# Regularity Properties of the Euler Equations in Lagrangian Variables 

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## The Euler equations

- We consider the Cauchy problem for the ideal incompressible homogeneous Euler equations

$$
\left\{\begin{array}{l}
u_{t}+u \cdot \nabla u+\nabla p=0  \tag{E}\\
\nabla \cdot u=0 \\
u(x, 0)=u_{0}(x)
\end{array}\right.
$$

where $(x, t) \in \mathbb{R}^{d} \times[0, \infty)$ or $\mathbb{T}^{d} \times[0, \infty)$ and $d \in\{2,3\}$.

- This Eulerian formulation (E) is due to Euler [1757].


## Well-posedness

- If $u_{0} \in H^{s}$ with $s>d / 2+1$, or $u_{0} \in L^{2} \cap C^{1, \gamma}$ for some $\gamma \in(0,1)$, there exists a $T>0$ and a unique solution $u$ bounded in the same class as the datum on $[0, T)$.
- $d=2$ : Wolibner ['33], Hölder ['33]. Kato ['67].
- $d=3$ : Lichstenstein ['30]. Kato ['72].


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- $d=2$ : Wolibner ['33], Hölder ['33]. Kato ['67].
- $d=3$ : Lichstenstein ['30]. Kato ['72].
- $d=$ 2: $T=\infty$, even for $\omega_{0} \in L^{1} \cap L^{\infty}$; Yudovich ['63].
- $d=3$ : the classical solution may be extended past time $T$ iff

$$
\int_{0}^{T}\|\omega(t)\|_{L \infty} d t<\infty
$$

where $\omega=\nabla \times u$ is the vorticity; Beale-Kato-Majda ['84].

- The local existence theorems are in classes which guarantee
$u$ is Lipschitz continuous
up to logarithms, as long as the solution exists.


## Lagrangian paths

- Given a Lipschitz velocity field $u(x, t)$ the Lagrangian path starting at "label" $a$ is given by the solution of the ODE

$$
\frac{d X}{d t}(a, t)=u(X(a, t), t), \quad X(a, 0)=a .
$$

- Conservation of momentum becomes

$$
\partial_{t}^{2} X(a, t)+\left(\nabla_{x} p\right)(X(a, t), t)=0
$$

- Conservation of mass becomes

$$
\operatorname{det}\left(\nabla_{a} X\right)=1
$$

i.e., the map $a \mapsto X(a, t)$ is volume preserving.

- Lagrangian description of ideal fluids is also due to Euler [1757].
- When $u \in C^{1, \gamma} \cap L^{2}$ the two formulations are equivalent, and local existence and uniqueness results are "the same".


## Any difference between Lagrangian and Eulerian?

- Consider $u_{0}$ that is in $L^{2} \cap C^{1, \gamma}$.
- If we view the Eulerian solution as a function of time with values in $C^{1, \gamma}$, then this function is everywhere discontinuous for generic initial data: Cheskidov-Shvydkoy ['10], Misiolek-Yoneda ['12-'14].
- See also Masmoudi-Elgindi ['14], Bourgain-Li ['14] for ill-posedness in critical spaces.


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- See also Masmoudi-Elgindi ['14], Bourgain-Li ['14] for ill-posedness in critical spaces.
- On the other hand, the Lagrangian paths, viewed as functions of time with values in $C^{1, \gamma}$ are real-analytic (wrt $t$ ).


## ＂Smooth＂Sea



## "Rough" Sea



## Eulerian regularity



## A Lagrangian path



## Lagrangian analyticity for 3D Euler

- Chemin ['92], Gamblin ['94], Serfati ['95], Sueur ['11], Glass-Sueur-Takahashi ['12]: commutators, Littlewood-Paley.
- Shnirelman ['12]: Complexification of geodesic exponential map in SDiff.
- Frisch-Zheligovsky ['12-'13] "A Very Smooth Ride in a Rough Sea": Cauchy invariant gives local elliptic system in label variables. Special structure of 3D Euler.
- Nadirashvili ['13]: 2D elliptic theory yields that nondegenerate level sets of stream function in steady 2D Euler are analytic.
- Quantifying the distinct degrees of regularity for weak solutions of 3D Euler with respect to Eulerian and Lagrangian derivatives is crucial for the recent works on the Onsager conjecture: Isett ['12-'13], Buckmaster-DeLellis-Szekelyhidi ['13-'14].


## Lagrangian analyticity in hydrodynamic systems

Question: is there anything robust about these results, or are all the results due to the special structure of the Euler equations?

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Theorem (Constantin-V.-Wu ('14))
Consider a well-posed hydrodynamic equation (such as 2D/3D Euler, 2D Boussinesq, 2D SQG, 2D IPM, etc...) on a time interval [ $0, T$ ) when the Eulerian velocities are $C^{1, \gamma}$, for some $\gamma \in(0,1)$.

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Then, the Lagrangian particle trajectories $X(a, t)$ are real-analytic functions of time.

- The radius of analyticity in time on the interval $[0, t]$ depends on the chord-arc parameter of this interval:

$$
\lambda(t)=\exp \left(\int_{0}^{t}\|\nabla u(\tau)\|_{L_{x}} d \tau\right) .
$$

- Recall: as long as $u \in L_{t}^{1} \operatorname{Lip}_{x}$, we have the chord-arc condition

$$
\lambda(t)^{-1} \leq \frac{|a-b|}{|X(a, t)-X(b, t)|} \leq \lambda(t) .
$$

- Proof also applies to smooth 2D vortex patches. In contrast, for generic vorticity in the Yudovich class, only Gevrey-3 regularity in time appears to be known: Gamblin ['94], Sueur ['11].
- Reformulation as closed Lagrangian system. The Lagrangian path, $X$, obeys

$$
\frac{d X}{d t}(a, t)=\frac{1}{4 \pi} \int \frac{X(a, t)-X(b, t)}{|X(a, t)-X(b, t)|^{3}} \times\left(\nabla_{b} X(b, t) \omega_{0}(b)\right) d b .
$$

and

$$
\begin{aligned}
\frac{d\left(\nabla_{a} X\right)}{d t}(a, t)= & \left(\nabla_{a} X\right)(a, t) \int K(X(a, t)-X(b, t))\left(\nabla_{b} X(b, t) \omega_{0}(b)\right) d b \\
& +\frac{1}{2}\left(\nabla_{a} X(a, t) \omega_{0}(a)\right) \times\left(\nabla_{a} X\right)(a, t) .
\end{aligned}
$$

with kernel $K$ is given by

$$
(K(x) y)_{i j}=\frac{3}{8 \pi} \frac{(x \times y)_{i} x_{j}+(x \times y)_{j} x_{i}}{|x|^{5}} .
$$

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- Key observations: initial datum just appears as a parameter; and the equations are closed ODEs with values in $C^{1, \gamma}$.
- Recall: If $K$ is real-analytic and $X \in C^{0}$ is a solution of

$$
\frac{d X}{d t}=K(X)
$$

then in fact $X$ is real-analytic with respect to $t$.

- Proof: keep track of proper Cauchy inequalities

$$
\left|\partial_{t}^{n} X\right| \leq(-1)^{n-1}\binom{1 / 2}{n} \frac{(2 C)^{n}}{R^{n-1}} n!
$$

by means of the Faá di Bruno formula (or method of majorants).

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- Instead, for a large class of inviscid hydrodynamical models:

$$
\begin{aligned}
& \frac{d}{d t}[X, \nabla X](a) \\
& =\mathcal{P}_{1}(X(a), \nabla X(a)) \\
& \quad \times p . v . \int \mathcal{K}(X(a)-X(b)) \mathcal{P}_{2}(X(b), \nabla X(b)) \mathcal{P}_{3}\left(u_{0}(b), \nabla u_{0}(b)\right) d b
\end{aligned}
$$

where $\mathcal{P}_{i}$ are polynomials, and $\mathcal{K}$ are Calderon-Zygmund kernels.

- C-Z operators remain OK after composition with $C^{1, \gamma}$ maps.


## Fully Lagrangian formulation of the Euler equations

- The Lagrangian velocity $v$ and the pressure $q$ are obtained by composing with $X$

$$
v(a, t)=u(X(a, t), t), \quad q(a, t)=p(X(a, t), t)
$$

- Denote the matrix inverse of the Jacobian of the particle map as

$$
Y(a, t)=\left(\nabla_{a} X(a, t)\right)^{-1} .
$$

- The Lagrangian formulation of Euler is given in components by

$$
\left\{\begin{array}{l}
\partial_{t} v^{i}+Y_{i}^{j} \partial_{j} q=0  \tag{L}\\
Y_{i}^{k} \partial_{k} v^{i}=0 \\
\partial_{t} Y_{i}^{k}=-Y_{I}^{k}(\nabla v)_{j}^{l} Y_{i}^{j}
\end{array}\right.
$$

used summation convention on repeated indices, and $\partial_{k}=\partial_{a_{k}}$.

- The evolution of $Y$ follows from $\operatorname{det}(\nabla X)=1$ and $\nabla_{a}\left(\partial_{t} X=v\right)$.
- The closed system for $(v, q, Y)$ is supplemented with initial datum

$$
v(a, 0)=v_{0}(a)=u_{0}(a), \quad Y(a, 0)=I .
$$

## Any difference between Lagrangian and Eulerian?

- Consider $u_{0}$ that is real-analytic wrt $x$.
- Then as long as the smooth solution exists (i.e. does not blow up in $L_{t}^{1} \mathrm{Lip}_{x}$ ), it remains real-analytic wrt $x$.


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- Then as long as the smooth solution exists (i.e. does not blow up in $L_{t}^{1} \mathrm{Lip}_{x}$ ), it remains real-analytic wrt $x$.
- Bardos-Benachour-Zerner ['76], Bardos-Benachour ['77], Alinhac-Metivier ['86], Levermore-Oliver ['97], Kukavica-V. ['09-'11], Zheligovsky ['11], Sueur ['11], Glass-Sueur-Takahashi ['12], Sawada ['13].
- Best lower bounds on the uniform spatial analyticity radius $\tau(t)$ are given explicitly in terms of the chord-arc parameter

$$
\tau(t) \geq \frac{\tau_{0}}{\lambda(t)}=\tau_{0} \exp \left(-\int_{0}^{t}\|\nabla u(s)\|_{L_{\infty}} d s\right)
$$

- Analyticity with respect to label a follows (with possibly different convergence radius) due to composition of real-analytic functions, and Cauchy-Kowalevski.
- Analyticity in time in this case follows directly from the equations: $\partial_{t} u=$ real-analytic function.


## Constantin-Kukavica-V. ('15)

- In the Lagrangian formulation, one may solve the equations locally in time, at fixed analyticity radius.
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- In the Lagrangian formulation, one may solve the equations locally in time, at fixed analyticity radius.
- In Eulerian variables, it may deteriorate instantaneously.
- The Lagrangian formulation allows solvability in highly anisotropic classes, e.g. functions which have analyticity in one variable, but are not analytic in the others.
- In the Eulerian formulation, the equations are ill-posed in such functions spaces.


## Norms for real-analytic and Gevrey functions

- Fix $r>d / 2$, so that $H^{r}\left(\mathbb{R}^{d}\right)$ is an algebra.
- For a Gevrey-index $s \geq 1$ and Gevrey-radius $\delta>0$, we denote the isotropic Gevrey norm by

$$
\|f\|_{G_{s, \delta}}=\sum_{\beta \geq 0} \frac{\delta^{|\beta|}}{|\beta|!^{s}}\left\|\partial^{\beta} f\right\|_{H^{r}}=\sum_{m \geq 0} \frac{\delta^{m}}{m!^{s}}\left(\sum_{|\beta|=m}\left\|\partial^{\beta} f\right\|_{H^{r}}\right)
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where $\beta \in \mathbb{N}_{0}^{d}$ is a multi-index.

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- When $s=1$ this norm corresponds to the space of real-analytic functions, and $\delta$ represents the uniform radius of analyticity of $f$.
- The $\ell^{1}$ norm in $m$ is essential $\rightarrow$ Wiener algebra.
- See Oliver-Titi ['01] for an equivalent Fourier description.


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- The $\ell^{1}$ norm in $m$ is essential $\rightarrow$ Wiener algebra.
- See Oliver-Titi ['01] for an equivalent Fourier description.
- Similarly, given a coordinate $j \in\{1, \ldots, d\}$, we define the anisotropic $s$-Gevrey norm with radius $\delta>0$ by

$$
\|f\|_{G_{s, \delta}^{()}}=\sum_{m \geq 0} \frac{\delta^{m}}{m!s^{!}}\left\|\partial_{j}^{m} f\right\|_{H^{r}}
$$

## Persistence of Lagrangian analyticity radius

Theorem (Constantin-Kukavica-V. ('15))
Assume that $v_{0} \in L^{2}$ and

$$
\nabla v_{0} \in G_{s, \delta}
$$

for some Gevrey-index $s \geq 1$ and a Gevrey-radius $\delta>0$. Then there exists $T>0$ and a unique solution $v \in C\left([0, T] ; H^{r+1}\right)$, $Y \in C\left([0, T], H^{r}\right)$ of the Lagrangian Euler system (L), which moreover satisfies

$$
\nabla v, Y \in L^{\infty}\left([0, T], G_{s, \delta}\right)
$$

## Instantaneous decay of Eulerian analyticity radius

Theorem (Constantin-Kukavica-V. ('15))
There exist smooth periodic functions $f, g$ such that

$$
\left\|u_{0}\right\|_{G_{1,1}}<\infty
$$

and such that the unique solution $u$ of the Euler equations (E) measured in the Eulerian variables obeys

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\|u(t)\|_{G_{1,1}}=\infty
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- Let $f, g$ be two $2 \pi$-periodic functions. The function

$$
u\left(x_{1}, x_{2}, x_{3}, t\right)=\left(f\left(x_{2}\right), 0, g\left(x_{1}-t f\left(x_{2}\right)\right)\right)
$$

is an exact solution of the Euler equations ( E ) on $\mathbb{T}^{3}$, with datum

$$
u_{0}\left(x_{1}, x_{2}, x_{3}\right)=\left(f\left(x_{2}\right), 0, g\left(x_{1}\right)\right)
$$

and vanishing pressure. Di Perna-Majda ['87]; Bardos-Titi ['10].

## Proof

- Simply letting

$$
f(y)=\sin (y) \quad \text { and } \quad g(y)=\frac{1}{\sinh (1)^{2}+\sin (y)^{2}}
$$

does not work, since then $u_{0} \notin G_{1,1}\left(\ell^{1}\right.$ vs $\ell^{\infty}$ in derivative order).

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- Instead, start with $1 /\left(1+y^{2}\right)$; integrate four times (so that the holomorphic extension is $C^{2}$ up to $\operatorname{Im}(z)=1$ ); cut off in Gaussian way at infinity; periodize.


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- Instead, start with $1 /\left(1+y^{2}\right)$; integrate four times (so that the holomorphic extension is $C^{2}$ up to $\operatorname{Im}(z)=1$ ); cut off in Gaussian way at infinity; periodize.
- As soon as we turn on time, the holomorphic extension of the function

$$
\partial_{x_{1}}^{3} u_{3}\left(x_{1}, x_{2}, x_{3}, t\right)=\partial_{x_{1}}^{3}\left(g\left(x_{1}-t f\left(x_{2}\right)\right)\right)
$$

has a singularity in the complex plane at

$$
\begin{aligned}
& z_{1}=0-(1-t) i \\
& z_{2}=0+i \log 2 .
\end{aligned}
$$

- Thus, $u(t) \notin G_{1, \delta(t)}$, for any $\delta(t)>1-t$.


## Proof



## Proof



## Solvability in anisotropic Lagrangian Gevrey classes

Theorem (Constantin-Kukavica-V. ('14))
Fix a direction $j \in\{1, \ldots, d\}$, assume that $v_{0} \in H^{r+1}$ and that

$$
\nabla v_{0} \in G_{s, \delta}^{(j)}
$$

for some index $s \geq 1$ and radius $\delta>0$. Then there exists $T>0$ and $a$ unique solution $v \in C\left([0, T], H^{r+1}\right), Y \in C\left([0, T], H^{r}\right)$ of the Lagrangian Euler system (L), which moreover satisfies

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- At low regularity, i.e. Hölder classes, the equivalent question is the propagation of smoothness along vector fields transported by the Euler flow: "striated regularity". Bae-Kelliher ['15], following earlier works of Chemin ['93], Gamblin-Saint Raymond ['95], Danchin ['99], in spaces with negative degrees of smoothness.


## III-posedness for anisotropic Eulerian real-analyticity

Theorem (Constantin-Kukavica-V. ('15))
There exists $T>0$ and an initial datum $u_{0} \in C^{\infty}\left(\mathbb{R}^{2}\right)$ for which $u_{0}$ and $\omega_{0}$ are real-analytic in $x_{1}$, uniformly with respect to $x_{2}$, such that the unique $C\left([0, T] ; H^{r}\right)$ solution $\omega(t)$ of the Cauchy problem for the Euler equations $(E)$ is not real-analytic in $x_{1}$, for any $t \in(0, T]$.

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- The fact that the Eulerian version of the theorem does not hold should not be so surprising: isotropy and time-reversibility of the Euler equations.
- By contrast, the fact that the Lagrangian formulation keeps the memory of initial anisotropy is a bit more puzzling.
- Navier-Stokes $\approx$ Euler + Prandtl?


## Proof



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## Proof



## The Lagrangian vorticity in 2D

- For $d=2$ the Lagrangian scalar vorticity

$$
\zeta(a, t)=\omega(X(a, t), t)
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is conserved in time

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for $t \geq 0$.

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for $t \geq 0$.

- The Lagrangian velocity $v$ can then be computed from the Lagrangian vorticity $\zeta$ using the elliptic curl-div system

$$
\begin{aligned}
\varepsilon_{i j} Y_{i}^{k} \partial_{k} v^{j} & =Y_{1}^{k} \partial_{k} v^{2}-Y_{2}^{k} \partial_{k} v^{1} \\
Y_{i}^{k} \partial_{k} v^{i} & =Y_{1}^{k} \partial_{k} v^{1}+Y_{2}^{k} \partial_{k} v^{2}
\end{aligned}=0
$$

where $\varepsilon_{i j}$ is the sign of the permutation $(1,2) \mapsto(i, j)$.

## The Cauchy identities for Lagrangian vorticity in 3D

- For $d=3$ the vorticity vector is not conserved along particle trajectories, and instead we have the vorticity transport formula

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\zeta^{i}(a, t)=\partial_{k} X^{i}(a, t) \omega_{0}^{k}(a) .
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- Thus, in three dimensions, the elliptic curl-div system becomes

$$
\begin{aligned}
\varepsilon_{i j k} Y_{j}^{\prime} \partial_{l} v^{k} & =\zeta^{i}=\partial_{k} X^{i} \omega_{0}^{k} \\
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\end{aligned}
$$

- In order to make use of the above identity, we need to reformulate it so that the right side is time-independent, as in 2D.
- Multiplying the equation for the Lagrangian curl with $Y_{i}^{m}$ and summing in $i$, we get

$$
\varepsilon_{i j k} Y_{i}^{m} Y_{j}^{\prime} \partial_{l} v^{k}=\omega_{0}^{m}
$$

which is the form of the Cauchy [1827] identity containing only $Y$.

## Proof of Lagrangian persistence

- Fix $s \geq 1$ and $\delta>0$ so that $\left\|\nabla v_{0}\right\|_{G_{s, \delta}} \leq M$, that is

$$
\Omega_{m}:=\sum_{|\alpha|=m}\left\|\partial^{\alpha} \nabla v_{0}\right\|_{H^{r}}
$$

obeys

$$
\sum_{m \geq 0} \Omega_{m} \frac{\delta^{m}}{m!^{s}} \leq M
$$

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\sum_{m \geq 0} \Omega_{m} \frac{\delta^{m}}{m!^{s}} \leq M
$$

- Fix $T>0$, to be chosen later sufficiently small in terms of $M$ and $s$, and for $m \geq 0$ define

$$
\begin{aligned}
& V_{m}=V_{m}(T)=\sup _{t \in[0, T]} \sum_{|\alpha|=m}\left\|\partial^{\alpha} \nabla v(t)\right\|_{H^{r}}, \\
& Z_{m}=Z_{m}(T)=\sup _{t \in[0, T]} t^{-1 / 2} \sum_{|\alpha|=m}\left\|\partial^{\alpha}(Y(t)-I)\right\|_{H^{r}}
\end{aligned}
$$

## Velocity estimates

- In order to estimate $\nabla v$ and its derivatives, we use the three-dimensional div-curl system we conclude that for $\alpha \in \mathbb{N}_{0}^{3}$ :

$$
\begin{aligned}
\left\|\partial^{\alpha} \nabla v\right\|_{H^{r}} & \leq C\left\|\partial^{\alpha} \omega_{0}^{m}\right\|_{H^{r}}+C\left\|\partial^{\alpha}\left(\varepsilon_{i j k}\left(\delta_{i m}-Y_{i}^{m}\right)\left(\delta_{j l}-Y_{j}^{\prime}\right) \partial_{l} v^{k}\right)\right\|_{H^{r}} \\
& +C\left\|\partial^{\alpha}\left(\varepsilon_{m j k}\left(\delta_{j l}-Y_{j}^{\prime}\right) \partial_{l} v^{k}\right)\right\|_{H^{r}}+C\left\|\partial^{\alpha}\left(\varepsilon_{i j k}\left(\delta_{i m}-Y_{i}^{m}\right) \partial_{j} v^{k}\right)\right\|_{H^{r}} \\
& +C\left\|\partial^{\alpha}\left(\left(\delta_{i k}-Y_{i}^{k}\right) \partial_{k} v^{i}\right)\right\|_{H^{r}} .
\end{aligned}
$$

- Summing the above inequality over all multi-indices with $|\alpha|=m$ and taking a supremum over $t \in[0, T]$ we arrive at

$$
\begin{aligned}
V_{m} \leq & C \Omega_{m}+C T Z_{m} Z_{0} V_{0}+C T Z_{0}^{2} V_{m}+C T^{1 / 2} Z_{0} V_{m}+C T^{1 / 2} Z_{m} V_{0} \\
& +C T^{1 / 2} \sum_{0<j<m}\binom{m}{j} Z_{j} V_{m-j}+C T \sum_{0<(j, k)<m}\binom{m}{j k} Z_{j} Z_{k} V_{m-j-k}
\end{aligned}
$$

for all $m \geq 0$.

## Flow map estimates

- In order to bound $Z_{m}$ we appeal to the evolution for $Y(t)-I$ :

$$
\begin{aligned}
I-Y(t)= & \int_{0}^{t}(Y-I): \nabla v:(Y-I) d \tau+\int_{0}^{t}(Y-I): \nabla v d \tau \\
& +\int_{0}^{t} \nabla v:(Y-I) d \tau+\int_{0}^{t} \nabla v d \tau
\end{aligned}
$$

- We obtain

$$
\begin{aligned}
& Z_{m} \leq C T^{1 / 2}\left(T Z_{0}^{2} V_{m}+T Z_{m} Z_{0} V_{0}+T^{1 / 2} Z_{0} V_{m}+T^{1 / 2} Z_{m} V_{0}+V_{m}\right) \\
& +C T^{3 / 2} \sum_{0<|(j, k)|<m}\binom{m}{j k} Z_{j} Z_{k} V_{m-j-k}+C T \sum_{j=1}^{m-1}\binom{m}{j} Z_{j} V_{m-j}
\end{aligned}
$$

for all $m \geq 0$.

- Summing over $m$ completes the proof.

Thank you!

