(T) = \sup_{t \in [0,T]} t^{-1/2} \sum_{|\alpha|=m} \|\partial^{\alpha} (Y(t) - I)\|_{H^{r}}.$$

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Velocity estimates

In order to estimate ∇ν and its derivatives, we use the three-dimensional div-curl system we conclude that for α ∈ N₀³:

$$\begin{split} |\partial^{\alpha} \nabla \mathbf{v}\|_{H^{r}} &\leq \mathbf{C} \|\partial^{\alpha} \omega_{0}^{m}\|_{H^{r}} + \mathbf{C} \|\partial^{\alpha} (\varepsilon_{ijk} (\delta_{im} - Y_{i}^{m}) (\delta_{jl} - Y_{j}^{l}) \partial_{l} \mathbf{v}^{k})\|_{H^{r}} \\ &+ \mathbf{C} \|\partial^{\alpha} (\varepsilon_{mjk} (\delta_{jl} - Y_{j}^{l}) \partial_{l} \mathbf{v}^{k})\|_{H^{r}} + \mathbf{C} \|\partial^{\alpha} (\varepsilon_{ijk} (\delta_{im} - Y_{i}^{m}) \partial_{j} \mathbf{v}^{k})\|_{H^{r}} \\ &+ \mathbf{C} \|\partial^{\alpha} ((\delta_{ik} - Y_{i}^{k}) \partial_{k} \mathbf{v}^{i})\|_{H^{r}}. \end{split}$$

Summing the above inequality over all multi-indices with |α| = m and taking a supremum over t ∈ [0, T] we arrive at

$$V_{m} \leq C\Omega_{m} + CTZ_{m}Z_{0}V_{0} + CTZ_{0}^{2}V_{m} + CT^{1/2}Z_{0}V_{m} + CT^{1/2}Z_{m}V_{0} + CT^{1/2}\sum_{0 < j < m} {m \choose j}Z_{j}V_{m-j} + CT\sum_{0 < (j,k) < m} {m \choose j}Z_{j}Z_{k}V_{m-j-k}$$

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for all $m \ge 0$.

Flow map estimates

▶ In order to bound Z_m we appeal to the evolution for Y(t) - I:

$$I - Y(t) = \int_0^t (Y - I) : \nabla v : (Y - I) \, d\tau + \int_0^t (Y - I) : \nabla v \, d\tau$$
$$+ \int_0^t \nabla v : (Y - I) \, d\tau + \int_0^t \nabla v \, d\tau$$

We obtain

$$Z_{m} \leq CT^{1/2} (TZ_{0}^{2}V_{m} + TZ_{m}Z_{0}V_{0} + T^{1/2}Z_{0}V_{m} + T^{1/2}Z_{m}V_{0} + V_{m}) + CT^{3/2} \sum_{0 < |(j,k)| < m} {m \choose j k} Z_{j}Z_{k}V_{m-j-k} + CT \sum_{j=1}^{m-1} {m \choose j} Z_{j}V_{m-j}$$

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for all $m \ge 0$.

Summing over *m* completes the proof.

Thank you!