Optimal shape and location of sensors or actuators in PDE models

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SIAM Conference on Analysis of Partial Differential Equations, 2015













What is the best shape and placement of sensors?

- Reduce the cost of instruments.
- Maximize the efficiency of reconstruction and estimations.











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The observed system may be described by:

• wave equation
$$\partial_{tt} y = \Delta y$$

or
Schrödinger equation $i\partial_t y = \Delta y$

• general parabolic equations $\partial_t y = Ay$ (e.g., heat or Stokes equations)

in some domain $\Omega,$ with either Dirichlet, Neumann, mixed, or Robin boundary conditions



For instance, when dealing with the heat equation: What is the optimal shape and placement of a thermometer?



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Observability inequality

The observability constant $C_T(\omega)$ is the largest nonnegative constant such that

$$\forall (y^0, y^1) \in L^2(\Omega) \times H^{-1}(\Omega) \qquad C_T(\omega) \| (y^0, y^1) \|_{L^2 \times H^{-1}}^2 \leq \int_0^T \int_{\omega} |y(t, x)|^2 \, dx \, dt$$

The system is said observable on [0, T] if $C_T(\omega) > 0$ (otherwise, $C_T(\omega) = 0$).





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Bardos-Lebeau-Rauch (1992): Observability holds if the pair (ω , *T*) satisfies the Geometric Control Condition (GCC) in Ω :



Every ray of geometrical optics that propagates in Ω and is reflected on its boundary $\partial \Omega$ intersects ω in time less than T.





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Q: What is the "best possible" subdomain ω of fixed given measure? (say, $|\omega| = L|\Omega|$ with 0 < L < 1)



N.B.: we want to optimize not only the placement but also the shape of ω, over all possible measurable subsets.
 (they do not have a prescribed shape, they are not necessarily BV, etc)





Related problems

1) What is the "best domain" for achieving HUM optimal control?

 $y_{tt} - \Delta y = \chi_{\omega} u$

2) What is the "best domain" domain for stabilization (with localized damping)?

$$y_{tt} - \Delta y = -k\chi_{\omega}y_t$$

Existing works by

- P. Hébrard, A. Henrot: theoretical and numerical results in 1D for optimal stabilization.
- A. Münch, P. Pedregal, F. Periago: numerical investigations (fixed initial data).
- S. Cox, P. Freitas, F. Fahroo, K. Ito, ...: variational formulations and numerics.

- M.I. Frecker, C.S. Kubrusly, H. Malebranche, S. Kumar, J.H. Seinfeld, ...: numerical investigations over a finite number of possible initial data.

- M. Demetriou, K. Morris, S.L. Padula, O. Sigmund, M. Van de Wal, ...: actuator placement (predefined set of possible candidates), Riccati approaches.



- ...

- A. Armaou, M. Demetriou, K. Chen, C. Rowley, K. Morris, S. Yang, W. Kang, S. King, L. Xu, ...: *H*₂ optimization, frequency methods, LQ criteria, Gramian approaches.



The model

Observability inequality

$$\forall y \text{ solution} \qquad C_{\mathcal{T}}(\omega) \| (y(0,\cdot), \partial_t y(0,\cdot)) \|_{L^2 \times H^{-1}}^2 \leq \int_0^T \int_\omega |y(t,x)|^2 \, dx \, dt$$

Let $L \in (0, 1)$ and T > 0 fixed.

It is a priori natural to model the problem as:

$$\sup_{\substack{\omega\subset\Omega\\|\omega|=L|\Omega|}}C_T(\omega)$$

with

$$C_{T}(\omega) = \inf\left\{\frac{\int_{0}^{T} \int_{\omega} |y(t,x)|^{2} dx dt}{\|(y(0,\cdot),\partial_{t}y(0,\cdot))\|_{L^{2}\times H^{-1}}^{2}} \mid (y(0,\cdot),\partial_{t}y(0,\cdot)) \in L^{2}(\Omega) \times H^{-1}(\Omega) \setminus \{(0,0)\}\right\}$$

BUT...



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The model

Observability inequality

$$\forall y \text{ solution} \qquad C_{\mathcal{T}}(\omega) \| (y(0,\cdot), \partial_t y(0,\cdot)) \|_{L^2 \times H^{-1}}^2 \leq \int_0^T \int_\omega |y(t,x)|^2 \, dx \, dt$$

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It is a priori natural to model the problem as:

$$\sup_{\substack{\omega\subset\Omega\\|\omega|=L|\Omega|}}C_{\mathcal{T}}(\omega)$$

BUT:

- Theoretical difficulty due to crossed terms in the spectral expansion (cf Ingham inequalities).
- In practice: many experiments, many measures. This deterministic constant is pessimistic: it gives an account for the worst case.
- → optimize shape and location of sensors in average, over a large number of measurements



define an averaged observability inequality

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Randomized observability constant

Averaging over random initial data:

Randomized observability inequality (wave equation)

$$C_{T,\text{rand}}(\omega) \| (y(0,\cdot), y_t(0,\cdot)) \|_{L^2 \times H^{-1}}^2 \leq \mathbb{E} \left(\int_0^T \int_\omega |y_\nu(t,x)|^2 \, dx \, dt \right)$$

where

$$y_{\nu}(t,x) = \sum_{j=1}^{+\infty} \left(\beta_{1,j}^{\nu} a_j e^{i\lambda_j t} + \beta_{2,j}^{\nu} b_j e^{-i\lambda_j t} \right) \phi_j(x)$$

with $\beta_{1,i}^{\nu}, \beta_{2,i}^{\nu}$ i.i.d. random variables (e.g., Bernoulli, Gaussian) of mean 0

(inspired from Burq-Tzvetkov, Invent. Math. 2008)

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with $(\phi_i)_{i \in \mathbb{N}^*}$ Hilbert basis of eigenfunctions

Randomization • generates a full measure set of initial data • does not regularize



Randomized observability constant



with $(\phi_i)_{i\in\mathbb{N}^*}$ a fixed Hilbert basis of eigenfunctions of riangle

Remark

There holds $C_{T,rand}(\chi_{\omega}) \ge C_T(\chi_{\omega})$.

For the wave equation, the randomized observability constant is a spectral quantity ignoring the rays' contribution.

(→ spectral criterion = half of the truth!)

There are examples where the inequality is strict:

• in 1D:
$$\Omega = (0, \pi), T \neq k\pi$$

in multi-D: Ω stadium-shaped, ω containing the wings.





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Randomized observability constant



with $(\phi_i)_{i \in \mathbb{N}^*}$ a fixed Hilbert basis of eigenfunctions of \triangle

Conclusion: we model the problem as

$$\sup_{\substack{\omega \subset \Omega \\ |\omega| = L|\Omega|}} \inf_{j \in \mathbb{N}^*} \gamma_j \int_{\omega} \phi_j(x)^2 \, dx$$



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$$\sup_{\substack{\omega \subset \Omega \\ |\omega| = L|\Omega|}} \inf_{j \in \mathbb{N}^*} \gamma_j \int_{\omega} \phi_j(x)^2 \, dx$$

To solve the problem, we distinguish between:

parabolic equations (e.g., heat, Stokes) \neq wave or Schrödinger equations

Remarks

- requires some knowledge on the asymptotic behavior of ϕ_i^2
- $\mu_j = \phi_j^2 dx$ is a probability measure \Rightarrow strong difference between $\gamma_i \sim e^{\lambda_j T}$ (parabolic) and $\gamma_i = 1$ (hyperbolic)



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Parabolic equations

(e.g.: heat, Stokes, anomalous diffusions)

We assume that Ω is piecewise C^1

Theorem

There exists a unique optimal domain ω^*

- Quite difficult proof, requiring in particular: Hartung minimax theorem; fine lower estimates of φ²_i by J. Apraiz, L. Escauriaza, G. Wang, C. Zhang (JEMS 2014)
- Algorithmic construction of the best observation set ω^* : to be followed (further)





Optimal value

Under appropriate spectral assumptions:

$$\sup_{\substack{\omega \subset \Omega \\ \omega \mid = L|\Omega|}} \inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j(x)^2 \, dx = L$$

- Proof: 1) convexification (relaxation), 2) no-gap (not obvious because not lsc).
- Main spectral assumption:

QUE (Quantum Unique Ergodicity): the whole sequence $\phi_j^2 dx \rightarrow \frac{dx}{|\Omega|}$ vaguely.

true in 1D, but in multi-D?





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Relationship to quantum chaos theory:

what are the possible (weak) limits of the probability measures $\mu_j = \phi_j^2 dx$? (quantum limits, or semi-classical measures)

 See also Shnirelman theorem: ergodicity implies Quantum Ergodicity (QE; but possible gap to QUE!)

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- If QUE fails, we may have scars
- QUE conjecture (negative curvature)





Optimal value

Under appropriate spectral assumptions:

$$\sup_{\substack{\omega \subset \Omega \\ \omega \mid = L|\Omega|}} \inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j(x)^2 \, dx = L$$

<u>Remark:</u> The above result holds true as well in the disk. Hence the spectral assumptions are not sharp.

(proof: requires the knowledge of all quantum limits in the disk, Privat Hillairet Trélat)





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(this is one QL: whispering galleries)



Optimal value

Under appropriate spectral assumptions:

$$\sup_{\substack{\omega \subset \Omega \\ \omega \mid = L|\Omega|}} \inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j(x)^2 \, dx = L$$

• Supremum reached? Open problem in general.

- in 1D: reached $\Leftrightarrow L = 1/2$ (infinite number of optimal sets)
- in 2D square: reached over Cartesian products $\Leftrightarrow L \in \{1/4, 1/2, 3/4\}$

Conjecture: Not reached for generic domains Ω and generic values of L.

• Construction of a maximizing sequence (by a kind of homogenization)





Spectral approximation

Following Hébrard-Henrot (SICON 2005), we consider the finite-dimensional spectral approximation:

$$\sup_{\substack{\omega \subset \Omega \\ \omega \mid = L|\Omega|}} \min_{1 \le j \le N} \gamma_j \int_{\omega} \phi_j^2(x) \, dx$$

Theorem

The problem has a unique solution ω^N .

Moreover, ω^N is semi-analytic and thus has a finite number of connected components.







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Wave and Schrödinger equations

The complexity of ω^N is increasing with *N*.

Spillover phenomenon: the best domain ω^N for the N first modes is the worst possible for the N + 1 first modes.



Parabolic equations

(e.g., heat, Stokes, anomalous diffusions)

Under a slight spectral assumption: (satisfied, e.g., by $(-\Delta)^{\alpha}$ with $\alpha > 1/2$)

The sequence of optimal sets ω^N is stationary:

$$\exists N_0 \mid \forall N \geq N_0 \quad \omega^N = \omega^{N_0} = \omega^*$$

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with ω^* the optimal set for all modes. In particular, ω^* is semi-analytic and thus has a finite number of connected components.



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The complexity of ω^N is increasing with *N*.

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with ω^* the optimal set for all modes. In particular, ω^* is semi-analytic and thus has a finite number of connected components.

 \rightarrow no fractal set!

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$$\Omega = (0,\pi)^2$$

1, 4, 9, 16, 25, 36 eigenmodes

$$L = 0.2, T = 0.05$$

 \rightarrow optimal thermometer in a square

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Optimal shape and location of sensors

Modeling

Conclusion and perspectives

- Same kind of analysis for the optimal design of the control domain.
- Intimate relations between domain optimization and quantum chaos (quantum ergodicity properties).
- Optimal design for boundary observability (P. Jounieaux' PhD):

$$\sup_{|\omega|=L|\partial\Omega|} \inf_{j\in\mathbb{N}^*} \gamma_j \int_{\omega} \frac{1}{\lambda_j} \left(\frac{\partial\phi_j}{\partial\nu}\right)^2 \, d\mathcal{H}^{n-1}$$

- Strategies to avoid spillover?
- Discretization issues: do the numerical optimal designs converge to the continuous optimal design as the mesh size tends to 0?



Y. Privat, E. Trélat, E. Zuazua,

- Optimal observation of the one-dimensional wave equation, J. Fourier Analysis Appl. (2013).
- Optimal location of controllers for the one-dimensional wave equation, Ann. Inst. H. Poincaré (2013).
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 Optimal observability of the multi-dimensional wave and Schrödinger equations in quantum ergodic results and domains, to appear in J. Europ. Math. Soc. (2015).

What can be said for the classical (deterministic) observability constant? ۰

A result for the wave observability constant: (Humbert Privat Trélat, ongoing)

$$\lim_{T \to +\infty} \frac{C_T(\omega)}{T} = \frac{1}{2} \min \left(\underbrace{\inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j^2 dx}_{j \in \mathbb{N}^*}, \underbrace{\lim_{T \to +\infty} \inf_{\{\gamma \text{ ray}\}} \frac{1}{T} \int_{0}^{T} \chi_{\omega}(\gamma(t)) dt}_{0} \right)$$

iwo quantities: spectral geometric (rays)
$$\downarrow$$
randomized obs. constant



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Remark: another way of arriving at the criterion (wave equation)

Averaging in time:

Time asymptotic observability inequality:

$$\mathcal{C}_{\infty}(\chi_{\omega})\|(y(0,\cdot),y_t(0,\cdot))\|_{L^2\times H^{-1}}^2\leq \lim_{T\to +\infty}\frac{1}{T}\int_0^T\int_{\omega}|y(t,x)^2|\,dx\,dt,$$

with

$$\mathcal{C}_{\infty}(\chi_{\omega}) = \inf \left\{ \lim_{T \to +\infty} \frac{1}{T} \frac{\int_{0}^{T} \int_{\omega} |y(t, x)|^{2} dx dt}{\left\| (y(0, \cdot), y_{t}(0, \cdot)) \right\|_{L^{2} \times H^{-1}}^{2}} \left\| (y(0, \cdot), y_{t}(0, \cdot)) \in L^{2} \times H^{-1} \setminus \{(0, 0)\} \right\}.$$

Theorem

If the eigenvalues of \triangle_g are simple then $C_{\infty}(\chi_{\omega}) = \frac{1}{2} \inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j(x)^2 dx = \frac{1}{2} J(\chi_{\omega}).$

Remarks

•
$$C_{\infty}(\chi_{\omega}) \leq \frac{1}{2} \inf_{j \in \mathbb{N}^*} \int_{\omega} \phi_j(x)^2 dx.$$



Imsup $\frac{C_T(\chi_\omega)}{T} \leq C_\infty(\chi_\omega)$. There are examples where the inequality is strict.



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A remark for fixed initial data

If we maximize $\omega \mapsto \int_0^T \int_{\omega} |y(t, x)|^2 dx dt$ with **fixed initial data**, then, using a decreasing rearrangement argument:

There always exists (at least) one optimal set ω . The regularity of ω depends on the initial data: it may be a Cantor set of positive measure, even for C^{∞} data.



 \rightarrow In our model, we consider an infimum over all initial data.



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Let A > 0 fixed. If we restrict the search to

$$\{\omega \subset \Omega \mid |\omega| = L|\Omega| \text{ and } P_{\Omega}(\omega) \leq A\} \qquad (\text{perimeter})$$
or
$$\{\omega \subset \Omega \mid |\omega| = L|\Omega| \text{ and } ||\chi_{\omega}||_{BV(\Omega)} \leq A\} \qquad (\text{total variation})$$
or
$$\{\omega \subset \Omega \mid |\omega| = L|\Omega| \text{ and } \omega \text{ satisfies the } 1/A\text{-cone property}\}$$
or

 ω ranges over some finite-dimensional (or "compact") prescribed set...

then there always exists (at least) one optimal set ω .

 \rightarrow but then...

- the complexity of ω may increase with A
- we want to know if there is a "very best" set (over all possible measurable)





Remedies (wave and Schrödinger equations)

1. Existence of a maximizer

Ensured if \mathcal{U}_L is replaced with any of the following choices:

$$\begin{aligned} \mathcal{V}_L &= \{ \chi_\omega \in \mathcal{U}_L \mid \mathcal{P}_\Omega(\omega) \leq \mathbf{A} \} & \text{(perimeter)} \\ \mathcal{V}_L &= \{ \chi_\omega \in \mathcal{U}_L \mid \| \chi_\omega \|_{\mathcal{B}V(\Omega)} \leq \mathbf{A} \} & \text{(total variation)} \\ \mathcal{V}_L &= \{ \chi_\omega \in \mathcal{U}_L \mid \omega \text{ satisfies the } 1/\mathbf{A}\text{-cone property} \} \end{aligned}$$

where A > 0 is fixed.





Modeling

Remedies (wave and Schrödinger equations)

2. Weighted observability inequality

$$C_{T,\sigma}(\chi_{\omega})\left(\|(y^{0},y^{1})\|_{L^{2}\times H^{-1}}^{2}+\sigma\|y^{0}\|_{H^{-1}}^{2}\right)\leq \int_{0}^{T}\int_{\Omega}|y(t,x)|^{2}\,dx\,dt,$$

where $\sigma \geq$ 0: weight.

Note that $C_{T,\sigma}(\chi_{\omega}) \leq C_T(\chi_{\omega})$.

Randomization \Rightarrow 2 $C_{T,\sigma,rand}(\chi_{\omega}) = T J_{\sigma}(\chi_{\omega})$, where

$$J_{\sigma}(\chi_{\omega}) = \inf_{j \in \mathbb{N}^*} \sigma_j \int_{\omega} \phi_j(x)^2 \, dx,$$



with
$$\sigma_j = \frac{\lambda_j^2}{\sigma + \lambda_j^2}$$
.

Remedies (wave and Schrödinger equations)

Theorem

Assume that L^{∞} -QUE holds. If $\sigma_1 < L < 1$ then there exists $N \in \mathbb{N}^*$ such that

$$\sup_{\omega \in \mathcal{U}_L} \inf_{j \in \mathbb{N}^*} \sigma_j \int_{\omega} \phi_j^2 = \max_{\chi_\omega \in \mathcal{U}_L} \inf_{1 \leq j \leq n} \sigma_j \int_{\omega} \phi_j^2 \leq \sigma_1 < L$$

for every $n \ge N$. In particular there is a unique solution χ_{ω^N} . Moreover if M is analytic then ω^N is semi-analytic and has a finite number of connected components.

- The condition $\sigma_1 < L < 1$ seems optimal (see numerical simulations).
- This result holds as well in any torus, or in the Euclidean *n*-dimensional square for Dirichlet or mixed Dirichlet-Neumann conditions.





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An additional remark

Anomalous diffusion equations, Dirichlet: with a surprising result:

$$\partial_t y + (-\triangle)^{\alpha} y = 0$$
 ($\alpha > 0$ arbitrary)

In the square $\Omega = (0, \pi)^2$, with the usual basis (products of sine): the optimal domain ω^* has a finite number of connected components, $\forall \alpha > 0$.

In the disk $\Omega = \{x \in \mathbb{R}^2 \mid ||x|| < 1\}$, with the usual basis (Bessel functions), the optimal domain ω^* is radial, and

•
$$\alpha > 1/2 \Rightarrow \omega^* =$$
 finite number of concentric rings (and $d(\omega, \partial \Omega) > 0$)

 α < 1/2 ⇒ ω^{*} = infinite number of concentric rings accumulating at ∂Ω! (or α = 1/2 and *T* small enough)

The proof is long and very technical. It uses in particular the knowledge of quantum limits in the disk. (L. Hillairet, Y. Privat, E.Trélat)



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1, 4, 9, 16, 25, 36 eigenmodes

 $L = 0.2, T = 0.05, \alpha = 1$



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1, 4, 25, 100, 144, 225 eigenmodes

 $L = 0.2, T = 0.05, \alpha = 0.15$



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Comparison

$$\sup_{\chi_{\omega}\in\mathcal{U}_{L}}\inf_{j\in\mathbb{N}^{*}}\gamma_{j}\int_{\omega}\phi_{j}^{2}$$

	square	disk
wave or Schrödinger	relaxed solution $a = L$ $\exists \omega \text{ for } L \in \{\frac{1}{4}, \frac{1}{2}, \frac{3}{4}\}$ $\nexists \text{ otherwise (conjecture)}$	relaxed solution $a = L$ $\exists \omega \text{ for } L \in \{\frac{1}{4}, \frac{1}{2}, \frac{3}{4}\}$ $\not\exists$ otherwise (conjecture)
diffusion $(-\triangle)^{lpha}$	$\exists ! \omega orall L orall lpha > 0 \ \# c.c.(\omega) < +\infty$	$\exists ! \omega \text{ (radial)} \forall L \forall \alpha > 0$ if $\alpha > 1/2$ then $\# c.c.(\omega) < +\infty$ if $\alpha < 1/2$ then $\# c.c.(\omega) = +\infty$

