

Advances on Wright's Conjecture: Counting and discounting periodic orbits in Wright's equation

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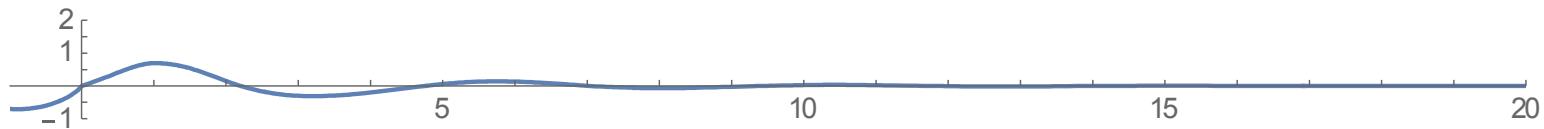
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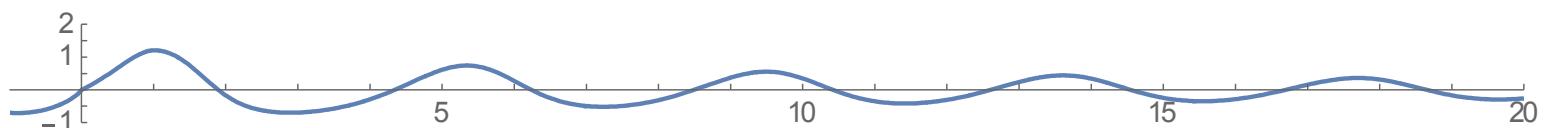
May 21st, 2017

Wright's Equation

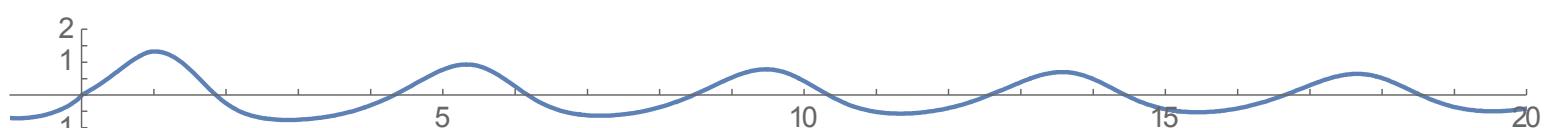
$$y' (t) = -\alpha y(t-1)[1+y(t)]$$



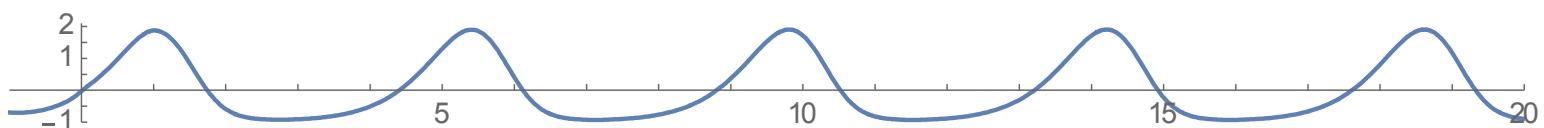
$\alpha=1.0$



$\alpha=1.5$



$\alpha=1.6$

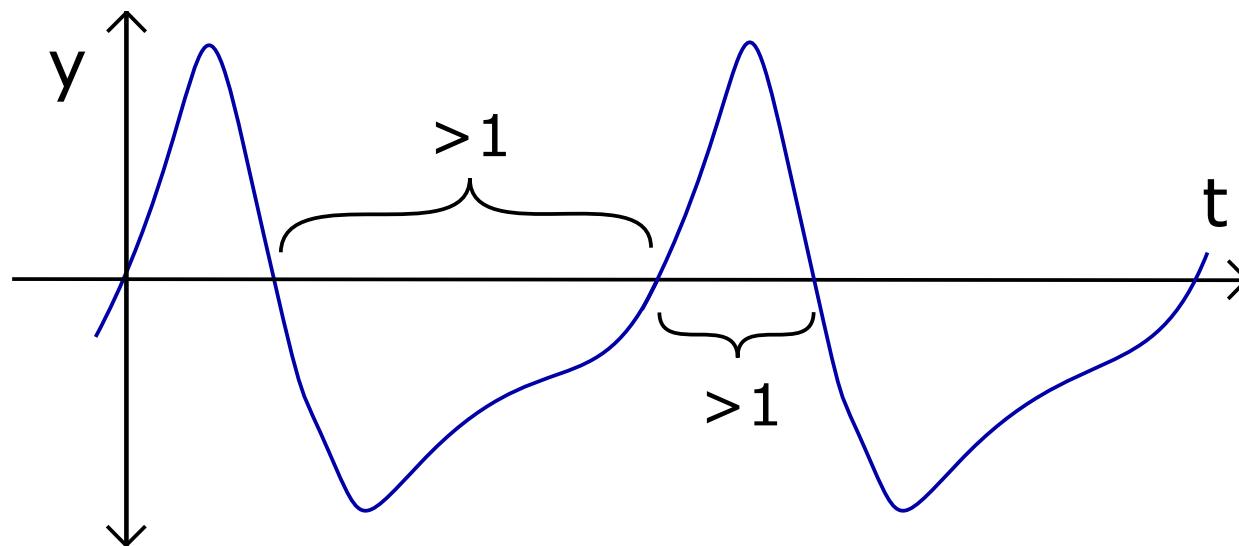


$\alpha=2.0$

Slowly Oscillating Periodic Solutions

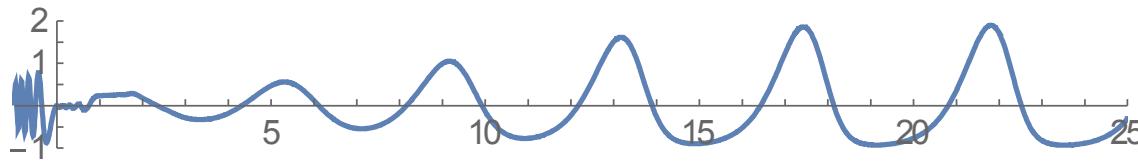
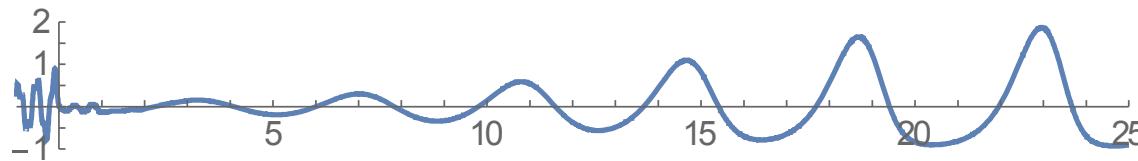
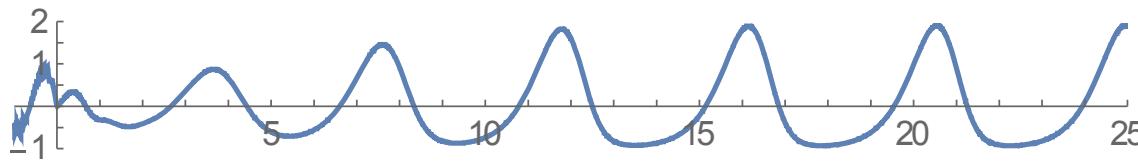
A function is a **Slowly Oscillating Periodic Solution** (SOPS) if it

- It is a solution to Wright's equation
- It is **positive** for at least one second, and then ...
- It is **negative** for at least one second, and then ...
- It repeats!



SOPs Exist

Theorem (Jones, 1962): For every $\alpha > \pi/2$ there exists at least one slowly oscillating periodic solution (SOPs) to Wright's equation



$$y' = -\alpha y(t-1)[1+y(t)]; \quad \alpha=2.0$$

Conjectures

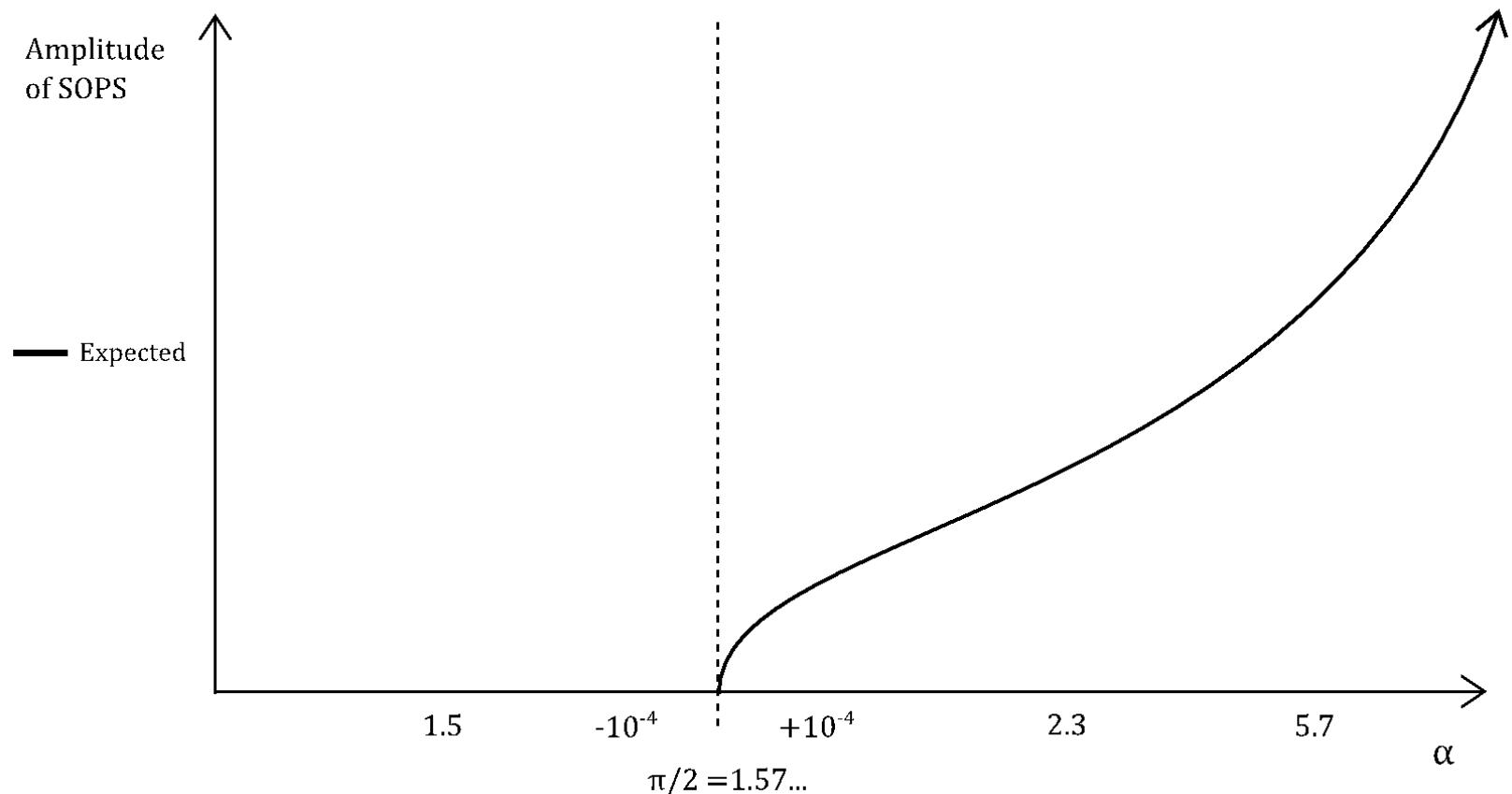
- **Wright's Conjecture:**

For $\alpha \in (0, \pi/2]$ zero is the global attractor

- **Jones' Conjecture:**

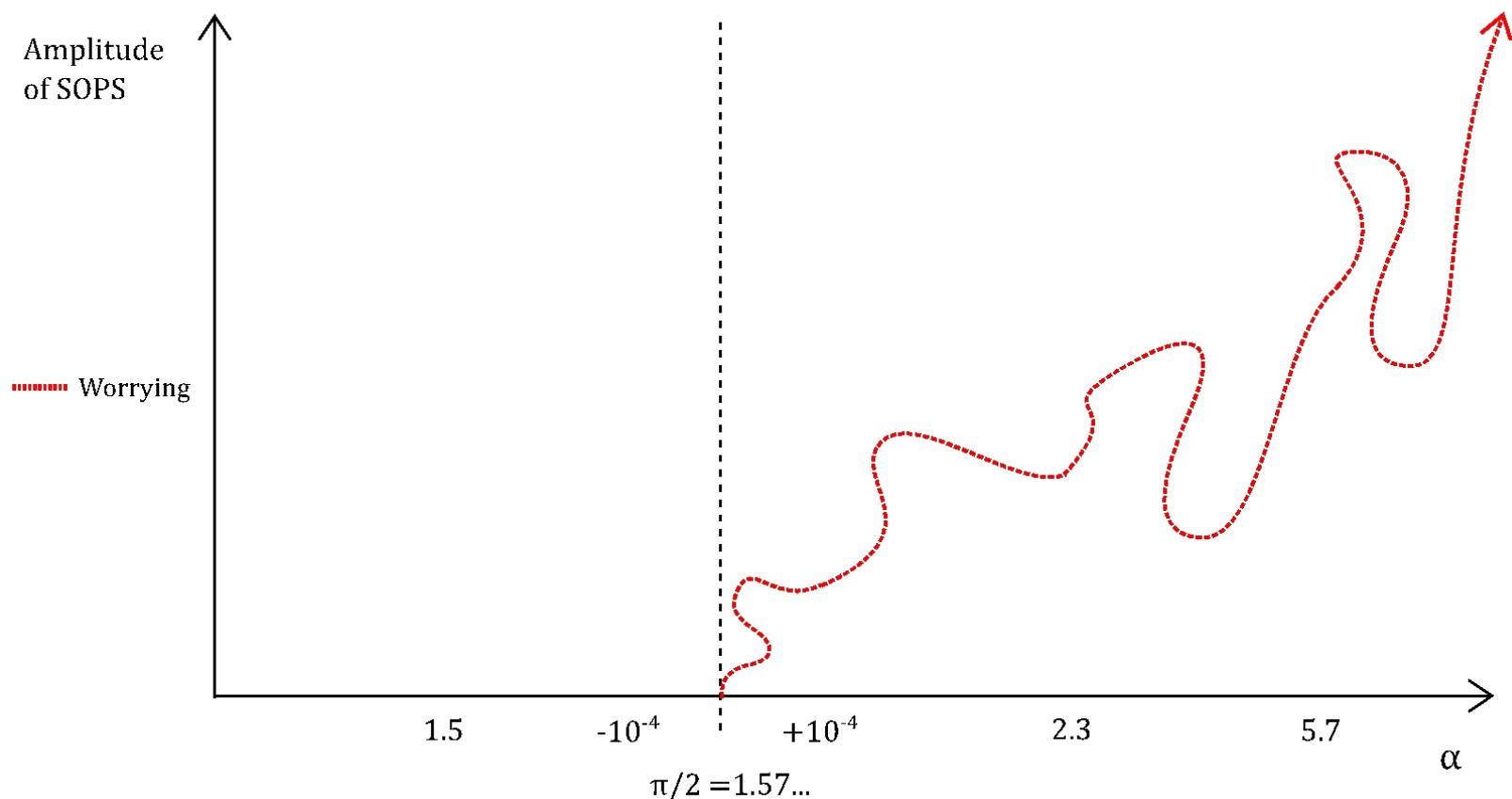
For $\alpha > \pi/2$ there is a unique slowly oscillating periodic orbit (SOPS)

The conjectured bifurcation diagram for Wright's equation



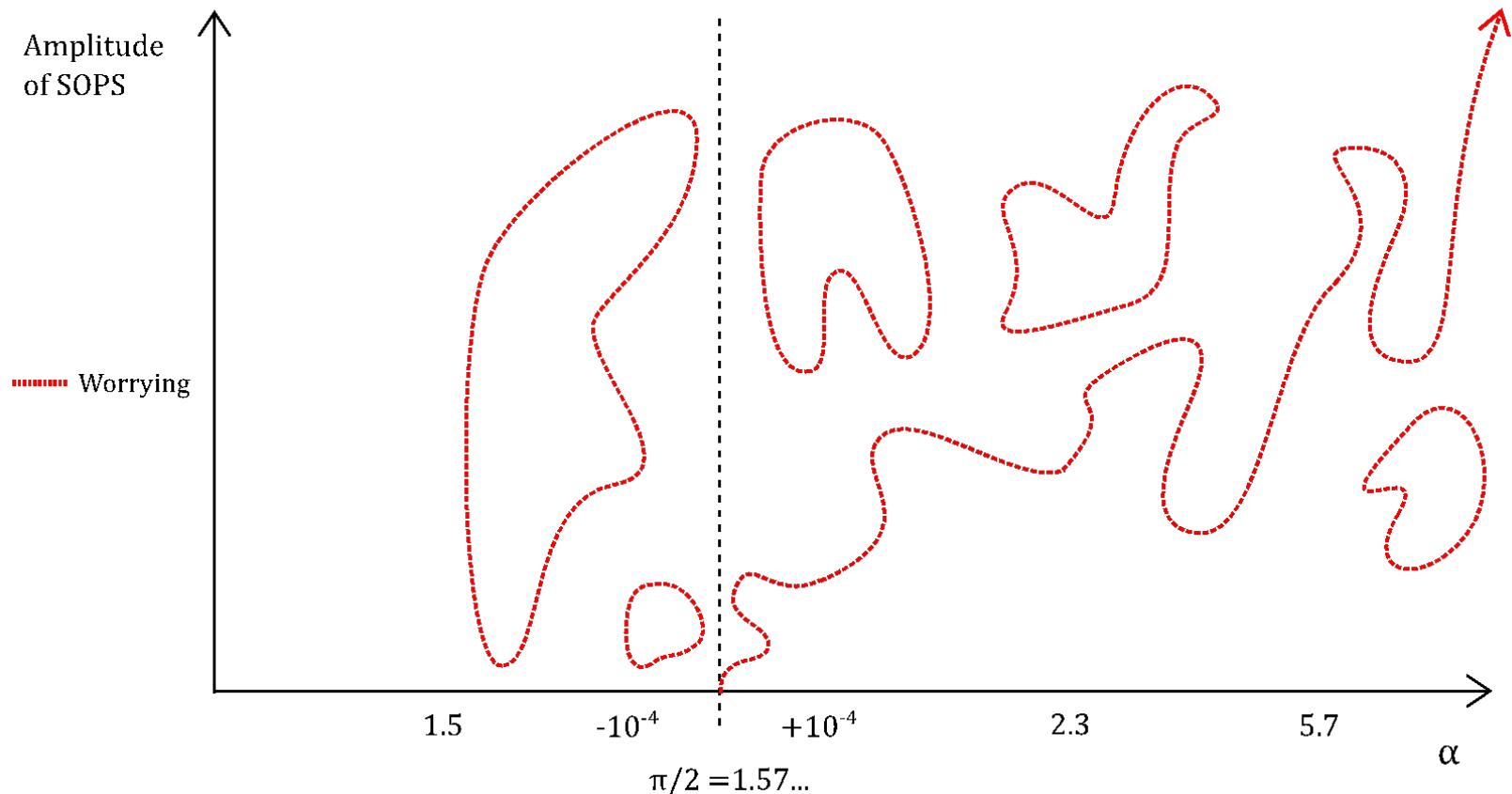
What could go wrong?

Fold bifurcations!

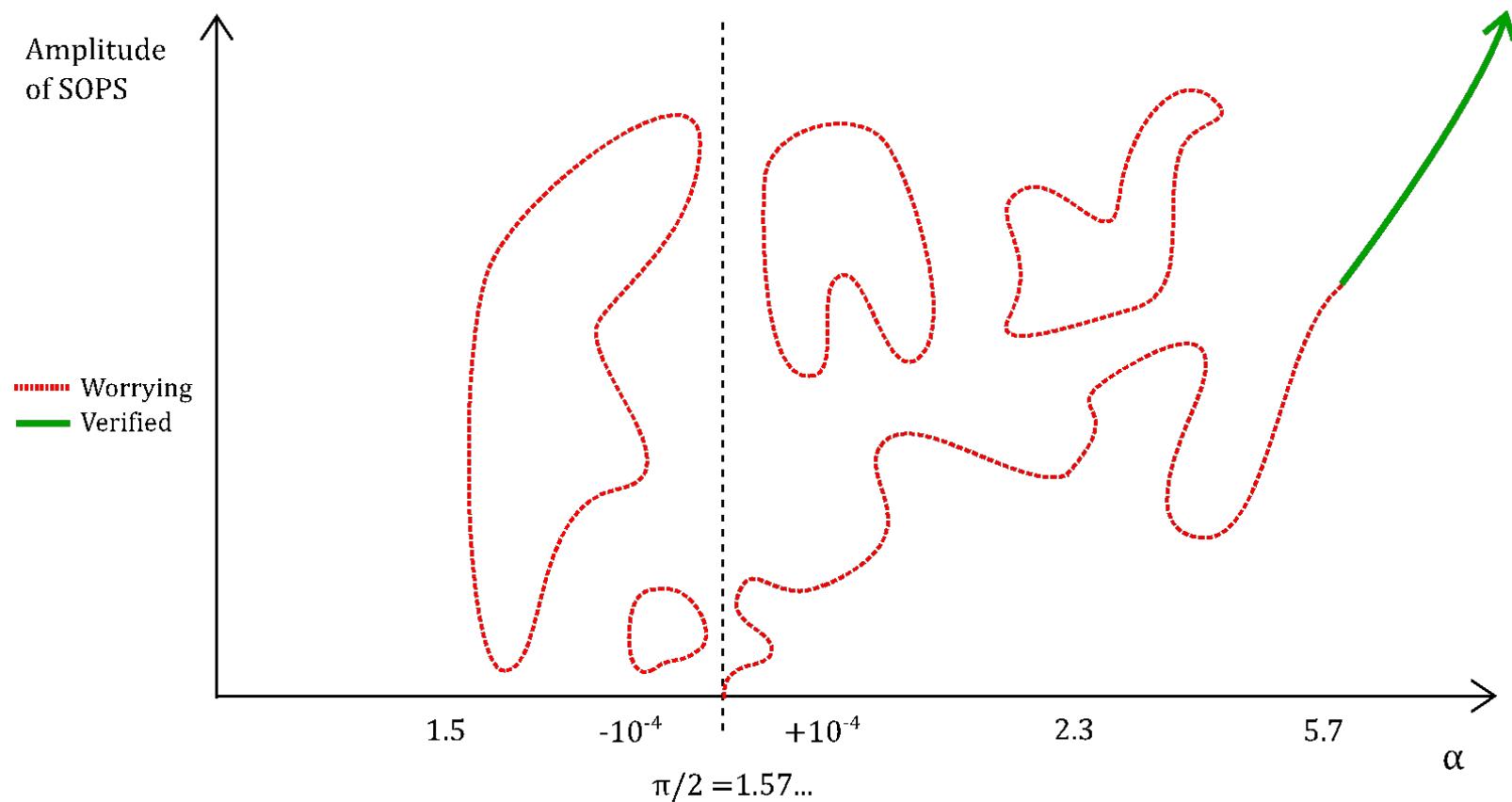


What could go wrong?

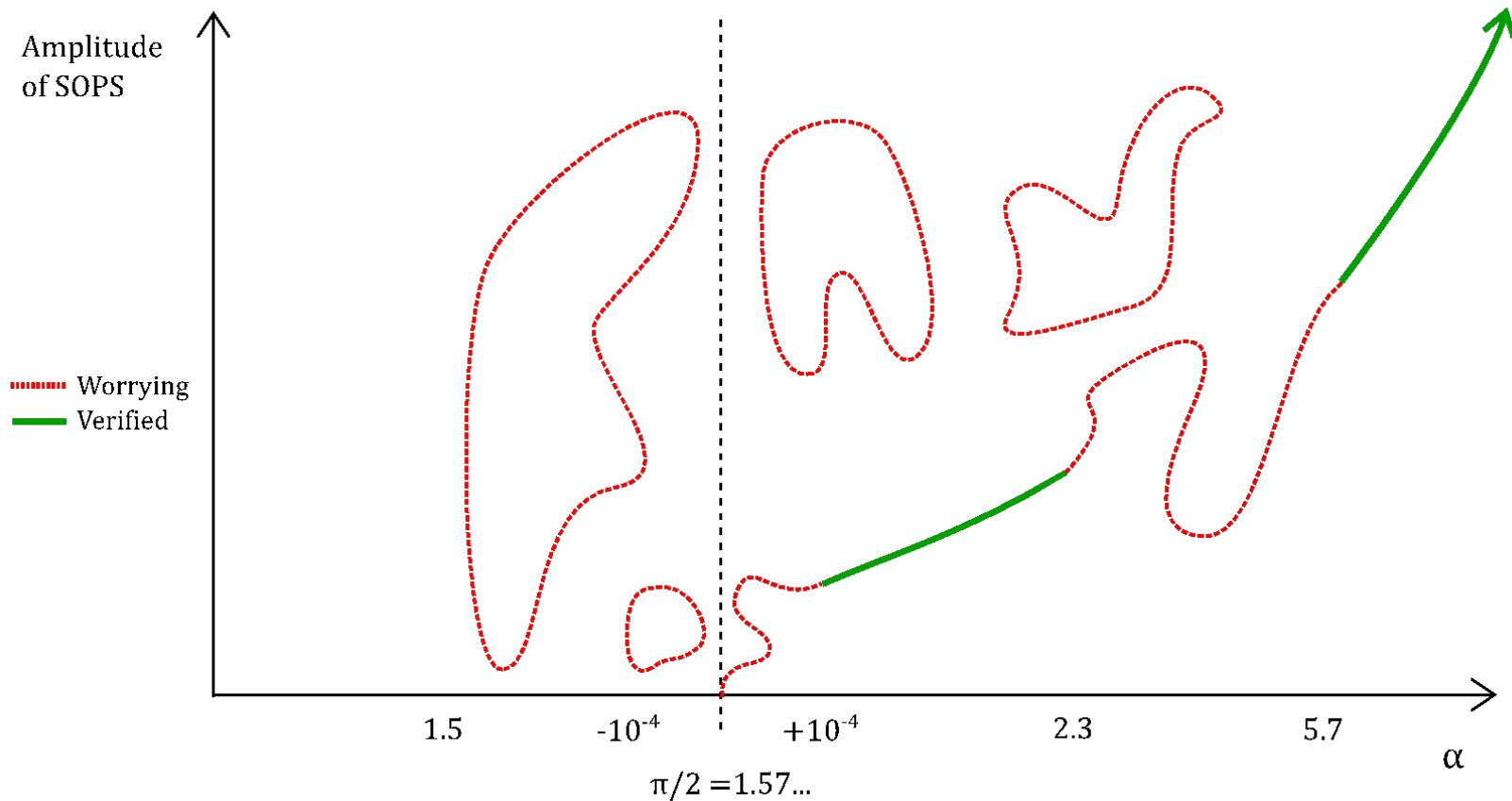
Isolas of SOPS!



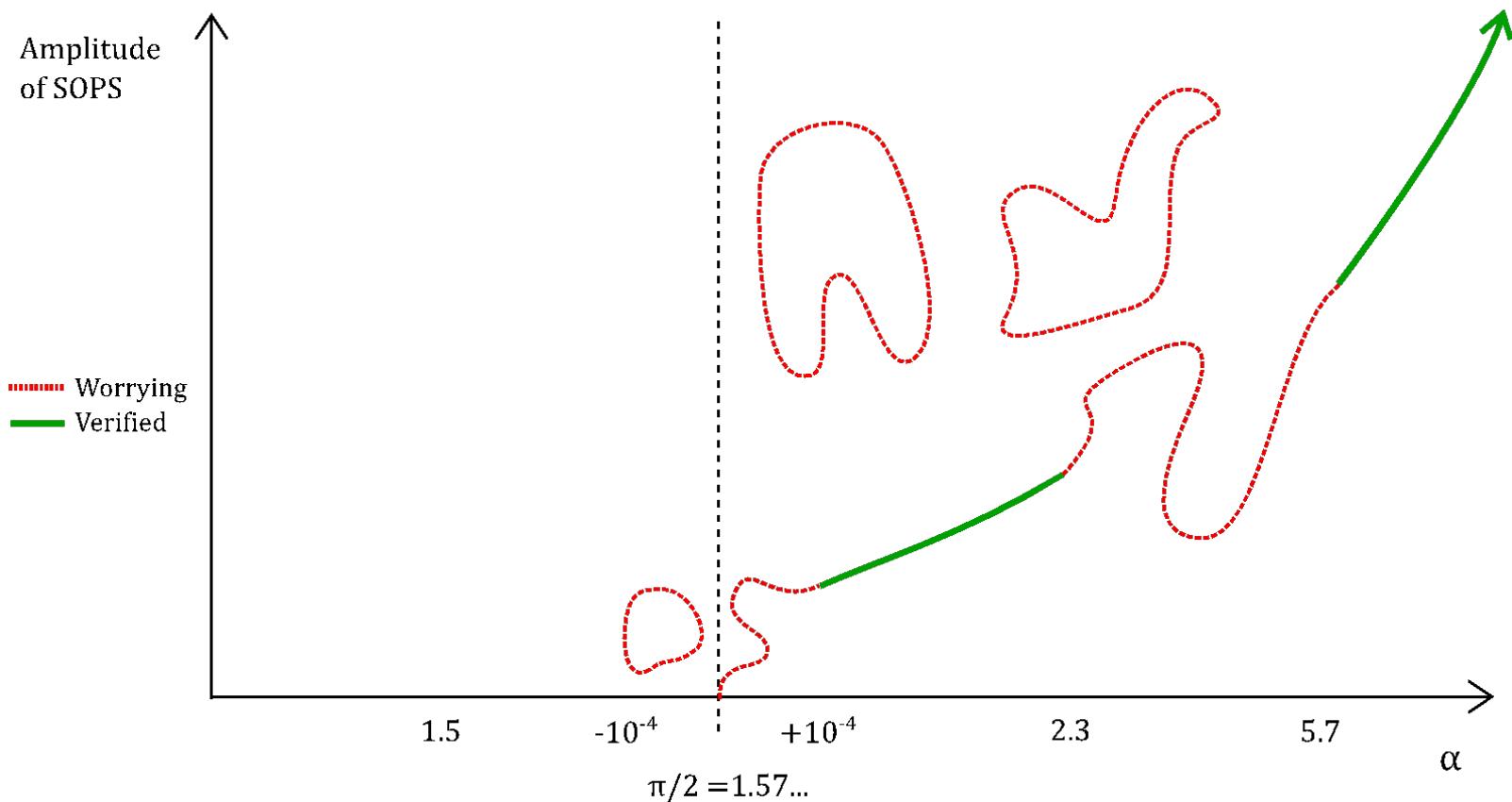
(1991) Xie



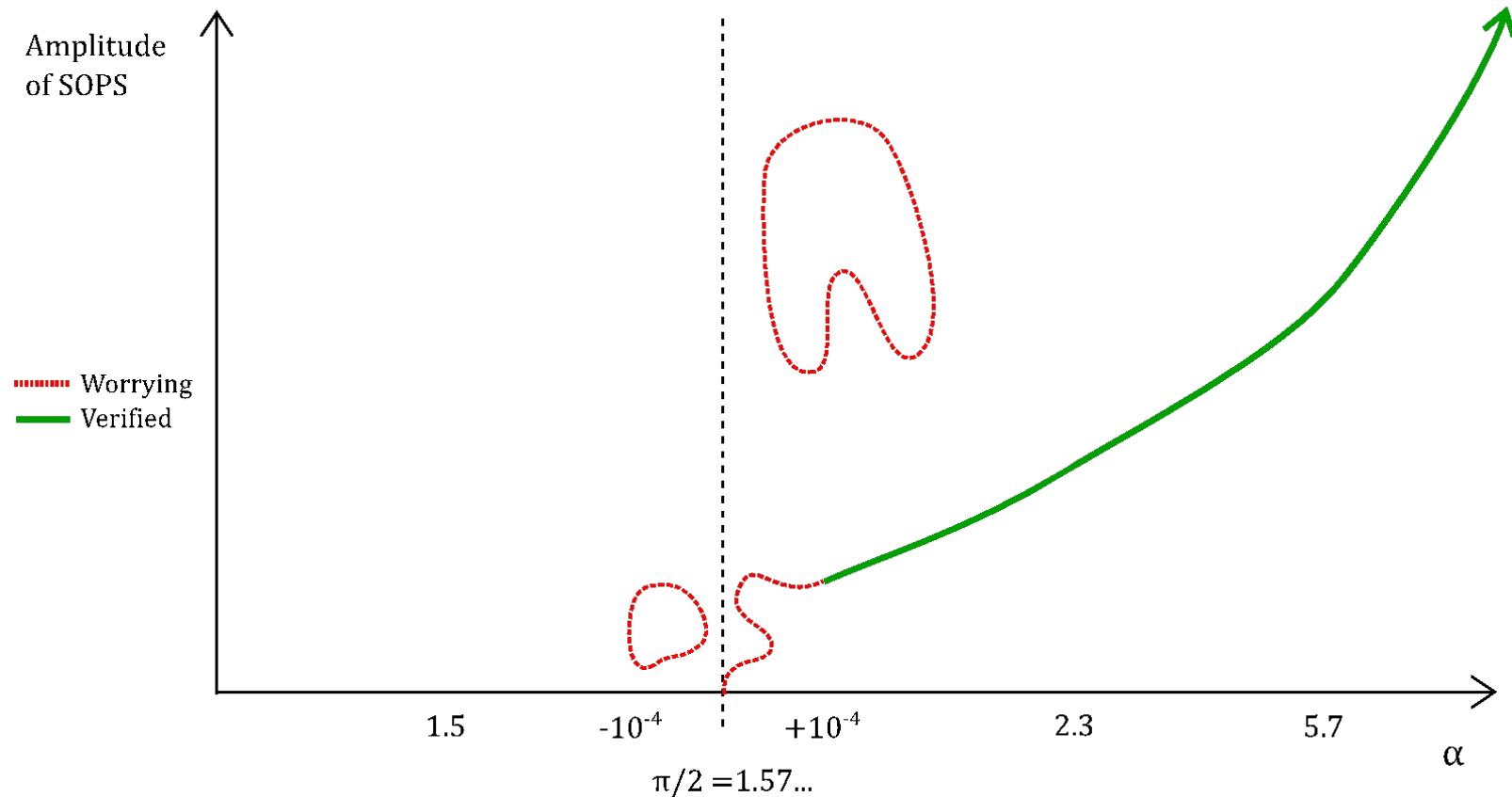
(2010) Lessard



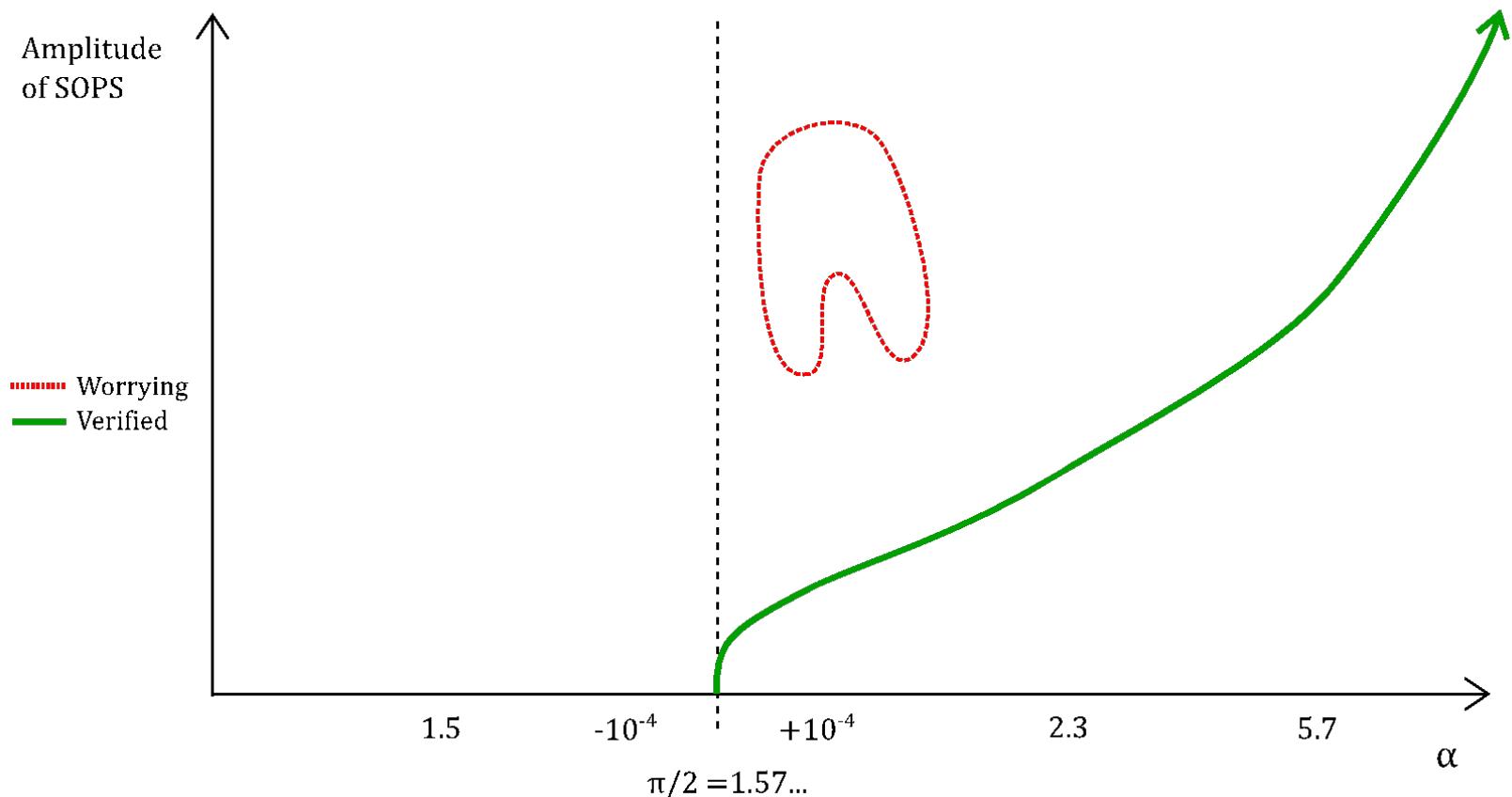
(2014) Banhelyi, Csendes, Krisztin, Neumaier



(2017)^{*} Jaquette, Lessard, Mischaikow



(2017)^{*} van den Berg, Jaquette



Our Results

- For $\alpha \in (0, \pi/2]$ zero is the global attractor
- For $\alpha \in [1.9, 6.0]$ there is a unique SOPS to Wright's equation
- There are no subsequent bifurcations in the branch of SOPS originating at $\alpha = \pi/2$

Proof of Wright's Conjecture

- **Wright's Conjecture:** For $\alpha \in (0, \pi/2]$ zero is the global attractor
 - Zero is the global attractor \Leftrightarrow no SOPS
 - It suffices to show that there are no SOPS for $\alpha \in [1.5706, \pi/2]$

Outline of the Rest of Talk

- Interpret Wright's Equation as a Functional Equation
 - $y(t)$ is periodic $\Leftrightarrow F(x)=0$
- Fixed Point Problem
 - $F(x)=0$ $\Leftrightarrow T:B \rightarrow B$ has a fixed point
- Radii Polynomials
 - Technique for proving Banach fixed point theorem
- Tie together local and global results

Fourier Series

- For frequency $\omega > 0$ we can write a periodic solution as

$$y(t) = \sum_{k \in \mathbb{Z}} a \downarrow k e^{\uparrow i \omega k t}$$
$$a \downarrow k \in \mathbb{C}$$

- Since $y(t) \in \mathbb{R}$ then $a \downarrow -k = a \downarrow k^*$
- Solutions to Wright's equation satisfy $a \downarrow 0 = 0$
- Define the space

$$\ell^1 := \{ \{a \downarrow k\}_{k \geq 1} : \sum_{k \geq 1} |a \downarrow k| < \infty \}$$

Wright's Equation in Fourier Space

- For frequency ω we can write a periodic solution as

$$y(t) = \sum_{k \in \mathbb{Z}} a \downarrow k e^{\uparrow i \omega k t}$$
$$a \downarrow k \in \mathbb{C}$$

- We can rewrite Wright's equation ...

$$y' \uparrow (t) = -\alpha y(t-1)[1+y(t)]$$

- ... in each mode using the function $G(\alpha, \omega, a)$

$$[G(\alpha, \omega, a)] \downarrow k := i \omega k a \downarrow k + \alpha e^{\uparrow} - i \omega k a \downarrow k + \alpha \sum_{l=1}^{k-1} a \downarrow l + a \downarrow k$$
$$= k \uparrow e^{\uparrow} - i \omega k \downarrow 1 a \downarrow k \downarrow 1 a \downarrow k \downarrow 2$$

Equivalence Theorem (1)

- Let $\alpha \in \ell \downarrow \mathbb{N}_1$, $\alpha > 0, \omega > 0$
- Define $y: \mathbb{R} \rightarrow \mathbb{R}$ as

$$y(t) = \sum_{k=1}^{\infty} a_k e^{i\omega k t} + a_k^* e^{-i\omega k t}$$

- Then $y(t)$ is a periodic solution to Wright's equation if and only if $G(\alpha, \omega, a) = 0$

Banach Algebra

- Define basis vectors $e \downarrow k \in \ell^{\uparrow 1}$ as

$$[e \downarrow k] \downarrow j = \begin{cases} 1 & \text{if } k=j \\ 0 & \text{if } k \neq j \end{cases}$$

- We define the norm on $\ell^{\uparrow 1}$ as follows

$$\|a\| = \|a\| \downarrow \ell^{\uparrow 1} := \sum_{k=1}^{\infty} |a \downarrow k|$$

- For $a, a \in \ell^{\uparrow 1}$ we define the discrete convolution

$$[a * a] \downarrow k = \sum_{k_1, k_2 \in \mathbb{Z}} k_1 + k_2 = k \uparrow a \downarrow k_1 \cdot a \downarrow k_2$$
$$a \downarrow -k = a \downarrow k^*$$

- Then we have $\{a * a\} \downarrow k \geq 1 \in \ell^{\uparrow 1}$ and

$$\|a * a\| \leq \|a\| \cdot \|a\|$$

Defining Some Operators

- We define a compact operator K
 - $[Ka] \downarrow k := a \downarrow k / k$
 - $Ka = \{a \downarrow 1 / 1, a \downarrow 2 / 2, a \downarrow 3 / 3, a \downarrow 4 / 4, a \downarrow 5 / 5, \dots\}$
- ... and a unitary operator $U \downarrow \omega$
 - $[U \downarrow \omega a] \downarrow k := e^{\uparrow} - ik\omega a \downarrow k$
 - $U \downarrow \omega a = \{e^{\uparrow} - i\omega a \downarrow 1, e^{\uparrow} - 2i\omega a \downarrow 2, \dots\}$
- ... so that we can write our function

$$[G(\alpha, \omega, a)] \downarrow k = i\omega k a \downarrow k + \alpha e^{\uparrow} - i\omega k a \downarrow k + \alpha \sum_{k \downarrow 1}^{k \downarrow 2} e^{\uparrow} - i\omega k \downarrow 1 a \downarrow k \downarrow 1 a \downarrow k \downarrow 2$$

- all in one condensed equation

$$G(\alpha, \omega, a) = (i\omega K \uparrow - 1 + \alpha U \downarrow \omega) a + \alpha (U \downarrow \omega a)^* a$$

Hopf Bifurcation

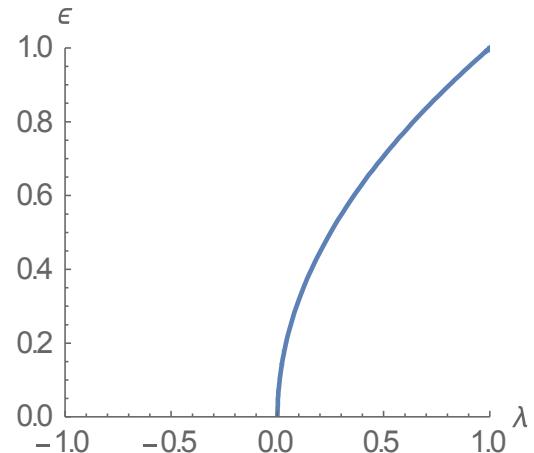
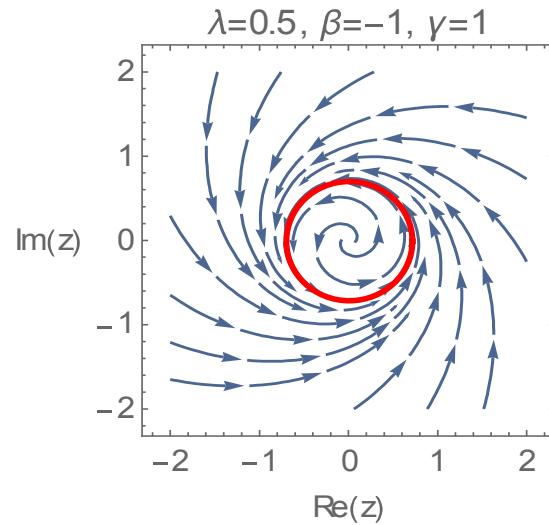
- The Hopf normal form is
 $\dot{z} = z(\lambda + i) + z|z|^2 / (\beta + i\gamma)$
- If $\beta < 0$ then the bifurcation is **supercritical**
- There is a stable limit cycle for $\lambda > 0$ given by...

$$z(t) = \epsilon e^{i\omega t}$$

where

$$\epsilon = \sqrt{-\lambda/\beta}$$

$$\omega = 1 + \gamma \epsilon^2$$



Phase Condition

- If $y(t)$ is a periodic solution, then so is $y(t+\tau)$

- Write $a \downarrow 1 = \epsilon e^{\uparrow i\theta}$ with $\epsilon \geq 0$
and choose $\tau := -\theta/\omega$,

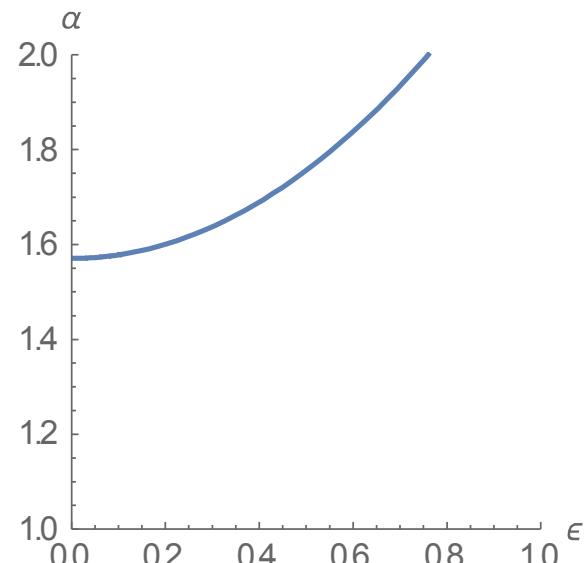
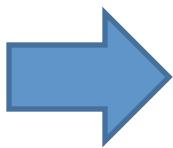
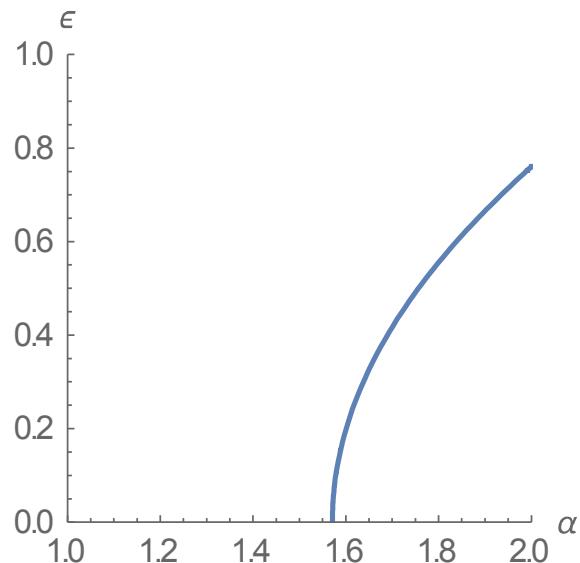
$$a \downarrow 1 e^{\uparrow i\omega(t+\tau)} = \epsilon e^{\uparrow i\omega t}$$

- Without loss of generality, write $a \in \ell \uparrow 1$ as

$$a = \epsilon e \downarrow 1 + c, \quad \text{with } c \in \ell \downarrow 0 \uparrow 1$$

$$\ell \downarrow 0 \uparrow 1 := \{c \in \ell \uparrow 1 : c \downarrow 1 = 0\}$$

Turning ϵ into a Parameter



Turning ϵ into a Parameter

- Rewrite the function $G(\alpha, \omega, a)$

$$G(\alpha, \omega, a) := (i\omega K^\uparrow - 1 + \alpha U \downarrow \omega) a + \alpha (U \downarrow \omega a) * a$$

using the change of variables, $a = \epsilon e \downarrow 1 + c$

$$G(\alpha, \omega, \epsilon e \downarrow 1 + c) = F \downarrow \epsilon (\alpha, \omega, c)$$

- $F \downarrow \epsilon (\alpha, \omega, c) :=$

$$(i\omega + \alpha e^\uparrow - i\omega) \epsilon e \downarrow 1 + (i\omega K^\uparrow - 1 + \alpha U \downarrow \omega) c \\ + \epsilon^{\uparrow 2} \alpha e^\uparrow - i\omega e \downarrow 2 + \alpha \epsilon L \downarrow \omega c + \alpha (U \downarrow \omega c) * c$$

where we define

- $L \downarrow \omega := \sigma^\uparrow + (e^\uparrow - i\omega I + U \downarrow \omega) + \sigma^\uparrow - (e^\uparrow i\omega I + U \downarrow \omega)$
- $\sigma^\uparrow +$ is the right shift operator
- $\sigma^\uparrow -$ is the left shift operator

Equivalence Theorem (2)

- Let $\epsilon \geq 0, c \in \ell \downarrow 0 \uparrow 1, \alpha > 0, \omega > 0$

- Define $y: \mathbb{R} \rightarrow \mathbb{R}$ as

$$y(t) = \epsilon(e^{\uparrow i\omega t} + e^{\uparrow -i\omega t}) + \sum_{k=2}^{\infty} c \downarrow k e^{\uparrow i\omega kt} + c \downarrow k \uparrow * e^{\uparrow -i\omega kt}$$

- Then $y(t)$ is a periodic solution to Wright's equation if and only if $F \downarrow \epsilon (\alpha, \omega, c) = 0$

Epsilon Rescaling

- We want to use a Newton-like method to solve $F \downarrow \epsilon(\alpha, \omega, c) = 0$ for small values of ϵ
- At the bifurcation point $DF \downarrow 0 (\pi/2, \pi/2, 0)$ is not invertible
- Make the change of variables $c = \epsilon c$ and define

$$F \downarrow \epsilon(\alpha, \omega, \epsilon c) = \epsilon F \downarrow \epsilon(\alpha, \omega, c)$$

$$\begin{aligned} F \downarrow \epsilon(\alpha, \omega, c) := & (i\omega + \alpha e^{\uparrow} - i\omega) e \downarrow 1 + (i\omega K^{\uparrow} - 1 + \alpha \\ & U \downarrow \omega) c + \epsilon \alpha (e^{\uparrow} - i\omega e \downarrow 2 + L \downarrow \omega c + (U \downarrow \omega c)^* c) \end{aligned}$$

Equivalence Theorem (3)

- Let $\epsilon > 0$, $c \in \ell \downarrow 0 \nearrow 1$, $\alpha > 0, \omega > 0$

- Define $y: \mathbb{R} \rightarrow \mathbb{R}$ as

$$y(t) = \epsilon(e^{\uparrow i\omega t} + e^{\uparrow -i\omega t}) + \epsilon \sum_{k=2}^{\uparrow \infty} c \downarrow k e^{\uparrow i\omega kt} + c \downarrow k \uparrow * e^{\uparrow -i\omega kt}$$

- Then $y(t)$ is a periodic solution to Wright's equation if and only if $F \downarrow \epsilon(\alpha, \omega, c) = 0$

Newton's Method

- Newton's Method produces a sequence by

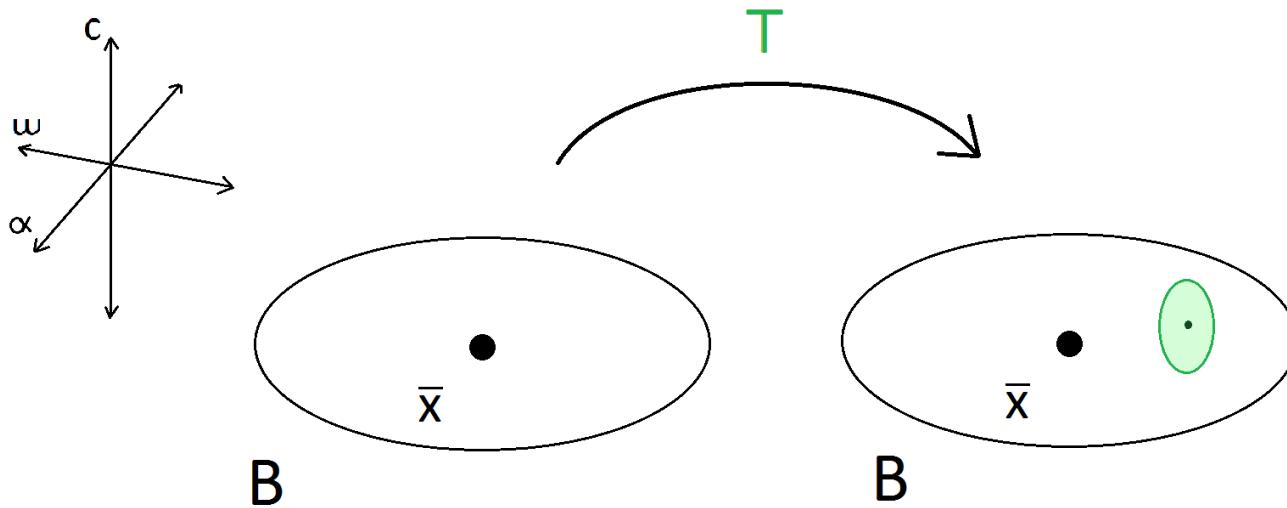
$$x \downarrow n+1 := x \downarrow n - f(x \downarrow n) / f' \uparrow (x \downarrow n)$$

- The same principle works in infinite dimensions

- Need approximate solution
 - Need approximate inverse-derivative

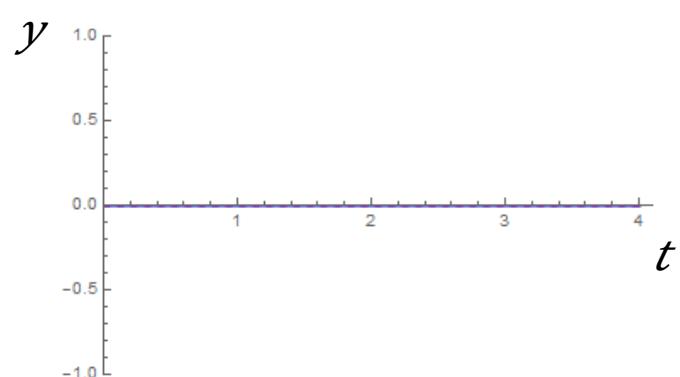
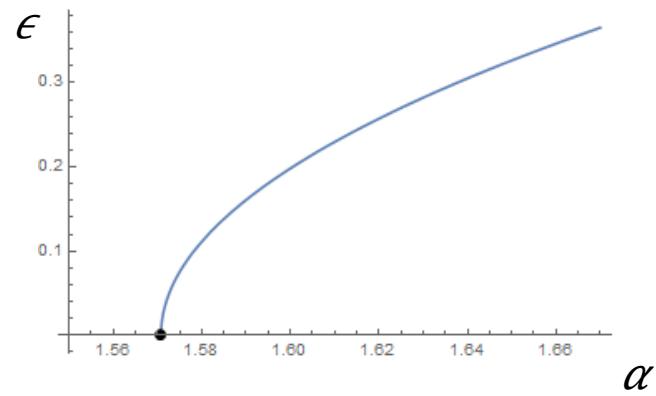
Newton-Like Operator

- Apply contraction mapping principle to a Newton-like operator $T(x) := x - A^\dagger F(x)$
- While A^\dagger, F, T all depend on $\epsilon \geq 0$, we suppress this in the notation



Approximate Solution

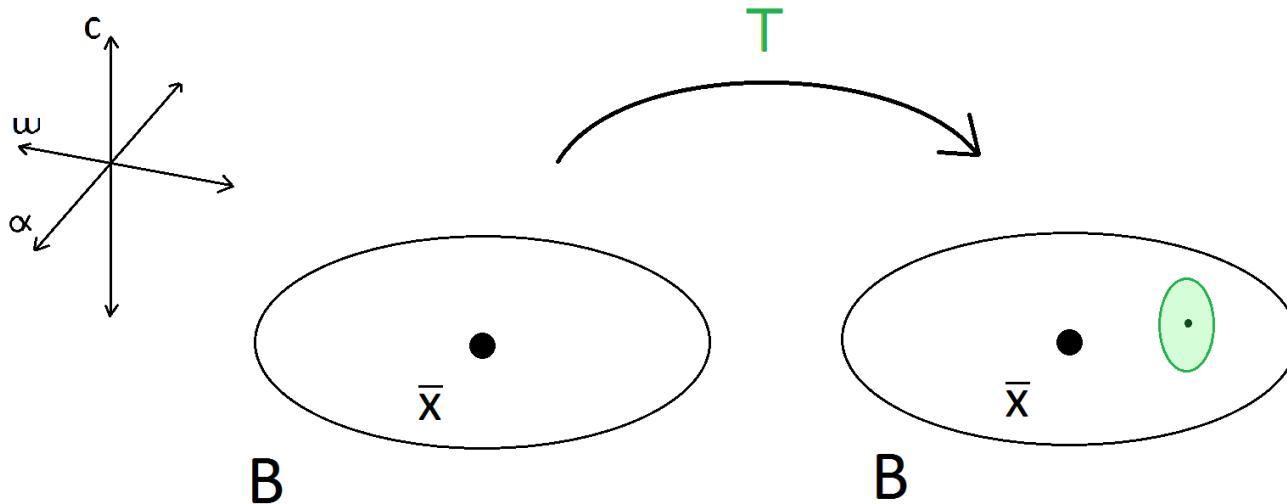
- Using normal forms theory, we define the approximate solution $x \downarrow \epsilon : \mathbb{R} \downarrow + \rightarrow \mathbb{R}^{12} \times \ell \downarrow 0 \uparrow 1$
- $x \downarrow \epsilon = \{\alpha \downarrow \epsilon, \omega \downarrow \epsilon, c \downarrow \epsilon\}$
 - $\alpha \downarrow \epsilon := \pi/2 + \epsilon^{12}/5 (3\pi/2 - 1)$
 - $\omega \downarrow \epsilon := \pi/2 - \epsilon^{12}/5$
 - $c \downarrow \epsilon := (2 - i/5) \epsilon e \downarrow 2$



Approximate Derivative

- Next we define $A\uparrow\dagger$ for our Newton-like operator

$$T(x) := x - A\uparrow\dagger F(x)$$



Approximate Derivative

- Define the map $A\uparrow\dagger = DF(x\downarrow\epsilon)\uparrow-1 + O(\epsilon^{12})$ by
$$A\uparrow\dagger := A\downarrow 0\uparrow-1 - \epsilon A\downarrow 0\uparrow-1 A\downarrow 1 A\downarrow 0\uparrow-1$$
- Define the maps
 - $i\downarrow\mathbb{C}(s,t) := s + i t$
 - $A\downarrow 0 x = A\downarrow 0(\alpha, \omega, c) := i\downarrow\mathbb{C} A\downarrow 0, 1 [\alpha @ \omega] e\downarrow 1 + A\downarrow 0, * c$
 - $A\downarrow 1 x = A\downarrow 1(\alpha, \omega, c) := i\downarrow\mathbb{C} A\downarrow 1, 2 [\alpha @ \omega] e\downarrow 2 + A\downarrow 1, * c$
- Define $\omega\downarrow 0 = \pi/2$, and the maps...
$$A\downarrow 0, 1 := [\begin{matrix} 0 & -\pi/2 \\ -2 & 2 - 3\pi/2 \end{matrix} @ \begin{matrix} -1 & 1 \\ -4 & 2(2 + \pi) \end{matrix}] \qquad A\downarrow 1, 2 := 1/5$$

$$A\downarrow 0, * := \pi/2 (iK\uparrow-1 + U\downarrow\omega\downarrow 0) \qquad A\downarrow 1, * := \pi/2 L\downarrow\omega\downarrow 0$$

Equivalence Theorem (4)

- Define the Newton-like operator

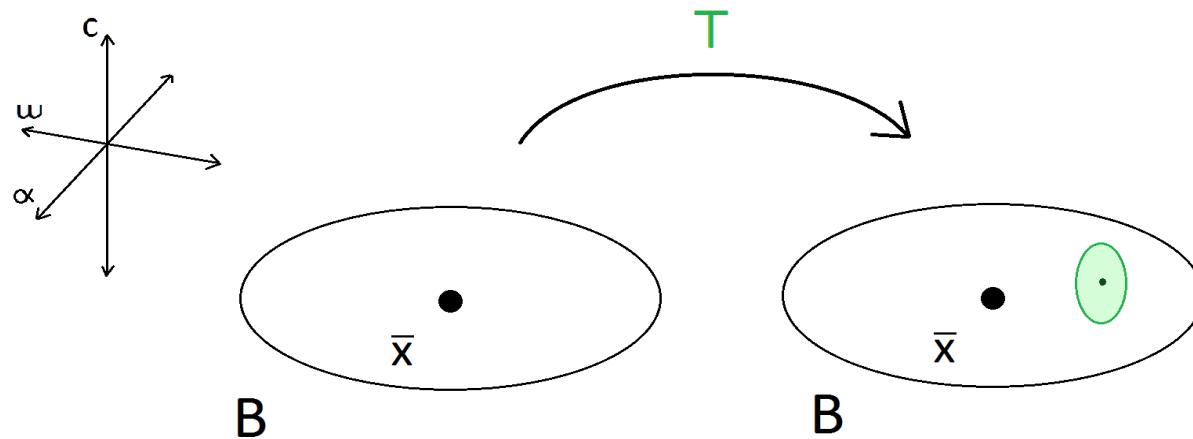
$$T(x) := x - A^{\uparrow\dagger} F(x)$$

- For $0 \leq \epsilon < 0.79$ the operator $A^{\uparrow\dagger}$ is injective and the following are equivalent:
 - Fixed points of $T(x)$
 - Zeros of $F(x)$
 - SOPS to Wright's equation

Newton-Like Operator

- To have a contraction mapping, we need

$$T(B) \subseteq B$$



A Ball about our Approximation

- Let $\epsilon \geq 0$, $r = \{r \downarrow \alpha, r \downarrow \omega, r \downarrow c\} \in \mathbb{R}^3$, $\rho > 0$
- Define $B \downarrow \epsilon(r, \rho)$ to be the collection of points $\{\alpha, \omega, c\} \in \mathbb{R}^3 \times \ell \downarrow [0, 1]$ satisfying ...
 - $|\alpha - \alpha \downarrow \epsilon| \leq r \downarrow \alpha$
 - $|\omega - \omega \downarrow \epsilon| \leq r \downarrow \omega$
 - $||c - c \downarrow \epsilon|| \leq r \downarrow c$
 - $||K \uparrow - 1 c|| \leq \rho$
 - ρ makes the ball compact!

$\{\alpha \downarrow \epsilon, \omega \downarrow \epsilon, c \downarrow \epsilon\}$ is the approximate solution

Radii Polynomials

- For $T(x \downarrow \epsilon) - x \downarrow \epsilon \in \mathbb{R}^{n_1 \times n_1 \times \ell \downarrow 0 \uparrow 1}$ we define $Y(\epsilon) \in \mathbb{R}^{13}$ which provides a component-wise bound
- For $DT(x) \in \mathcal{L}(\mathbb{R}^{n_1 \times n_1 \times \ell \downarrow 0 \uparrow 1}, \mathbb{R}^{n_1 \times n_1 \times \ell \downarrow 0 \uparrow 1})$ we define $Z(\epsilon, r, \rho) \in \text{Mat}(\mathbb{R}^{13}, \mathbb{R}^{13})$ which provides a component-wise bound for all $x \in B \downarrow \epsilon(r, \rho)$
- Define the radii polynomials:

$$P(\epsilon, r, \rho) := Y(\epsilon) - [I - Z(\epsilon, r, \rho)] \cdot r$$

Radii Polynomials: Uniform in ϵ

- $P(\epsilon, r, \rho)$ is increasing in ϵ
- If $0 \leq \epsilon \leq \epsilon \downarrow 0$ then

$$P(\epsilon \downarrow 0, r, \rho) < 0 \Rightarrow P(\epsilon, r, \rho) < 0$$

- If each component of $P(\epsilon \downarrow 0, r, \rho)$ is negative, then **for all** $0 \leq \epsilon \leq \epsilon \downarrow 0$ there is a unique $x \downarrow \epsilon \in B \downarrow \epsilon(r, \rho)$ such that $T(x \downarrow \epsilon) = x \downarrow \epsilon$

Radius Polynomials: Uniform in ϵ

- For $T(x \downarrow \epsilon) - x \downarrow \epsilon \in \mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1}$ we define $Y(\epsilon) \in \mathbb{R}^{13}$ which provides a component-wise bound
- For $DT(x) \in \mathcal{L}(\mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1}, \mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1})$ we define $Z(\epsilon, r, \rho) \in \text{Mat}(\mathbb{R}^{13}, \mathbb{R}^{13})$ which provides a component-wise bound for all $x \in B \downarrow \epsilon(r, \rho)$
- Define the radius polynomials:

$$P(\epsilon, r, \rho) := Y(\epsilon) - [I - Z(\epsilon, r, \rho)] \cdot r$$

Radius Polynomials: Uniform in $\epsilon^{\uparrow 2}$

- $P(\epsilon, \epsilon^{\uparrow 2} r, \rho)$ is increasing in ϵ
- If $0 \leq \epsilon \leq \epsilon \downarrow 0$ then

$$P(\epsilon \downarrow 0, \epsilon \downarrow 0^{\uparrow 2} r, \rho) < 0 \Rightarrow P(\epsilon, \epsilon^{\uparrow 2} r, \rho) < 0$$

- If each component of $P(\epsilon \downarrow 0, \epsilon \downarrow 0^{\uparrow 2} r, \rho)$ is negative,
then for all $0 \leq \epsilon \leq \epsilon \downarrow 0$ there is a unique $x \downarrow \epsilon \in B \downarrow \epsilon (\epsilon^{\uparrow 2} r, \rho)$ such that $T(x \downarrow \epsilon) = x \downarrow \epsilon$

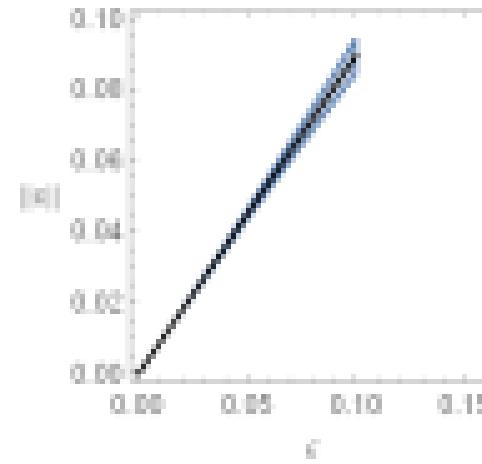
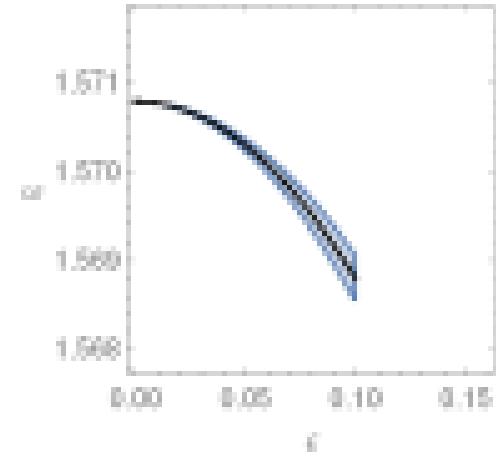
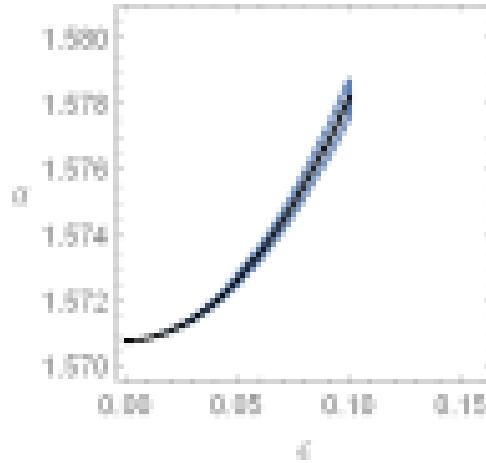
Radius Polynomials: Uniform in $\epsilon^{\uparrow 2}$

- For $T(x \downarrow \epsilon) - x \downarrow \epsilon \in \mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1}$ we define $Y(\epsilon) \in \mathbb{R}^{13}$ which provides a component-wise bound
- For $DT(x) \in \mathcal{L}(\mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1}, \mathbb{R}^{M_1 \times M_1 \times L \downarrow 0 \uparrow 1})$ we define $Z(\epsilon, r, \rho) \in \text{Mat}(\mathbb{R}^{13}, \mathbb{R}^{13})$ which provides a component-wise bound for all $x \in B \downarrow \epsilon(r, \rho)$
- Define the radius polynomials:

$$P(\epsilon, r, \rho) := Y(\epsilon) - [I - Z(\epsilon, r, \rho)] \cdot r$$

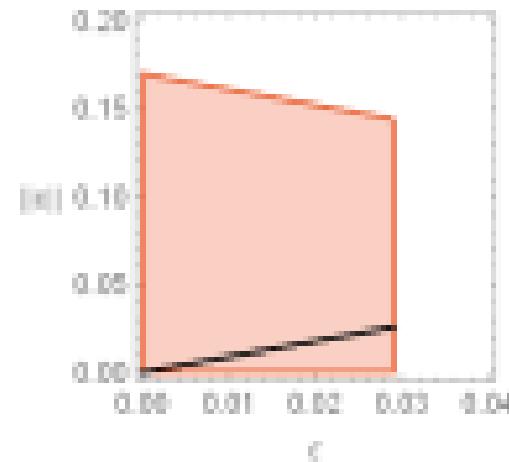
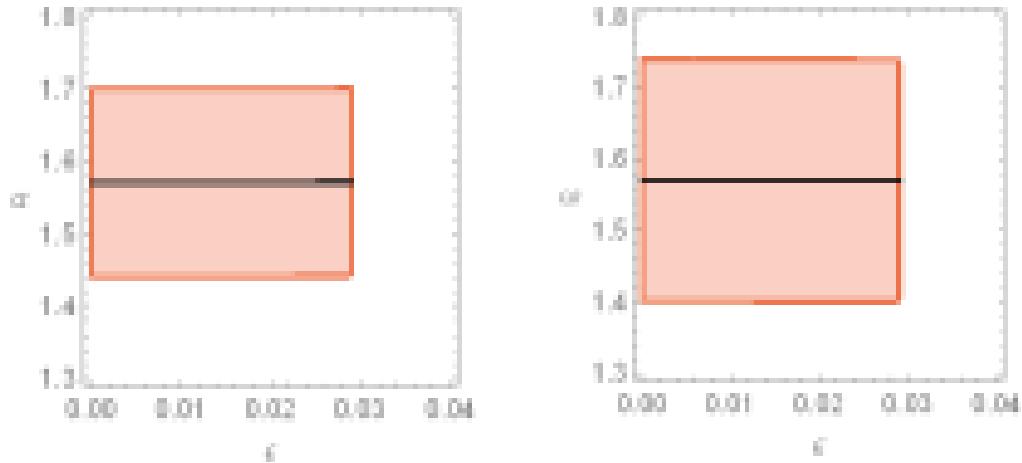
Applications (1)

- Fix the constants:
 - $\epsilon \downarrow 0 = 0.10$
 - $r \downarrow \alpha = 0.0594$
 - $r \downarrow \omega = 0.0260$
 - $r \downarrow c = 0.4929$
 - $\rho = 0.3191$
- The black line is $x \downarrow \epsilon$
The **blue region** is $B \downarrow \epsilon(\epsilon \uparrow 2, r, \rho)$
- For all $0 \leq \epsilon \leq \epsilon \downarrow 0$
there is a unique
 $x \downarrow \epsilon \in B \downarrow \epsilon(\epsilon \uparrow 2, r, \rho)$
such that $T(x \downarrow \epsilon) = x \downarrow \epsilon$
- For $\epsilon > 0$ these solutions $F(\alpha \downarrow \epsilon, \omega \downarrow \epsilon, c \downarrow \epsilon) = 0$
satisfy $\alpha \downarrow \epsilon > \pi/2$



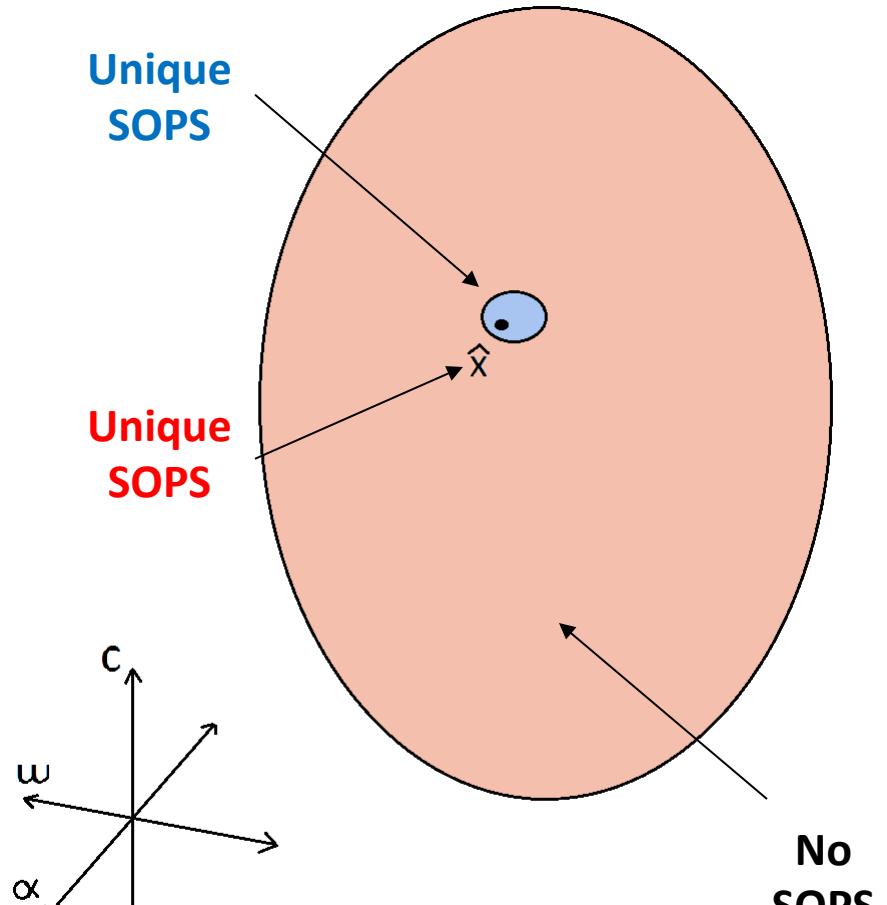
Applications (2)

- Fix the constants:
 - $\epsilon \downarrow 0 = 0.029$
 - $r \downarrow \alpha = 0.13$
 - $r \downarrow \omega = 0.17$
 - $r \downarrow c = 0.17$
 - $\rho = 1.78$
- The black line is $x \downarrow \epsilon$
The **red region** is $B \downarrow \epsilon(r, \rho)$
- For all $0 \leq \epsilon \leq \epsilon \downarrow 0$
there is a unique
 $x \downarrow \epsilon \in B \downarrow \epsilon(r, \rho)$
such that $T(x \downarrow \epsilon) = x \downarrow \epsilon$

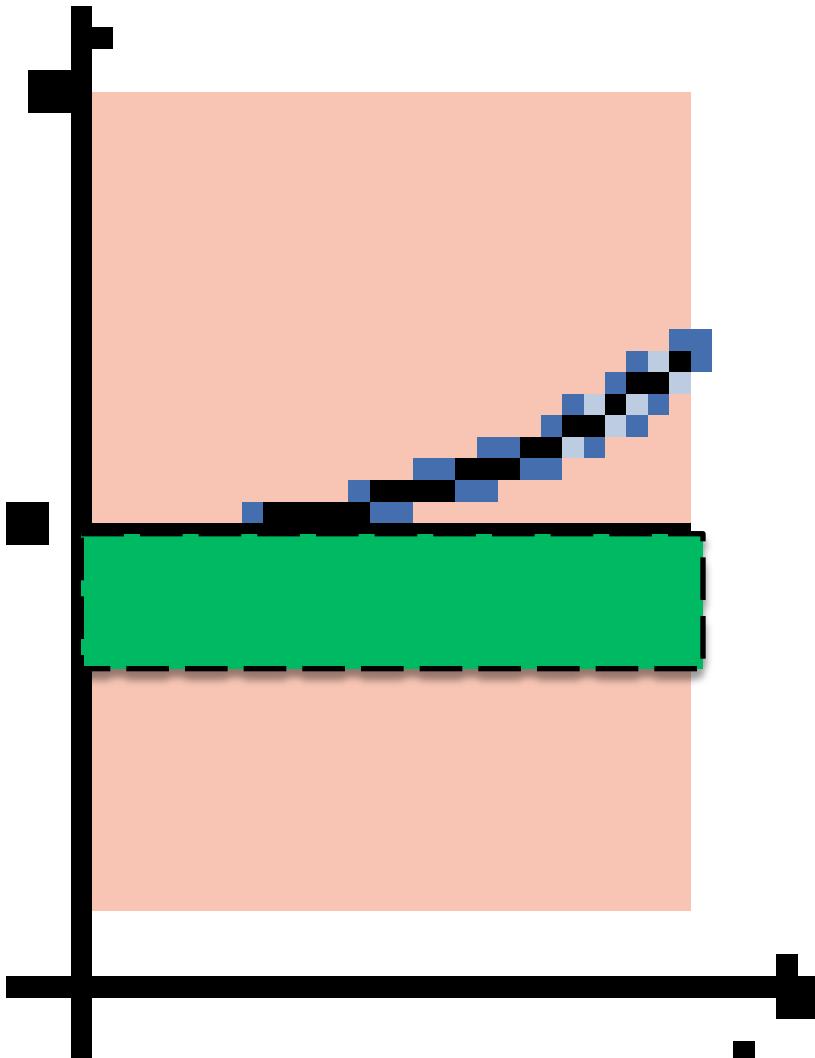


Large and Small Radii

- Fix $0 < \epsilon \leq 0.029$
- There is a unique SOPS
 $x \downarrow 1 \in B \downarrow \epsilon(r \downarrow 1, \rho \downarrow 1)$
- There is a unique SOPS
 $x \downarrow 2 \in B \downarrow \epsilon(r \downarrow 2, \rho \downarrow 2)$
- $B \downarrow \epsilon(r \downarrow 1, \rho \downarrow 1) \subset B \downarrow \epsilon(r \downarrow 2, \rho \downarrow 2)$
 - $x \downarrow 1 = x \downarrow 2$
 - No SOPS in
 $B \downarrow \epsilon(r \downarrow 2, \rho \downarrow 2) \setminus B \downarrow \epsilon(r \downarrow 1, \rho \downarrow 1)$

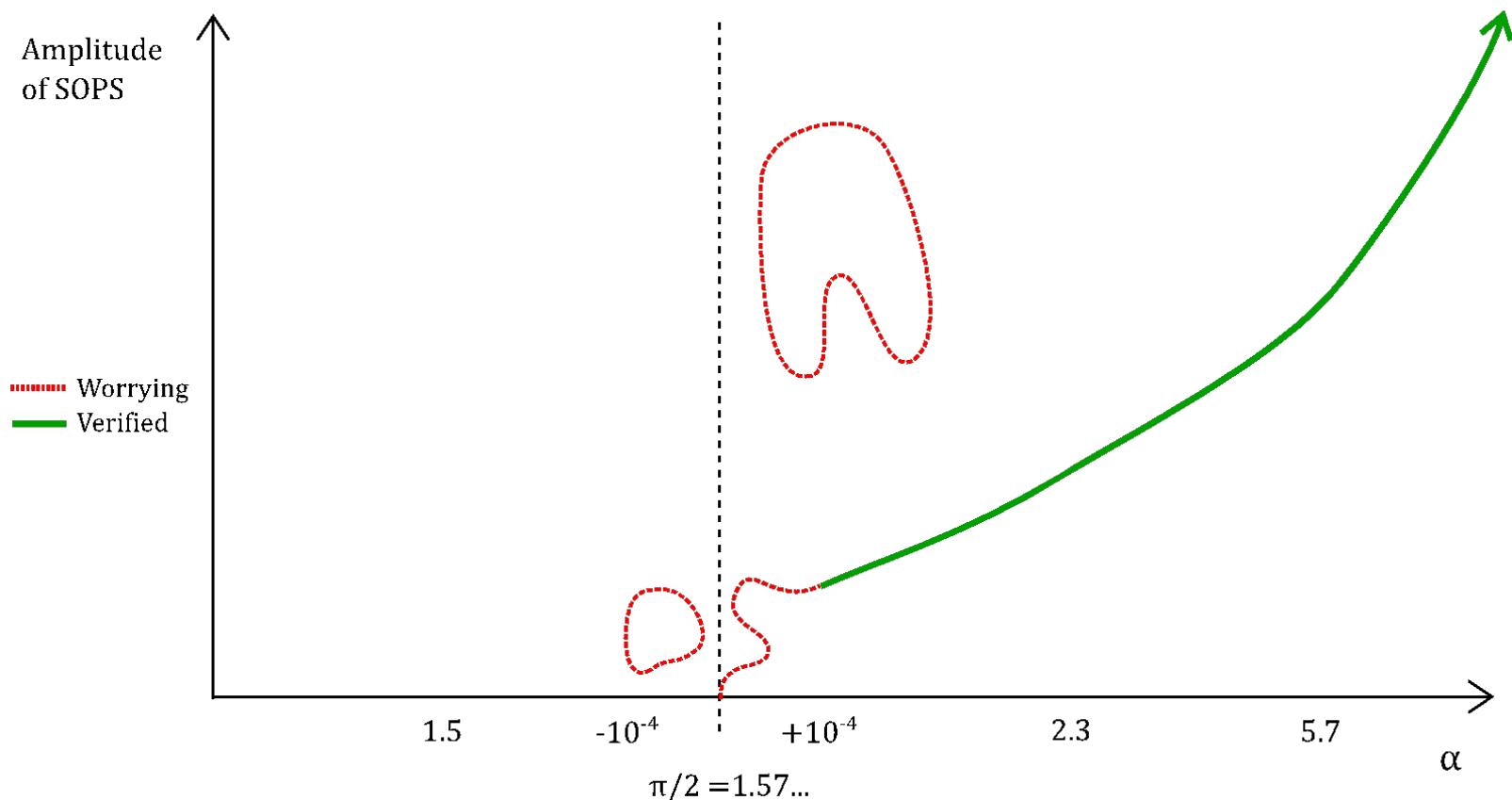


Sketch of Proof

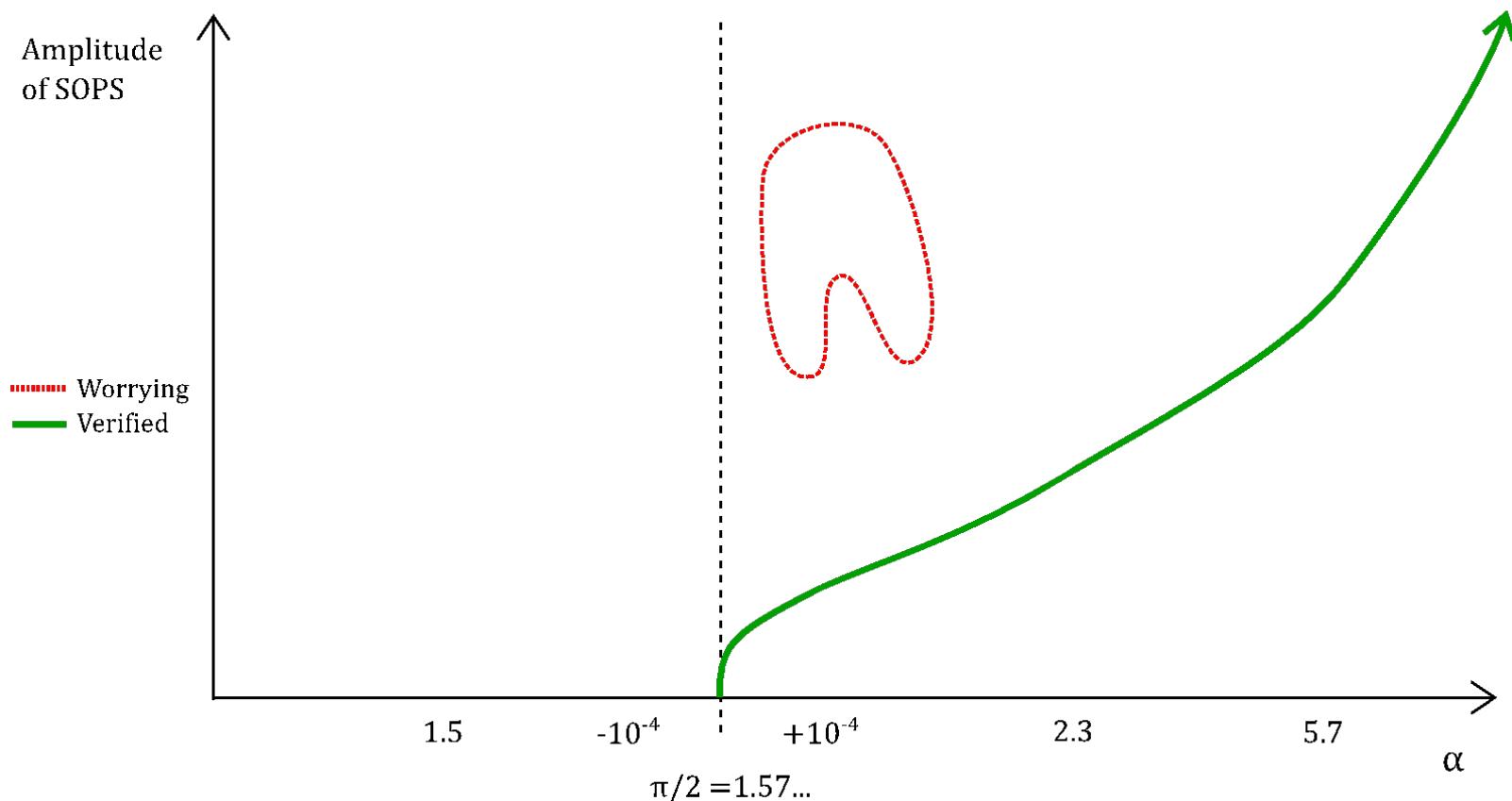


- The **blue region** satisfies $\alpha > \pi/2$
- There cannot be any SOPS in the **red region**
- The **green region** is the only place SOPS could be if $\alpha \in [1.5706, \pi/2]$
- The **green region** is contained inside the **red region**
- Hence, there cannot be any SOPS for $\alpha \in [1.5706, \pi/2]$

Summary



Summary



Thank You!