# An SDP relaxation for computing distances between metric spaces 

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## SIAM Imaging

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## Outline and References

- Gromov-Hausdorff distance.
- Facundo Mémoli. On the use of Gromov-Hausdorff Distances for Shape Comparison.
- SDP relaxation of Gromov-Hausdorff distance.
- Numerical performance on real data.
- Future work.


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- Yang, Sun and Toh. SDPNAL+: a majorized semismooth Newton-CG augmented Lagrangian method for semidefinite programming with nonnegative constraints.
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## The Hausdorff distance

Let $X, Y$ compact sets of a metric space. Define

$$
\begin{aligned}
d(x, Y) & =\inf \{d(x, y): y \in Y\} \\
d(X, Y) & =\sup \{d(x, Y): x \in X\}
\end{aligned}
$$



$$
d_{H}(X, Y)=\max \{d(X, Y), d(Y, X)\}
$$

## The Gromov-Hausdorff distance

Let $X, Y$ compact metric spaces. Define

$$
d_{G H}(X, Y)=\inf _{Z, f, g} d_{H}(f(X), g(Y))
$$

where $f: X \rightarrow Z, \quad g: Y \rightarrow Z$ are isometric embeddings.

Fact: $d_{G H}(X, Y)=0$ if and only if $X, Y$ are isometric

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## Gromov-Hausdorff distance in point clouds

Motivations

- Shape comparison of geometric objects (like surfaces).
- Applications to spaces where geometry is less apparent (like tree spaces, dna sequences, etc).


## Quadratic assignment formulation (Mémoli 2007)

$$
\begin{aligned}
& \text { Let } X=\left\{x_{1}, \ldots, x_{n}\right\}, Y=\left\{y_{1}, \ldots, y_{m}\right\} . \\
& \text { Let } R \subset X \times Y \text { and } \delta_{i j}=\left\{\begin{array}{cc}
1 & \text { if }\left(x_{i}, y_{j}\right) \in R \\
0 & \text { otherwise }
\end{array}\right. \\
& \text { Let } \Gamma_{i k, j l}=\left|d_{X}\left(x_{i}, x_{k}\right)-d_{Y}\left(y_{j}, y_{l}\right)\right| \\
& d_{G H}(X, Y)=\frac{1}{2} \quad \min _{R} \quad \max _{i k, j l} \Gamma_{i k, j l} \delta_{i j} \delta_{k l}
\end{aligned}
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Fact: Computing GH distance is NP-hard and also, to approximate it better than a factor of 3 is NP-hard (Agarwal et al 2015).

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& \text { subject to } \quad \delta_{i j} \in\{0,1\}, \sum_{j=1}^{m} \delta_{i j} \geq 1, \sum_{i=1}^{n} \delta_{i j} \geq 1
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## Gromov-Wasserstein distance (Mémoli 2007)

$$
D_{G W, p}(X, Y)=\frac{1}{2}\left(\inf _{\delta} \sum_{i, j} \sum_{k, l} \Gamma_{i k, j l}^{p} \delta_{i j} \delta_{k l}\right)^{1 / p} \quad \sum_{i} \delta_{i j}=1, \sum_{j} \delta_{i j}=1
$$

- In this formulation $\delta$ 's are thought as probability measures on the set of points ( $\delta^{\prime} s$ do not come from a map).
- The max is changed for a sum.
- Mémoli considers a spectral relaxation of the Gromov-Wasserstein distance using heat kernels.


## An SDP relaxation of the Gromov-Hausdorff distance

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\begin{array}{lll}
\tilde{d}(X, Y)= & \min _{Z} \quad \sum_{i, j, k, l} \Gamma_{i k, j l} Z_{i j, k l} \\
& & \sum_{i=1} X_{i j, i j}=1 \text { for all } j \\
& \sum_{j=1} Z_{i j, i j}=1 \text { for all } i \\
& Z_{i j, i l}=0, \text { for all } i, j, l \text { with } l \neq j, \\
& Z_{i j, k j}=0, \text { for all } i, j, k \text { with } i \neq k, \\
& Z_{i j, k l} \geq 0, \quad Z \succeq 0 \\
& \sum_{i} Z_{i j, N^{2}+1}=1 \text { for all } j, \\
& & \sum_{j} Z_{i j, N^{2}+1}=1 \text { for all } i, \\
& & Z_{N^{2}+1, N^{2}+1}=1
\end{array}
$$

## Some properties of $\tilde{d}$

- $\tilde{d}(X, Y)$ is a lower bound for a distance between metric spaces.
- $\tilde{d}(X, Y) \leq \tilde{d}(X, W)+\tilde{d}(W, Y)$
- $\tilde{d}(X, Y)=0$ if $X$ and $Y$ are isometric, and the SDP finds the isometry.
- $\tilde{d}(X, Y)$ may be 0 for non isometric $X$ and $Y$.


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## Numerical considerations

Computing $\tilde{d}$ involves solving a big SDP!

- Improving SDP solvers is an active research area.
- Work around with sampling, good initializations, etc.
- SDP's and dual certificates can be used to obtain fast algorithms (see Dustin's talk tomorrow).


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## Real data application

Boyer, Lipman, Daubechies, et al. Algorithms to automatically quantify the geometric similarity of anatomical surfaces.


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Objective: teeth classification.
Two methods:

1. Lipman and Daubechies map the teeth surfaces to the hyperbolic disk and consider a Wesserstein distance that is invariant under conformal transformations.
2. Boyer labels 18 landmarks on each teeth. Then they find the best rigid transformation to match the labeled landmarks.
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## Real data application

Our experiments

- Consider $X_{i}=\left\{p_{1}^{i}, \ldots p_{18}^{i}\right\} i=1 \ldots 116$.
- Find $\tilde{d}\left(X_{i}, X_{j}\right)$
- Use their classification scheme


## Future work

- Understand topological properties of this SDP-induced distance on the set of finite metric spaces.
- Convergence
- Compactness
- Applications to datasets that are not surfaces.
- Understand how the distance behaves with respect to sampling under geometric assumptions.
- Compare with other lower bounds available in the literature.


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## Questions?

Tomorrow:
MS22: Convex Signal Recovery from Pairwise Measurements

10:30-10:55. Dustin Mixon. Probably Certifiably Correct K-Means Clustering.

11:00-11:25. Soledad Villar. Efficient Global Solutions to K-Means Clustering Via Semidefinite Relaxation

