



Conceptual Climate Models Minitutorial Part II

Jim Walsh Oberlin College

SIAM MPE Conference Philadelphia, PA September 30, 2016

Resources:

- https://mcrn.hubzero.org/resources/81#series. Videos of lectures and lecture slides from Introduction to the Mathematics of Climate, taught by Richard McGehee, School of Mathematics, University of Minnesota.
- https://mcrn.hubzero.org/resources/523/supportingdocs. Material developed for the MAA-NCS Summer Seminar Conceptual Climate Models, held in Minneapolis, July 2013. Contributors: A. Barry, R. McGehee, S. Oestreicher, J.A. Walsh, E. Widiasih.
- J.A. Walsh, Climate modeling in differential equations, *The UMAP Journal* 36 (4) (2015), 325-363.





Coupled zonal temperature – ice line model



- An infinite-dimensional dynamical system
- Symmetry assumption \implies functions are even in y
- Consider an approximating system of ODEs





$$R\frac{\partial T}{\partial t} = Qs(y)(1 - \alpha(y, \eta)) - (A + BT) - C(T - \overline{T})$$

$$\int_{0}^{1} s(y)dy = 1$$

$$s(y)_{0} = \int_{0}^{1} \frac{1}{\beta(y)} dy = 1$$

$$s(y)_{0} = \int_{0}^{1} \frac{1}{\beta(y)} dy = 1$$

$$\int_{0}^{1} \frac{1}{\beta(y)} dy = 1$$

Dashed: actual (current) values

Solid: $s(y) = s_0 p_0(y) + s_2 p_2(y), \ p_0(y) = 1, \ p_2(y) = \frac{1}{2}(3y^2 - 1)$ the first two even Legendre polys, $s_0 = 1, \ s_2 = -0.482$











$$Rrac{\partial T}{\partial t} = Qs(y)(1-lpha(y,\eta)) - (A+BT) - C(T-\overline{T})$$







Approximating system of ODEs

 $s(y) = s_0 p_0(y) + s_2 p_2(y)$

$$egin{aligned} & \displaystyle \int R rac{\partial T}{\partial t} = Qs(y)(1-lpha(y,\eta)) - (A+BT) - C(T-\overline{T}) \ & \displaystyle rac{d\eta}{dt} = \epsilon(T(\eta,t)-T_c), \ \ \epsilon > 0 \end{aligned}$$



$$T(y,t) = egin{cases} U(y,t), & y < \eta \ V(y,t), & y > \eta \end{cases}$$

$$egin{aligned} U(y,t) &= u_0(t)p_0(y) + u_2(t)p_2(y) \ V(y,t) &= v_0(t)p_0(y) + v_2(t)p_2(y) \end{aligned}$$

$$T(\eta,t) = \tfrac{1}{2}(U(\eta,t) + V(\eta,t))$$

R. McGehee and E. Widiasih, A quadratic approximation to Budyko's ice albedo feedback model with ice line dynamics, *SIAM J. Appl. Dyn. Syst.* **13** (2014), 518-536.





 $p_0(y)=1, \; p_2(y)=rac{1}{2}(3y^2-1)$

Approximating system of ODEs

$$Rrac{\partial T}{\partial t} = Qs(y)(1 - \alpha(y, \eta)) - (B + C)T - A + C\overline{T}$$

$$T(y,t)= egin{cases} U(y,t), & y<\eta & U(y,t)=\ V(y,t), & y>\eta & V(y,t)=
ight.$$

$$egin{aligned} U(y,t) &= u_0(t)p_0(y) + u_2(t)p_2(y) \ V(y,t) &= v_0(t)p_0(y) + v_2(t)p_2(y) \end{aligned}$$

$$y < \eta$$

$$egin{aligned} Rrac{\partial T}{\partial t} &= R(\dot{u}_0p_0(y)+\dot{u}_2p_2(y)) \ Qs(y)(1-lpha(y,\eta)) &= Q(s_0p_0(y)+s_2p_2(y))(1-lpha_1) \ (B+C)T &= (B+C)(u_0p_0(y)+u_2p_2(y)) \ -A+C\overline{T} &= (-A+C\overline{T})p_0(y) \end{aligned}$$

plug in, equate coefficients of $p_0(y)$ and $p_2(y)$, respectively...





$$T(y,t) = egin{cases} U(y,t), & y < \eta \ V(y,t), & y > \eta \end{cases}$$

$$egin{aligned} U(y,t) &= u_0(t)p_0(y) + u_2(t)p_2(y) \ V(y,t) &= v_0(t)p_0(y) + v_2(t)p_2(y) \end{aligned}$$

$$egin{aligned} R\dot{u}_0 &= Q(1-lpha_1) - (B+C)u_0 - A + C\overline{T} \ R\dot{u}_2 &= Qs_2(1-lpha_1) - (B+C)u_2 \end{aligned}$$

Repeat for $y > \eta$:

Approximating system of ODEs

$$egin{aligned} R\dot{v}_0 &= Q(1-lpha_2) - (B+C)v_0 - A + C\overline{T} \ R\dot{v}_2 &= Qs_2(1-lpha_2) - (B+C)v_2 \end{aligned}$$

Include the ice line equation...





Approximating system of ODEs

$$egin{aligned} & R\dot{u}_0 = Q(1-lpha_1) - (B+C)u_0 - A + C\overline{T} \ & R\dot{u}_2 = Qs_2(1-lpha_1) - (B+C)u_2 \ & R\dot{v}_0 = Q(1-lpha_2) - (B+C)v_0 - A + C\overline{T} \ & R\dot{v}_2 = Qs_2(1-lpha_2) - (B+C)v_2 \ & \dot{\eta} = \epsilon(T(\eta,t)-T_c) \end{aligned}$$

$$ullet \ \overline{T} = \int_0^\eta U(y,t) dy + \int_\eta^1 V(y,t) dy = \overline{T}(u_0,u_2,v_0,v_2,\eta)$$

•
$$T(\eta,t) = \frac{1}{2}(U(\eta,t) + V(\eta,t)) = T(u_0,u_2,v_0,v_2,\eta)$$

change variables $w = rac{1}{2}(u_0+v_0), \,\, z=u_0-v_0$







Approximating system of ODEs

$$\left[lpha_0=rac{1}{2}(lpha_1+lpha_2)
ight]$$

$$egin{aligned} R\dot{w} &= Q(1-lpha_0) - (B+C)w - A + C\overline{T} \ R\dot{z} &= Q(lpha_2 - lpha_1) - (B+C)z \ Ru_2 &= Qs_2(1-lpha_1) - (B+C)u_2 \ Rv_2 &= Qs_2(1-lpha_2) - (B+C)v_2 \ \dot{\eta} &= \epsilon(T(\eta,t) - T_c) \end{aligned}$$

$$ullet \ \overline{T} = \overline{T}(w,z,u_2,v_2,\eta) \quad ullet \ T(\eta,t) = T(w,z,u_2,v_2,\eta)$$

Assume
$$z, u_2, v_2$$
 are at equilibrium \implies $\bullet \overline{T} = \overline{T}(w, \eta)$
 $\bullet T(\eta, t) = T(w, \eta)$





$$\dot{w} = - au(w-F(\eta)) \ \dot{\eta} = \epsilon(w-G(\eta)),$$

 $egin{aligned} F(\eta) &= \gamma(\eta) - A/B \ & (F(\eta) ext{ cubic in } \eta; \ au = B/R) \ & G(\eta) ext{ quadratic in } \eta \end{aligned}$







$$\dot{w} = - au(w-F(\eta)) \ \dot{\eta} = \epsilon(w-G(\eta)),$$

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 $egin{aligned} F(\eta) &= \gamma(\eta) - A/B \ & (F(\eta) ext{ cubic in } \eta; \ au &= B/R) \ & G(\eta) ext{ quadratic in } \eta \end{aligned}$







Approximating system of ODEs

$$T(y,t) = egin{cases} U(y,t), & y < \eta \ V(y,t), & y > \eta \end{cases}$$

 $egin{aligned} U(y,t) &= u_0(t)p_0(y) + u_2(t)p_2(y) \ V(y,t) &= v_0(t)p_0(y) + v_2(t)p_2(y) \end{aligned}$





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$$F(\eta) = \gamma(\eta) - {oldsymbol A}/B$$

 $G(\eta)$ quadratic in η



 $(F(\eta) ext{ cubic in } \eta; \ au = B/R)$





Approximating system of ODEs







Approximating system of ODEs







 $egin{aligned} \dot{w} &= - au(w-F(\eta)) \ \dot{\eta} &= \epsilon(w-G(\eta)), \end{aligned}$

Saturday, October 1 MS13 *Mathematics and Conceptual Climate Modeling* 9:30-9:55 Conceptual Models: Understanding Past Climate Through Mathematics, Esther Widiasih







Meridional heat transport

$$R\frac{\partial T}{\partial t} = E_{\text{in}} - E_{\text{out}} - E_{\text{transport}}$$
$$= Qs(y)(1 - \alpha_{\eta}(y)) - (A + BT(y, t)) - C\left(T(y, t) - \int_{0}^{1} T(y, t) dy\right)$$

• $E_{\text{transport}} = C(T - \overline{T})$ (relaxation to the mean)

•
$$E_{\text{transport}} = D\nabla^2 T = D \frac{\partial}{\partial y} (1 - y^2) \frac{\partial T}{\partial y}$$
 (diffusion process)

Models: Heat flux resulting from horizontal redistribution by the circulations of the oceans and atmosphere



 $\sim \mathbf{T}$



Thermohaline Circulation



Image Credit: NASA

thermo: heat *haline*: salt

The rate of circulation is a function of the <u>temperature</u> and <u>salinity</u> and can change over time.





Atlantic Meridional Overturning Circulation

Part of the *thermohaline circulation*



illustration by jg. Source for Earth's topology: NASA/JPL-Caltech





Resources:

- H. Stommel, Thermohaline convection with two stable regimes of flow, *Tellus* XIII (2) (1961)
- https://mcrn.hubzero.org/resources/81#series. Videos of lectures and lecture slides from Introduction to the Mathematics of Climate, taught by Richard McGehee, School of Mathematics, University of Minnesota.
- H. Kaper and H. Engler, *Mathematics and Climate*, SIAM (2013)







Inreases as salinity (S) increases







Temperature

$$egin{aligned} \dot{T}_1 &= c(\mathcal{T}^* - T_1) - |q|(T_1 - T_2) \ \dot{T}_2 &= c(-\mathcal{T}^* - T_2) + |q|(T_1 - T_2) \end{aligned}$$









Temperature

$$egin{aligned} \dot{T}_1 &= c(\mathcal{T}^* - T_1) - |q|(T_1 - T_2) \ \dot{T}_2 &= c(-\mathcal{T}^* - T_2) + |q|(T_1 - T_2) \end{aligned}$$

$egin{aligned} & \underline{ ext{Salinity}} \ \dot{S}_1 = d(\mathcal{S}^* - S_1) - |q|(S_1 - S_2) \ \dot{S}_2 = d(-\mathcal{S}^* - S_2) + |q|(S_1 - S_2) \end{aligned}$

$$rac{d}{dt}(T_1+T_2) = -c(T_1+T_2) \; \Rightarrow \; T_1+T_2 o 0.$$
 Set $T_1 = -T_2 = T$

Similarly, set
$$S_1 = -S_2 = S$$







$$egin{aligned} \dot{T} &= c(\mathcal{T}^* - T) - 2|q|T \ \dot{S} &= d(\mathcal{S}^* - S) - 2|q|S \end{aligned}$$

Flow rate q: proportional to density differences

$$kq = \rho_1 - \rho_2$$

Density
$$ho=
ho(T,S)=
ho_0(1-lpha T+eta S), \ \ lpha,eta>0$$

 $\left| egin{array}{c}
ho_0 & \mathrm{reference} \ \mathrm{density} \end{array}
ight|$

Flow rate:
$$kq =
ho_1 -
ho_2 = 2
ho_0(-lpha T + eta S)$$





$$egin{aligned} \dot{T} &= c(\mathcal{T}^* - T) - 2|q|T \ \dot{S} &= d(\mathcal{S}^* - S) - 2|q|S \end{aligned}$$

$$kq=2
ho_0(-lpha T+eta S)$$

Nondimensionalize ... and more!

flow rate

$$y=rac{T}{\mathcal{T}^*},\,\,x=rac{S}{\mathcal{S}^*},\,\, au=ct,\,\,\delta=rac{d}{c},\,\,f=2rac{q}{c}$$

$$egin{array}{l} \displaystylerac{dx}{d au} = \delta(1-x) - |f|x \ \displaystylerac{dy}{d au} = 1 - y - |f|y \end{array}$$





$$y = \frac{T}{\mathcal{T}^*}, \ x = \frac{S}{\mathcal{S}^*}, \ \tau = ct, \ \delta = \frac{d}{c}, \ f = 2\frac{q}{c}$$

$$\begin{bmatrix} \frac{dx}{d\tau} = \delta(1-x) - |f|x\\ \frac{dy}{d\tau} = 1 - y - |f|y \end{bmatrix}$$

$$kq = 2\rho_0(-\alpha T + \beta S)$$
Flow rate:
$$kq = 2\rho_0 \alpha \mathcal{T}^*(-y + Rx) = k\frac{cf}{2}$$

$$\begin{bmatrix} R = \frac{\beta \mathcal{S}^*}{\alpha \mathcal{T}^*} \end{bmatrix}$$

$$f = \frac{1}{\lambda}(-y + Rx), \ \lambda = \frac{ck}{4\rho_0 \alpha \mathcal{T}^*}$$





$$y=rac{T}{\mathcal{T}^*},\,\,x=rac{S}{\mathcal{S}^*}$$

$$egin{aligned} rac{dx}{d au} &= \delta(1-x) - |f|x \ rac{dy}{d au} &= 1-y - |f|y \end{aligned}$$

$$f=rac{1}{\lambda}(-y+Rx), ~~~\lambda=rac{ck}{4
ho_0lpha \mathcal{T}^*}$$

At equilibrium:
$$x^* = \frac{\delta}{\delta + |f|}, \ y^* = \frac{1}{1 + |f|}$$

 $\lambda f = -y^* + Rx^* = -\frac{1}{1 + |f|} + R\frac{\delta}{\delta + |f|} = \phi(f, R, \delta)$

Solutions of $\lambda f = \phi(f, R, \delta)$ yield equilibria (x^*, y^*)

















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$$\frac{dx}{d\tau} = \delta(1-x) - |f|x$$

$$\frac{dy}{d\tau} = 1 - y - |f|y$$

$$\lambda f = -y + Rx$$

$$\frac{\delta = 1/6}{R = 2}$$

$$\lambda = 1/5$$
Gulf Stream flowing north
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x salinity







Increase $k \Rightarrow$ increase λ : Increase the resistance in the capillary











$$\delta = 1/6 \ R = 2 \ \lambda = 1/5$$



 $\delta=1/6\ R=2$











$$\delta = 1/6 \ R = 2 \ \lambda = 0.3$$

The stable node *a* and the saddle *b* begin to merge

$$\delta = 1/6$$
 , $R = 2$ $\lambda = 0.33$













 $\delta = 1/6$ R = 2 $\lambda = 0.4$

Increase the flow resistance sufficiently and the stable node and saddle disappear. The Gulf Stream will eventually reverse.



Now decrease $\lambda \Rightarrow$ decrease the resistance in the capillary





Stommel's model: Hysteresis

The stable node *a* and the saddle *b* have remerged, but it is difficult to get to *a*. The Gulf Stream is still reversed.

We are back to our original parameters, but the Gulf Stream is still reversed.



MCRN

Stommel's model: Hysteresis

$$\delta = 1/6 \ R = 2 \ \lambda = 0.1$$

The flow resistance is below the original value. Point *a* is the dominant attractor. Perhaps the Gulf Stream will find a way to return to normal.











Atlantic Meridional Overturning Circulation

L. G. Henry, J. F. McManus, W. B. Curry, N. L. Roberts, A. M. Piotrowski, L. D. Keigwin, North Atlantic ocean circulation and abrupt climate change during the last glaciation, *Science*, June 30, 2016.

"The last ice age wasn't one long big chill. Dozens of times temperatures abruptly rose or fell, causing all manner of ecological change.

Now, scientists have implicated the culprit behind those seesaws—changes to a conveyor belt of ocean currents known as the Atlantic Meridional Overturning Circulation (AMOC).

These currents, which today drive the Gulf Stream, bring warm surface waters north and send cold, deeper waters south. **But they weakened suddenly and drastically, nearly to the point of stopping, just before several periods of abrupt climate change**, researchers report today in Science."

Eric Hand, http://www.sciencemag.org/news/2016/06/crippled-atlantic-conveyor-triggered-ice-age-climate-change





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Saturday, October 1 MS13 Mathematics and Conceptual Climate Modeling 9:30 AM - 11:30 AM Room: Concerto B - 3rd Floor

9:30-9:55 Conceptual Models: Understanding Past Climate Through Mathematics *Esther Widiasih*

10:00-10:25 Peatlands, Agriculture, and the Carbon Budget: A Conceptual Model for 15kyr Bp to the Present, *Alice Nadeau*

10:30-10:55 Palaeoclimate Dynamics Modelled with Delay Equations, Courtney Quinn

11:00-11:25 Improved Validation of Conceptual Climate Models Using Data Analysis Techniques, *Charles D. Camp*



