k-means clustering of Gaussian mixtures

Soledad Villar

University of Texas at Austin

Based on work with: Dustin Mixon (AFIT) Rachel Ward (UT Austin)

SIAM Imaging

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

k-means SDP

k-means objective:

$$\sum_{t=1}^{k} \sum_{i \in C_t} \left\| x_i - \frac{1}{|C_t|} \sum_{j \in C_t} x_j \right\|^2$$



・ロト ・聞ト ・ヨト ・ヨト

э

k-means SDP

k-means objective:

$$\sum_{t=1}^{k} \sum_{i \in C_t} \left\| x_i - \frac{1}{|C_t|} \sum_{j \in C_t} x_j \right\|^2$$



 $\begin{array}{ll} \text{minimize} & \operatorname{Tr}(DX) \\ \text{subject to} & \operatorname{Tr}(X) = k \\ & X1 = 1 \\ & X \geq 0 \\ & X \succeq 0 \end{array}$





Peng, Wei, SIAM J. Optim., 2007

What about outliers?

We exploited the SDP being tight.



▲□▶ ▲圖▶ ★ 臣▶ ★ 臣▶ = 臣 = の Q @

SDP guarantees for more realistic data?

The big idea



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへで

The big idea

 $X1 = 1, X \ge 0 \text{ and } X^{\top} = X, \text{ so } X \text{ is doubly stochastic}$ $X_{\text{opt}} \text{ integral} \Longrightarrow PX_{\text{opt}} = \left[\begin{array}{cc} \hat{\gamma}_1 \cdots \hat{\gamma}_1 \\ n_1 \text{ copies} \end{array} \begin{array}{c} \hat{\gamma}_2 \cdots \hat{\gamma}_2 \\ n_2 \text{ copies} \end{array} \begin{array}{c} \cdots \\ n_k \text{ copies} \end{array} \right]$

What if X_{opt} is not integral?

Example: $P \mapsto PX_{opt}$

The big idea

 $X1 = 1, X \ge 0 \text{ and } X^{\top} = X, \text{ so } X \text{ is doubly stochastic}$ $X_{\text{opt}} \text{ integral} \Longrightarrow PX_{\text{opt}} = \left[\begin{array}{cc} \hat{\gamma}_1 \cdots \hat{\gamma}_1 \\ n_1 \text{ copies} \end{array} \begin{array}{c} \hat{\gamma}_2 \cdots \hat{\gamma}_2 \\ n_2 \text{ copies} \end{array} \begin{array}{c} \cdots \\ n_k \text{ copies} \end{array} \right]$

What if X_{opt} is not integral?

Example: $P \mapsto PX_{opt}$



Moral: PX_{opt} is a "denoised" version of P

How to explain denoising?

 $X_{\text{plant}} = \text{planted clustering (integral)}$

Denoising \iff small "mean squared error"

$$\begin{split} \mathsf{MSE} &= \frac{1}{N} \sum_{t=1}^{k} \sum_{i=1}^{n} \|c_{t,i} - \hat{\gamma}_{t}\|^{2} \\ &= \frac{1}{N} \|PX_{\mathrm{opt}} - PX_{\mathrm{plant}}\|_{\mathrm{F}}^{2} \leq \frac{1}{N} \|P\|_{2}^{2} \|X_{\mathrm{opt}} - X_{\mathrm{plant}}\|_{\mathrm{F}}^{2} \end{split}$$

Triangle: $||P||_2 \le ||Gaussian \text{ centers}||_2 + ||Gaussian \text{ noise}||_2$

Remaining task: Estimate $\|X_{opt} - X_{plant}\|_{F}$

How to explain denoising?

$$M(v) := \arg \max_{x \in S} \langle x, v \rangle$$

$$a \approx_S b \implies M(a) \approx M(b)$$

Trick: Find R such that

•
$$M(R) = X_{\text{plant}}$$

► $R \approx_S -D$



Guédon, Vershynin, arXiv:1411.4686 Mixon, Villar, Ward, arXiv:1602.06612

How to explain denoising?

$$M(v) := \arg \max_{x \in S} \langle x, v \rangle$$

$$a \approx_S b \implies M(a) \approx M(b)$$

Trick: Find *R* such that

$$M(R) = X_{\text{plant}}$$

$$R \approx_S - D$$



Theorem

$$\|X_{\text{opt}} - X_{\text{plant}}\|_{\text{F}} \le \epsilon \text{ whp provided } \min_{i \ne j} \|\gamma_i - \gamma_j\| \gtrsim \frac{k\sigma}{\epsilon}.$$

Guédon, Vershynin, arXiv:1411.4686 Mixon, Villar, Ward, arXiv:1602.06612

Estimating Gaussian centers

After denoising, "round":

for i = 1 : k

 $v_i \leftarrow$ denoised point with most neighbors delete denoised point and neighbors **endfor**

Mixon, Villar, Ward, arXiv:1602.06612 Dasgupta, FOCS, 1999

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Estimating Gaussian centers

After denoising, "round":

for i = 1 : k

 $v_i \leftarrow$ denoised point with most neighbors delete denoised point and neighbors **endfor**

Theorem $\frac{1}{k}\sum_{i=1}^{k} \|v_i - \hat{\gamma}_i\|^2 \lesssim k^2 \sigma^2 \text{ whp provided } \min_{i \neq j} \|\gamma_i - \gamma_j\| \gtrsim k\sigma.$

(Trade Dasgupta's *m*-dependence for *k*-dependence)

How to remove the *k*-dependence in SNR and MSE?

Mixon, Villar, Ward, arXiv:1602.06612 Dasgupta, FOCS, 1999

We say $\Gamma \subseteq \mathbb{R}^m$ is a **stable isogon** if

- ► |Γ| > 1
- the symmetry group $G \leq O(m)$ acts transitively on Γ
- ▶ for each $\gamma \in \Gamma$, the stabilizer G_{γ} has the property that

$$\left\{x \in \mathbb{R}^m : Qx = x \;\; \forall Q \in G_{\gamma}\right\} = \operatorname{span}\{\gamma\}$$

Example: Platonic solids



Given $\Gamma \subseteq \mathbb{R}^m$, consider the Voronoi cells $\{V_{\gamma}\}_{\gamma \in \Gamma}$

 $\mathcal{D}=\mathsf{mixture}$ of Gaussians centered at Γ

Define the Voronoi means by

$$\mu_{\gamma} := \mathop{\mathbb{E}}_{X \sim \mathcal{D}} \left[X \middle| X \in V_{\gamma} \right]$$



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <



・ロト ・聞ト ・ヨト ・ヨト



æ

イロト イポト イヨト イヨト



▲□▶ ▲□▶ ▲目▶ ▲目▶ = 目 - のへで



Voronoi Means Conjecture

Draw *N* points from a balanced mixture of spherical Gaussians of equal variance centered at points in a stable isogon. Then the *k*-means-optimal centroids converge in probability to the Voronoi means as $N \to \infty$.

 Γ = standard orthoplex in first k/2 dimensions of \mathbb{R}^m

 $\mathcal{D} =$ balanced Gaussian mixture with centers Γ , covariance $\sigma^2 I$

Theorem

For every $\sigma > 0$, either $\min_{\substack{\gamma,\gamma'\in\Gamma\\\gamma\neq\gamma'}} \|\gamma - \gamma'\| \gtrsim \sigma \sqrt{\log k} \quad \text{or} \quad \min_{\gamma\in\Gamma} \|\mu_{\gamma} - \gamma\| \gtrsim \sigma \sqrt{\log k}$

Moral: If VMC, then either SNR or MSE exhibits k-dependence

Numerical experiment on MNIST dataset

- 1. Train a simple (one layer) neural network using TensorFlow.
- 2. Use it to map 1000 testing digits to feature space.
- 3. Run SDP denoising.
- 4. Find clusters using rounding scheme.







イロト イポト イヨト イヨト

Questions?

Clustering subgaussian mixtures by semidefinite programming

D. G. Mixon, S. Villar, R. Ward arXiv:1602.06612