# Model Uncertainty and <br> Uncertainty Quantification 

Merlise Clyde<br>Duke University<br>http://stat.duke.edu/~clyde

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Rumsfeld's "Known Unknowns" versus "Unknown Unknowns",

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WLOG drop dependence on inputs, $p\left(\mathbf{y}^{*} \mid \mathbf{y}\right)$

## Multiple Models



## Bayesian Perspectives on Model Uncertainty

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$\mathcal{M}$-Complete the true model $\mathcal{M}_{T}$ exists but is not included in the model list $M$. We still wish to use the models in $M$ because of tractability of computations or communication of results, compared with the actual belief model
$\mathcal{M}$-Open we know the true model $\mathcal{M}_{T}$ is not in $M$, but we cannot specify the explicit form $p\left(y^{*} \mid \mathbf{y}\right)$ because it is too difficult conceptually or computationally, we lack time to do so, or do not have the expertise, etc.

Bernardo \& Smith (1994), Clyde \& Iversen (2013)

## Predictive Distributions under $\mathcal{M}$-Closed

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p\left(\mathcal{M}_{m} \mid \mathbf{Y}\right)=\frac{p\left(\mathbf{Y} \mid \mathcal{M}_{m}\right) p\left(\mathcal{M}_{m}\right)}{\sum_{m \in M} p\left(\mathbf{y} \mid \mathcal{M}_{m}\right) p\left(\mathcal{M}_{m}\right)}, \quad m \in M
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where $p\left(\mathbf{Y} \mid \mathcal{M}_{m}\right)=\int p\left(\mathbf{Y} \mid \boldsymbol{\theta}_{m}, \mathcal{M}_{m}\right) p\left(\boldsymbol{\theta}_{m} \mid \mathcal{M}_{m}\right) d \boldsymbol{\theta}_{m}$

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- Predictive distribution

$$
\begin{aligned}
p\left(\mathbf{y}^{*} \mid \mathbf{y}\right) & =\sum_{m \in \mathcal{M}} p\left(\mathbf{y}^{*} \mid \mathcal{M}_{m}, \mathbf{y}\right) p\left(\mathcal{M}_{m} \mid \mathbf{y}\right) \\
& =\sum_{m \in \mathcal{M}}\left[\int p\left(\mathbf{y}^{*} \mid \mathcal{M}_{m}, \boldsymbol{\theta}_{m}, \mathbf{y}\right) p\left(\boldsymbol{\theta}_{m} \mid \mathbf{y}, \mathcal{M}_{m}\right) d \boldsymbol{\theta}_{m}\right] p\left(\mathcal{M}_{m} \mid \mathbf{y}\right)
\end{aligned}
$$

## Estimation and Prediction

Consider the decision problem of estimation/prediction under squared error loss

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u\left(Y^{*}, a\right)=-\left(Y^{*}-a\right)^{2}
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where $a$ is a possible action ( $u$ is utility or negative loss) and $Y^{*}$ is an unknown.

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From a Bayesian perspective, the solution is to find the action that maximizes expected utility given the observed data $\mathbf{Y}$ :

$$
\mathrm{E}_{\mathbf{Y}^{*} \mid \mathbf{Y}}\left[u\left(\mathbf{Y}^{*}, a\right)\right]=-\int\left(y^{*}-a\right)^{2} p\left(\mathbf{y}^{*} \mid \mathbf{y}\right) d \mathbf{y}^{*}
$$

where the expectation is taken with respect to the predictive distribution of $\mathbf{Y}^{*}$ given the observed data $\mathbf{y}$.

## Bayesian Model Averaging

- Under the $\mathcal{M}$-closed perspective, optimal solution for prediction is Bayesian Model Averaging

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a^{*}=\mathrm{E}_{\mathbf{Y}^{*}}\left[\mathbf{Y}^{*} \mid \mathbf{Y}\right]=\sum_{m \in \mathcal{M}} p\left(\mathcal{M}_{m} \mid \mathbf{Y}\right) \hat{Y}_{\mathcal{M}_{m}}^{*}
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where $\hat{Y}_{\mathcal{M}_{m}}^{*}$ is the predictive mean of $\mathbf{Y}^{*}$ under model $\mathcal{M}_{m}$

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- Use joint posterior distribution on $\boldsymbol{\theta} \mid \mathcal{M}$ and $\mathcal{M}$ to obtain prediction intervals
- Full propagation of all "known" uncertainties
- Extensive literature for regression and generalized linear models [Hoeting et al 1999, Clyde \& George 2004, Bayarri et al 2012] with invariant priors/Spike \& Slab + software
- more complex models via RJ-MCMC, SMC, ABC


## Potential Problem with BMA

Two models in $\mathcal{M}$

- $\mathcal{M}_{1}: \mathbf{Y}=\mathbf{X}_{1} \beta_{1}+\mathbf{e}$
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True Model $\mathbf{Y}=\mathbf{X}_{1} \beta_{1 T}+\mathbf{X}_{2} \beta_{2 T}+\mathbf{e}$

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\text { BMA } \hat{\mathbf{Y}}^{*}=p\left(\mathcal{M}_{1} \mid \mathbf{Y}\right) \mathbf{X}_{1} \hat{\beta}_{1}+p\left(\mathcal{M}_{2} \mid \mathbf{Y}\right) \mathbf{X}_{2} \hat{\beta}_{2}
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- Other model ensembles ?


## Combining Models as a Decision Problem

- In $\mathcal{M}$-Complete or $\mathcal{M}$-Open viewpoints, if $\mathcal{M}_{T}$ is not in the list of models $M$ then $p\left(\mathcal{M}_{m}\right)=0$ for $\mathcal{M}_{m} \in M$.


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- Treat weights $\left\{w_{m}, m \in m\right\}$ as part of the action space (rather than an unknown) and maximize posterior expected utility,

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- For negative squared error:

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-\mathrm{E}_{\mathbf{Y}^{*} \mid \mathbf{y}, \mathcal{M}_{T}}\left\|\mathbf{Y}^{*}-a(\mathbf{w}, \mathbf{y})\right\|^{2}=-\int\left\|\mathbf{y}^{*}-\sum_{m} w_{m} \hat{\mathbf{Y}}_{m}^{*}\right\|^{2} p\left(\mathbf{y}^{*} \mid \mathbf{y}, \mathcal{M}_{T}\right)
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- Focus on $\mathcal{M}$-Open case


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- $\mathbf{Y}_{j}$ is a proxy for $\mathbf{Y}^{*}$ (the future observation(s))
- $\mathbf{Y}_{(-j)}$ is a proxy for $\mathbf{Y}$ (the observed data)
- randomly select $J$ partitions,

$$
\int u\left(\mathbf{Y}^{*}, a(\mathbf{w}, \mathbf{y})\right) p\left(\mathbf{y}^{*} \mid \mathbf{y}, \mathcal{M}_{T}\right) d \mathbf{y}^{*} \approx \frac{1}{J} \sum_{j=1}^{J} u\left(Y_{j}, a\left(\mathbf{w}, Y_{(-j)}\right)\right)
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- Guterriez-Pena \& Walker approximation to a (limiting) Dirichlet process model for estimating unknown distribution $F$ for $\mathcal{M}_{T}$

$$
\int u\left(y^{*}, a^{*}(\mathbf{w}, \mathbf{y})\right) d F_{n}\left(y^{*}\right) \rightarrow \frac{1}{n} \sum_{i=1}^{n} u\left(y_{i}, a^{*}\left(\mathbf{w}, \mathbf{Y}_{(-i)}\right)\right)
$$

## Optimization Problem under Approximation

Find weights

$$
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Equivalent representation (Lagrangian):
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Super-Learners! h2oEnsemble

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## MOMA Weights



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- Compute classification accuracy over 5 Splits


## MOMA with Sum-to-1 Constraint

|  | set1 | set2 | set3 | set4 | set5 |
| ---: | ---: | ---: | ---: | ---: | ---: |
| clin1 | 53.08 | -4.43 | -0.01 | -24.41 | 15.94 |
| clin2 | -79.92 | -5.16 | 0.90 | 0.80 | -4.63 |
| clin3 | -1.25 | -0.24 | -0.90 | -0.01 | 5.35 |
| clin4 | 27.36 | 10.14 | -0.33 | 23.73 | -17.24 |
| clin5 | 1.13 | 0.27 | 0.27 | 0.36 | 0.55 |
| tree1 | -0.05 | -0.55 | -2.92 | 0.03 | 27.93 |
| tree2 | -0.12 | -0.07 | -3.21 | -0.62 | 0.63 |
| tree3 | 0.51 | 0.53 | 0.15 | 0.48 | -3.35 |
| tree4 | -0.28 | 0.22 | 6.26 | -0.04 | -24.10 |
| Ida100.P1 | -0.40 | 0.04 | -0.01 | 0.02 | -0.11 |
| Ida100.P2 | 0.44 | -0.02 | 0.53 | -0.06 | -0.07 |
| Ida200.P1 | 0.30 | 0.17 | -0.32 | 0.09 | -0.03 |
| Ida200.P2 | 0.21 | 0.08 | 0.60 | 0.63 | 0.12 |
| Accuracy | 0.64 | 0.64 | 0.46 | 0.73 | 0.60 |

## MOMA with Non-negativity Constraint

|  | set1 | set2 | set3 | set4 | set5 |
| ---: | :---: | :---: | :---: | :---: | :---: |
| clin1 | 0.00 | 0.07 | 0.00 | 0.00 | 0.00 |
| clin2 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 |
| clin3 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 |
| clin4 | 0.00 | 0.11 | 0.00 | 0.00 | 0.00 |
| clin5 | 0.30 | 0.17 | 0.07 | 0.41 | 0.00 |
| tree1 | 0.00 | 0.00 | 0.00 | 0.00 | 0.77 |
| tree2 | 0.00 | 0.00 | 0.00 | 0.00 | 0.21 |
| tree3 | 0.23 | 0.44 | 0.21 | 0.00 | 0.01 |
| tree4 | 0.00 | 0.00 | 0.00 | 0.00 | 0.01 |
| Ida100.P1 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 |
| Ida100.P2 | 0.22 | 0.00 | 0.30 | 0.00 | 0.00 |
| Ida200.P1 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 |
| Ida200.P2 | 0.26 | 0.21 | 0.41 | 0.58 | 0.00 |
| Accuracy | 0.82 | 0.73 | 0.55 | 0.73 | 0.60 |

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