

# Mixing and Pumping by Pairs of Helices in a Viscous Fluid

Amy Buchmann and Lisa J. Fauci, Tulane University

Karin Leiderman, Colorado School of Mines

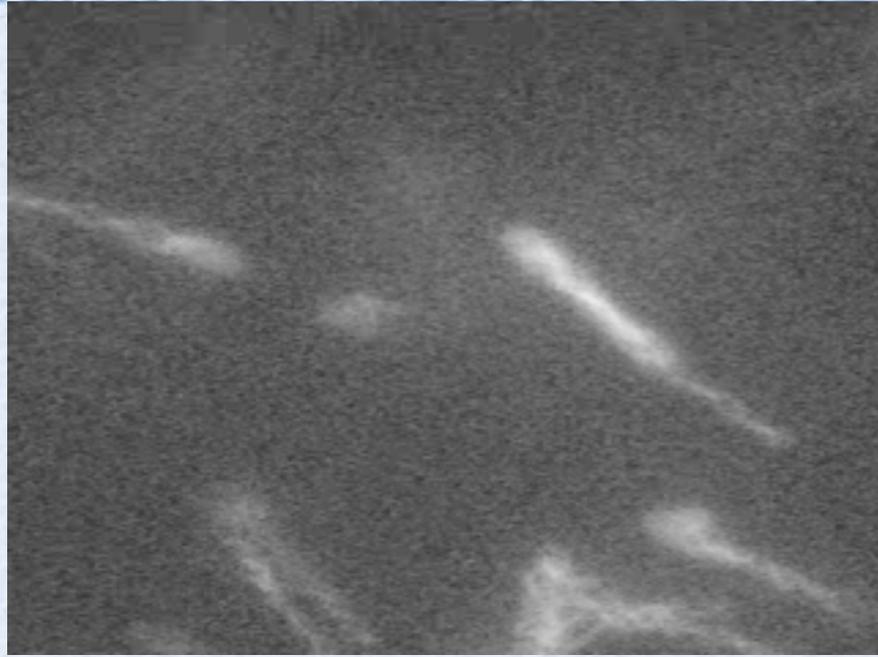
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Minneapolis, August 6 - 9, 2018

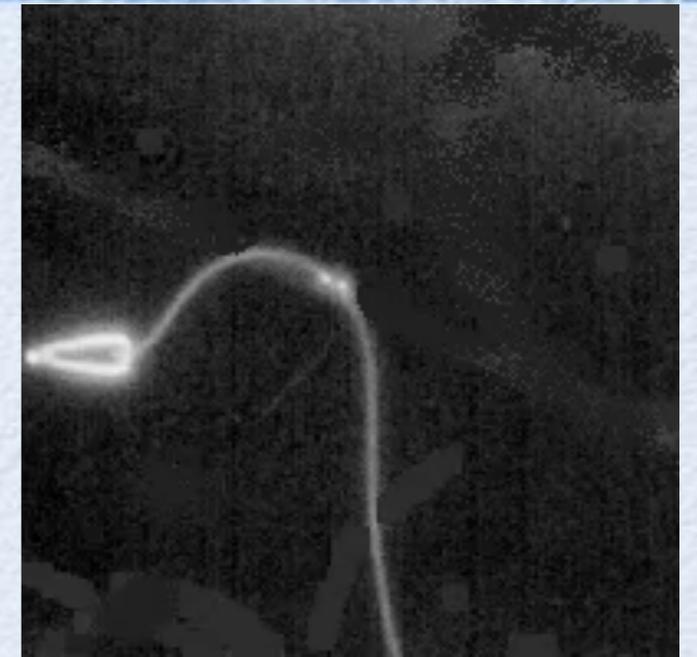
# Examples of Low Re swimmers



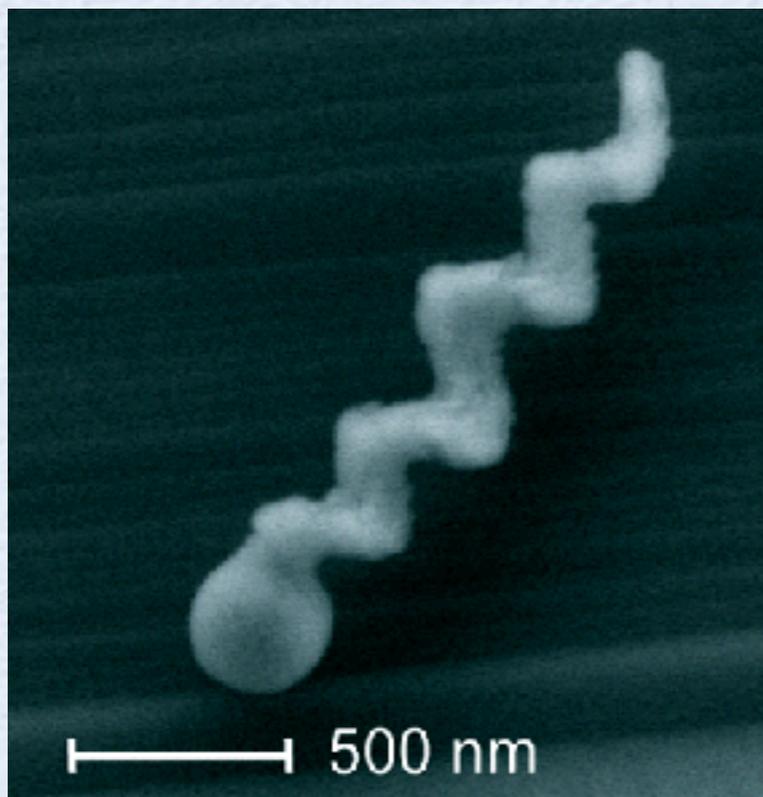
***E. Coli bacteria***  
L. Turner, Harvard



***Spirochete***  
S. Goldstein, UMN



***Sea urchin sperm***  
C. Brokaw, Caltech



***Artificial Propellers***  
Ghosh and Fischer, Nano Letters 2009

# Reynolds number

Dimensionless parameter – ratio of inertial forces to viscous forces:

$$Re = \text{Density} * \text{Length} * \text{Velocity} / \text{Viscosity}$$

Man swimming: 10,000

Goldfish: 100

Nematode: 1

Sperm cell: .01

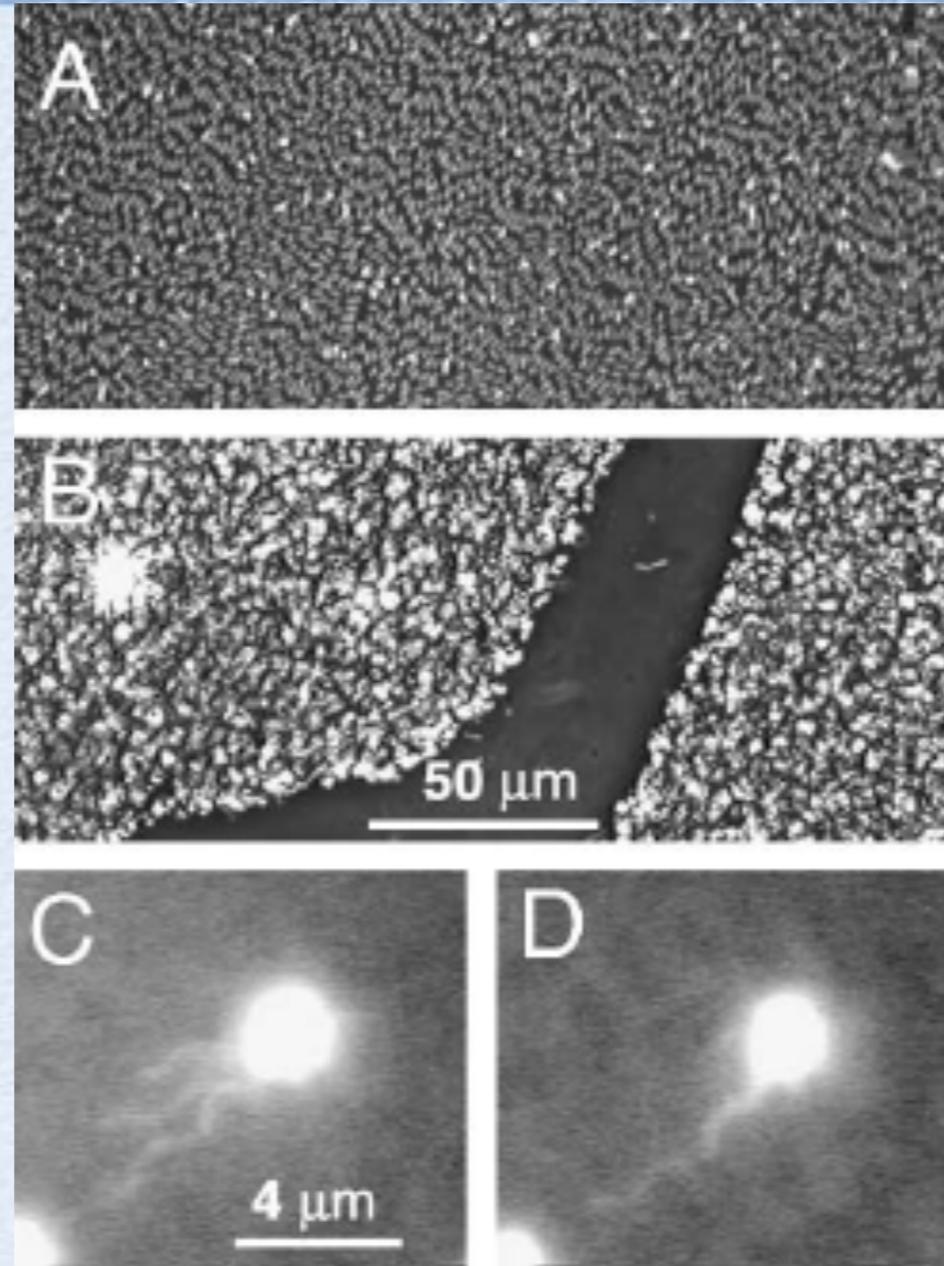
Bacteria: .0001



Life at low Reynolds number

E.M. Purcell, 1976 American J. Physics

# Bacterial Carpets



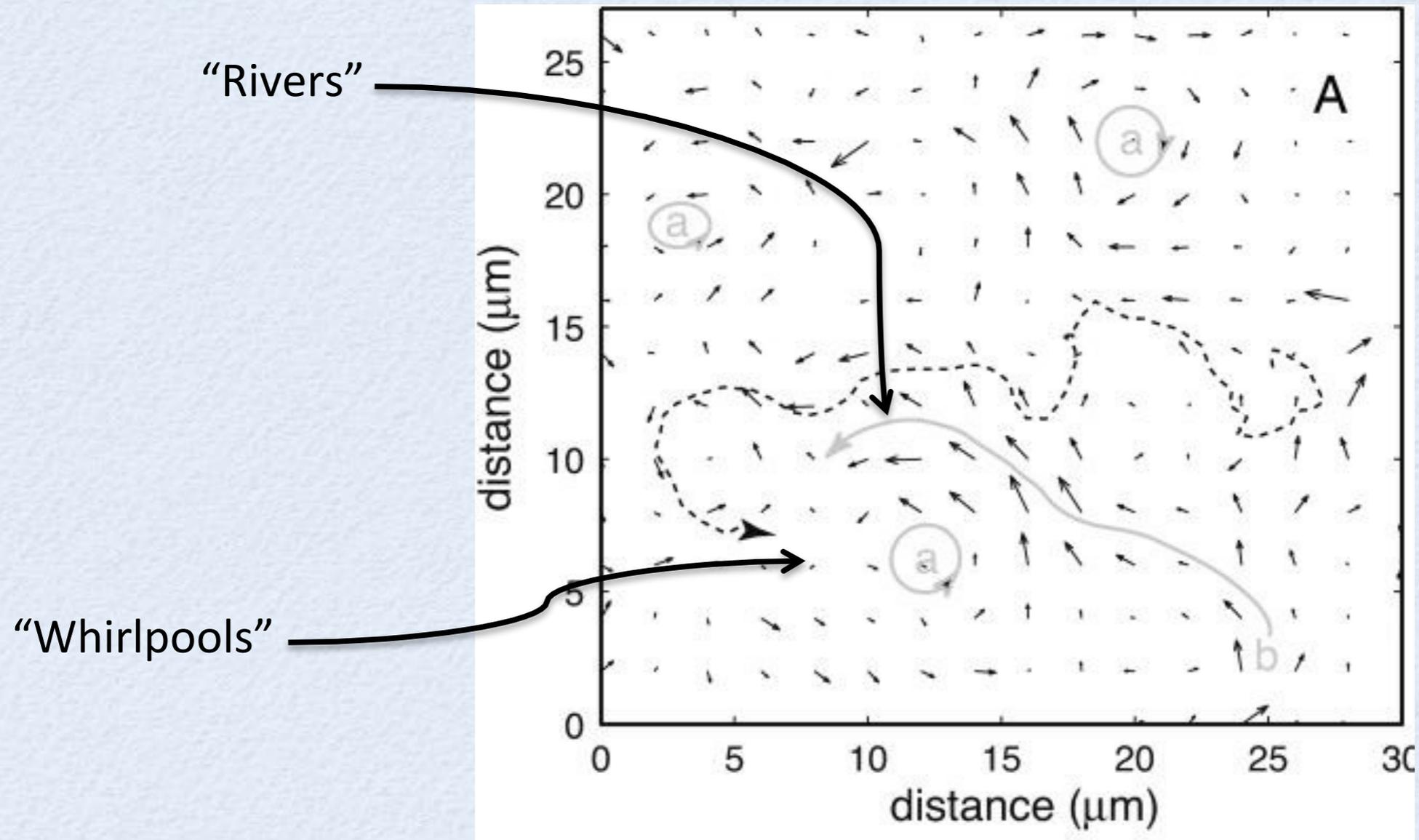
Biophysical Journal Volume 86 March 2004 1863–1870

## Moving Fluid with Bacterial Carpets

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# Flow structure



# Fundamental questions

These **bacterial carpets** bring up fundamental questions in fluid mechanics regarding the interaction of a collection of helices and finite-volume particles with a Newtonian Stokes fluid.

- How does **alignment** of helices affect transport?
- How does spatial **distribution** affect transport?
- How does the presence of the **planar wall** affect axial thrust and flow features?
- How are finite volume **particles** transported by bacterial carpet?

# Governing equations

## Navier-Stokes Equation

$$\rho \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla p + \mu \nabla^2 \mathbf{u}$$

$$\nabla \cdot \mathbf{u} = 0$$

+ boundary conditions

$\rho$  : fluid density,  $p$  : fluid pressure,  $\mu$  : dynamic viscosity

The condition for Stokes regime to hold

$$SrRe = \rho \omega \ell^2 / \mu \ll 1 \quad Re = \rho \omega \ell^2 \sin(\kappa) / \mu \ll 1 \quad (\text{Typically, } 10^{-4} - 10^{-3} )$$

# Fundamental solution: Stokeslet

$$\mu \nabla^2 \mathbf{u} + f_S = \nabla p$$

$$\nabla \cdot \mathbf{u} = 0$$

where  $f_S = 8\pi\mu\boldsymbol{\alpha}\delta(\mathbf{x})$

$\delta(\mathbf{x})$  : the 3D Dirac delta-function

$\boldsymbol{\alpha}$  : the strength of Stokeslet

$$\mathbf{u}_S(\mathbf{x}; \boldsymbol{\alpha}) = \frac{\boldsymbol{\alpha}}{|\mathbf{x}|} + \frac{(\boldsymbol{\alpha} \cdot \mathbf{x})\mathbf{x}}{|\mathbf{x}|^3}$$

$$p_S(\mathbf{x}; \boldsymbol{\alpha}) = -2\mu \frac{(\boldsymbol{\alpha} \cdot \mathbf{x})}{|\mathbf{x}|^3}$$

More singular solutions can be derived from the Stokeslet by differentiation.

# Many important models have been created with the fundamental solutions.

## Examples:

Analyses of flagellar motions

Beating motion of cilia

Flows between plates and inside cylinders

Flows in periodic geometries

Slender body theories

## Difficulties:

- Shapes
- Interaction between objects
- Instabilities near the singularities

# Regularized Stokeslet

$$\mu \nabla^2 \mathbf{u} + \mathbf{f} = \nabla p, \quad \nabla \cdot \mathbf{u} = 0$$

$\mathbf{f} = \mathbf{f}_0 \phi_\epsilon(\mathbf{x} - \mathbf{x}_0)$  the external force

$$\mathbf{u} = \frac{1}{\mu} [(\mathbf{f}_0 \cdot \nabla) \nabla \mathbf{B}_\epsilon - \mathbf{f}_0 \mathbf{G}_\epsilon]$$

$$\nabla^2 G_\epsilon = \phi_\epsilon \text{ and } \nabla^2 B_\epsilon = G_\epsilon$$

Forces are spread over a small ball -- in the case  $\mathbf{x}_0=0$

**Method of regularized Stokeslets** (R. Cortez, SIAM SISC 2001)

# Velocity field

For the choice:

$$\phi_\epsilon(\mathbf{x}) = \frac{15\epsilon^4}{8\pi(r^2 + \epsilon^2)^{7/2}}.$$

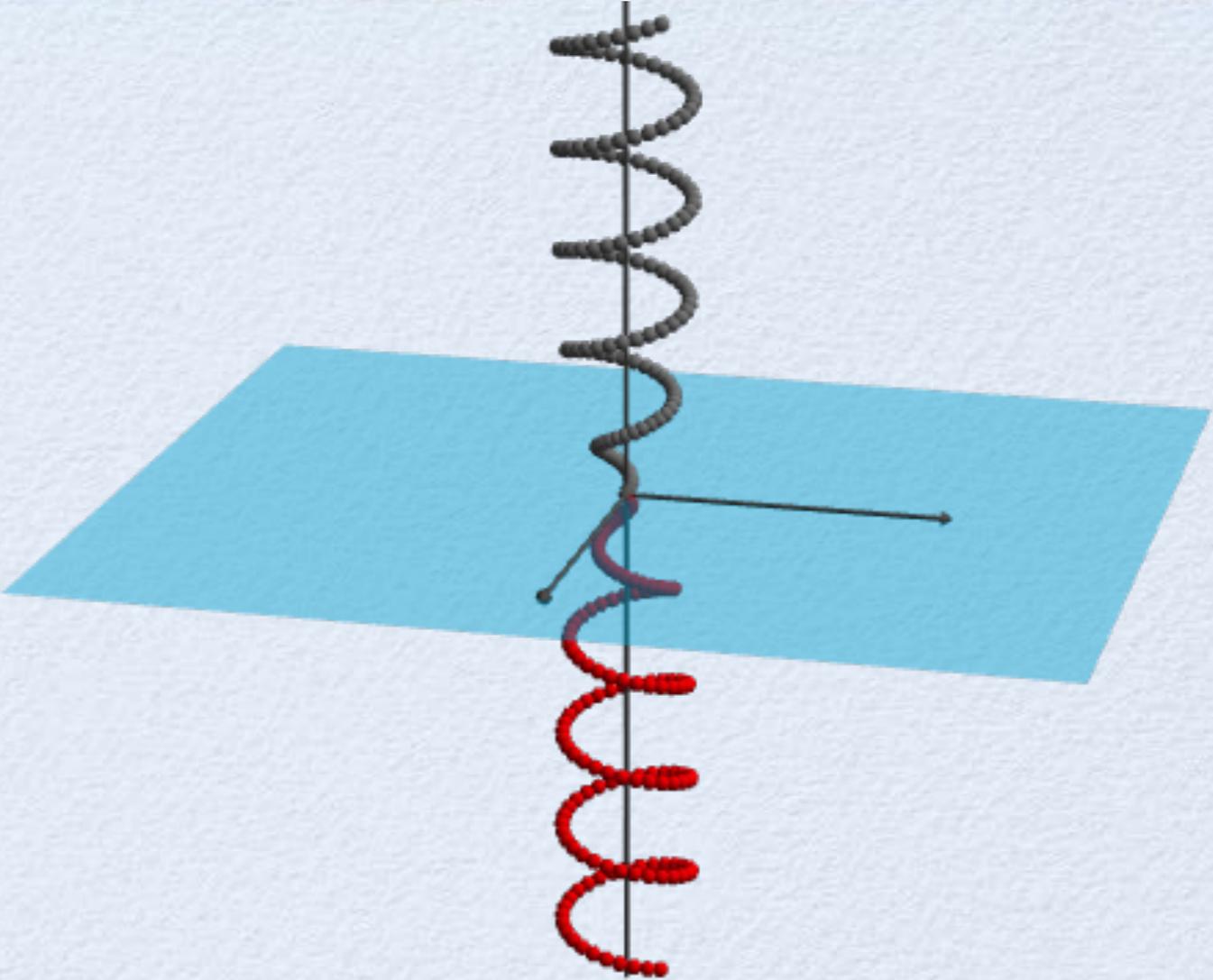
the resulting velocity field is:

$$\mathbf{u}(\mathbf{x}) = \frac{1}{8\pi\mu} \left\{ \mathbf{f}_0 \frac{2\epsilon^2 + r^2}{(r^2 + \epsilon^2)^{3/2}} + \frac{(\mathbf{f}_0 \cdot \mathbf{x})\mathbf{x}}{(r^2 + \epsilon^2)^{3/2}} \right\}$$

Note:

- $\mathbf{u}(\mathbf{x})$  is defined everywhere
- $\mathbf{u}(\mathbf{x})$  is an exact solution to the Stokes equations, and is incompressible
- **Grid-free** numerical method

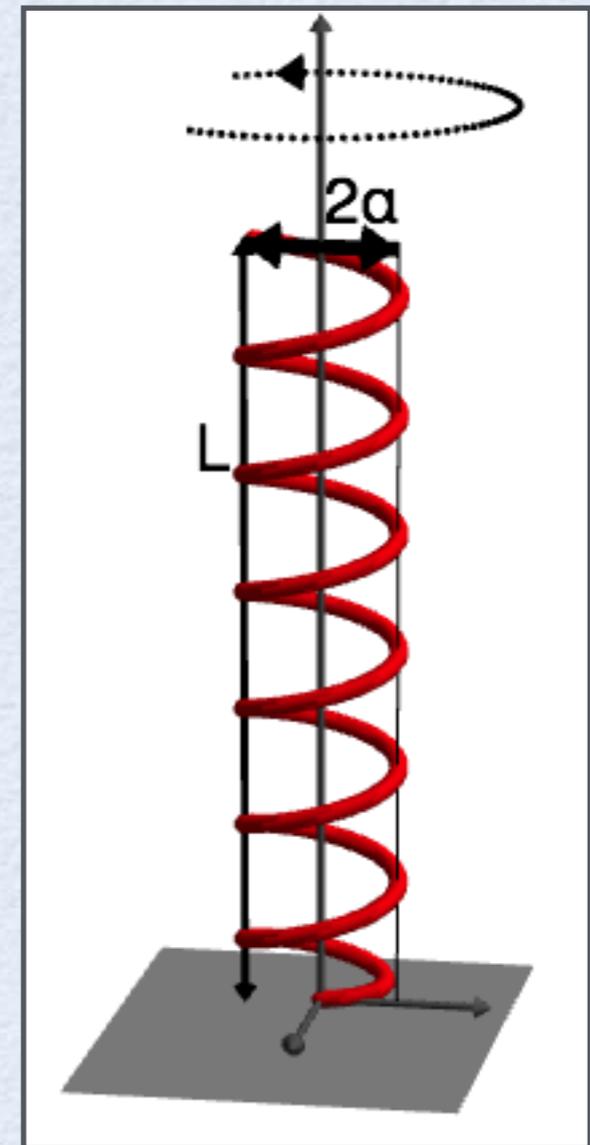
# Superposition of singularity and image system

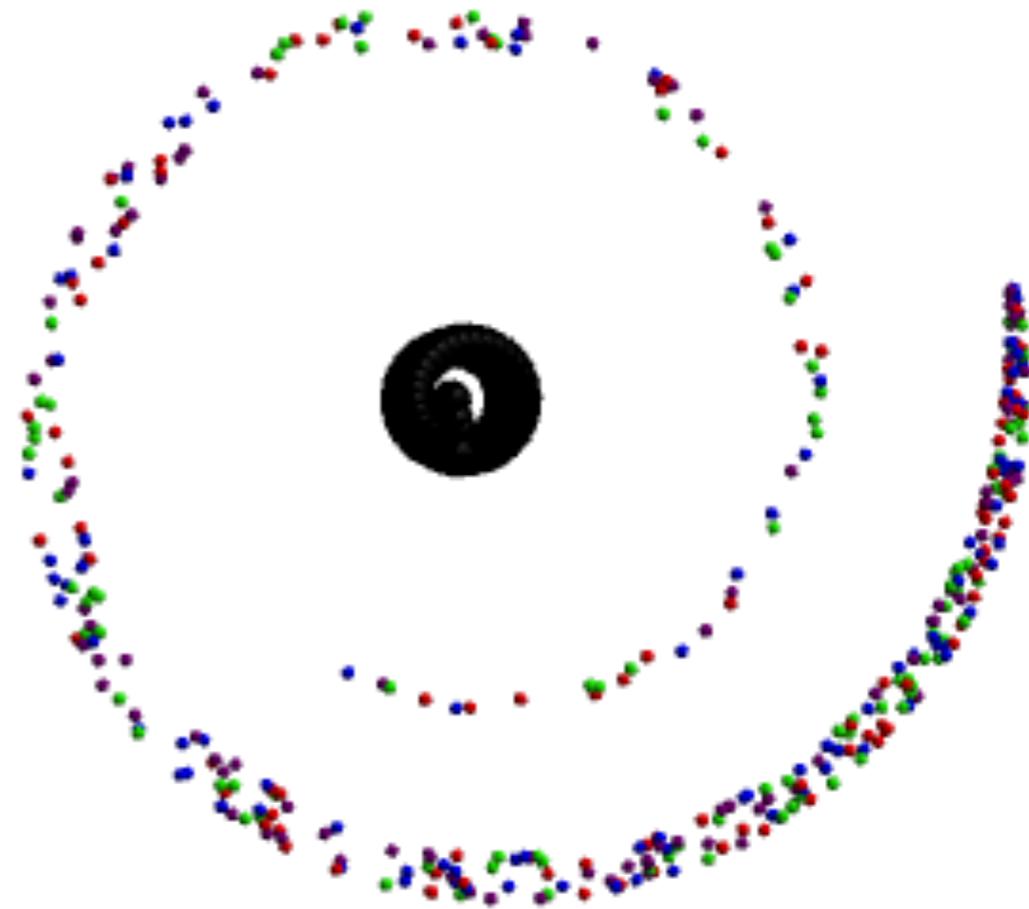
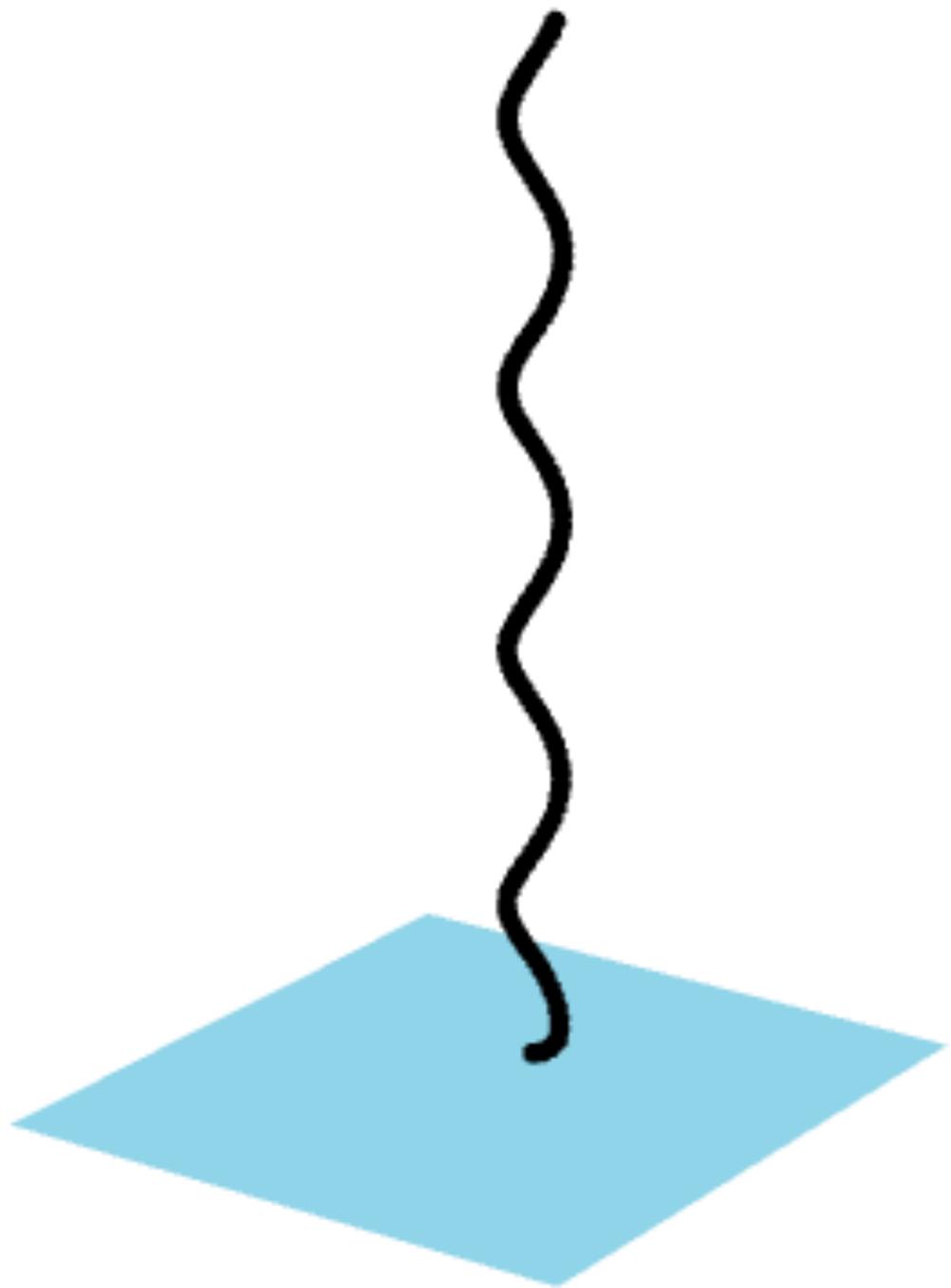
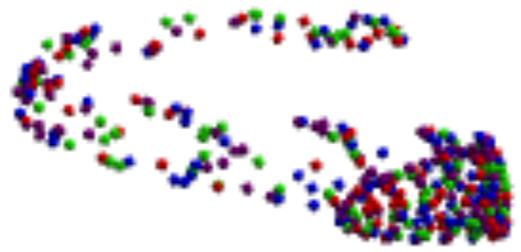


# Modeling Helical Flagellum

$$U = AF$$

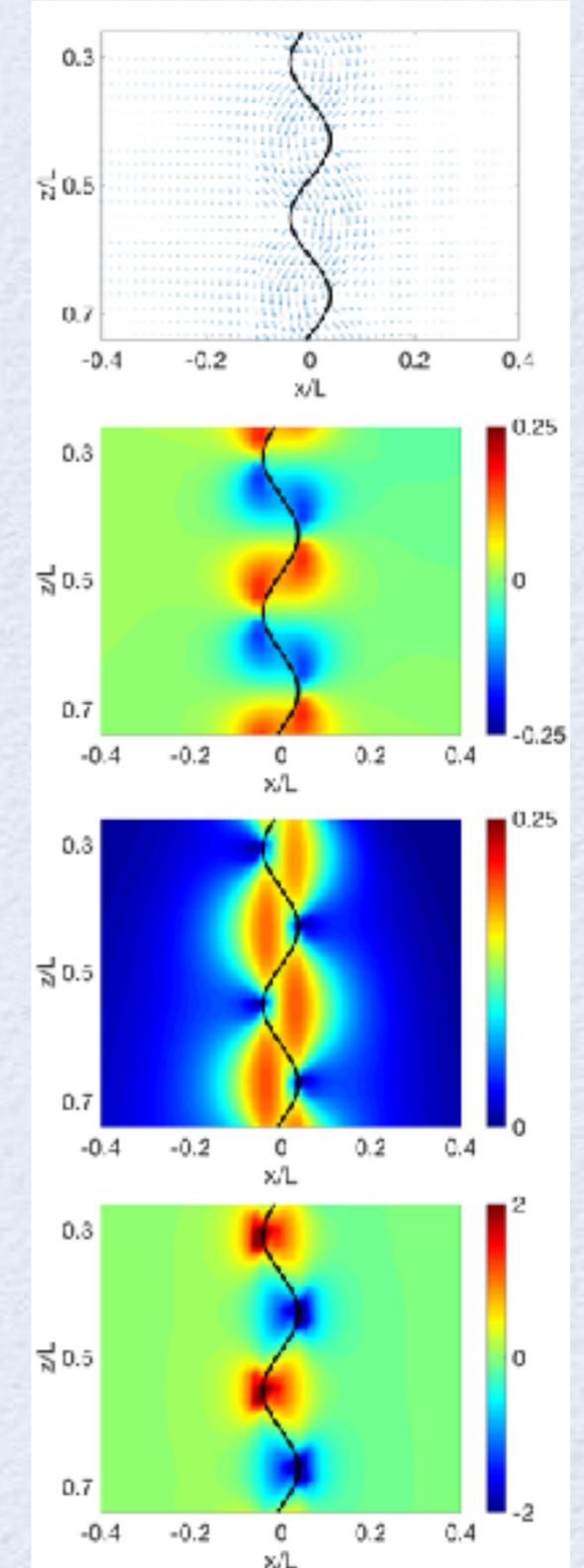
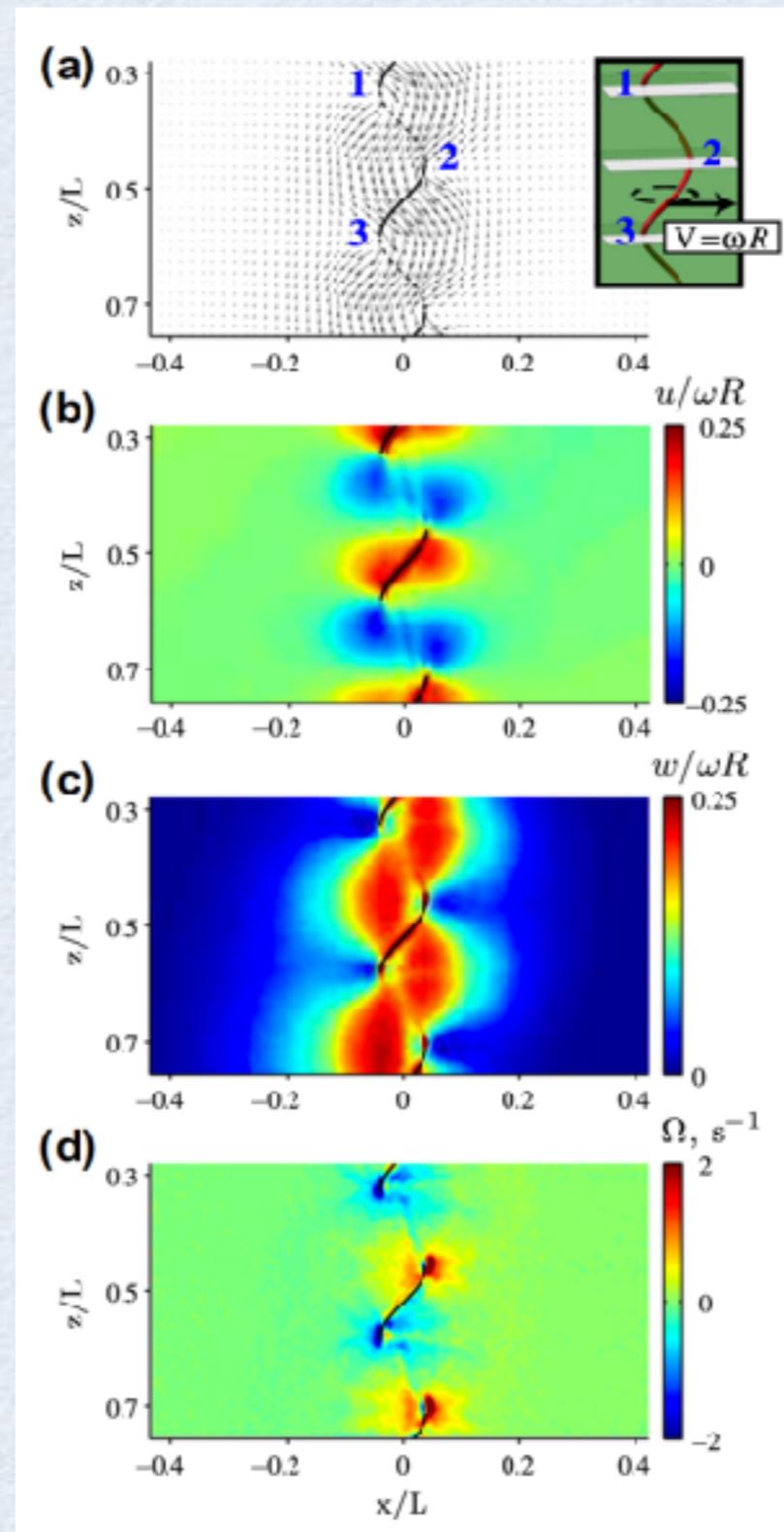
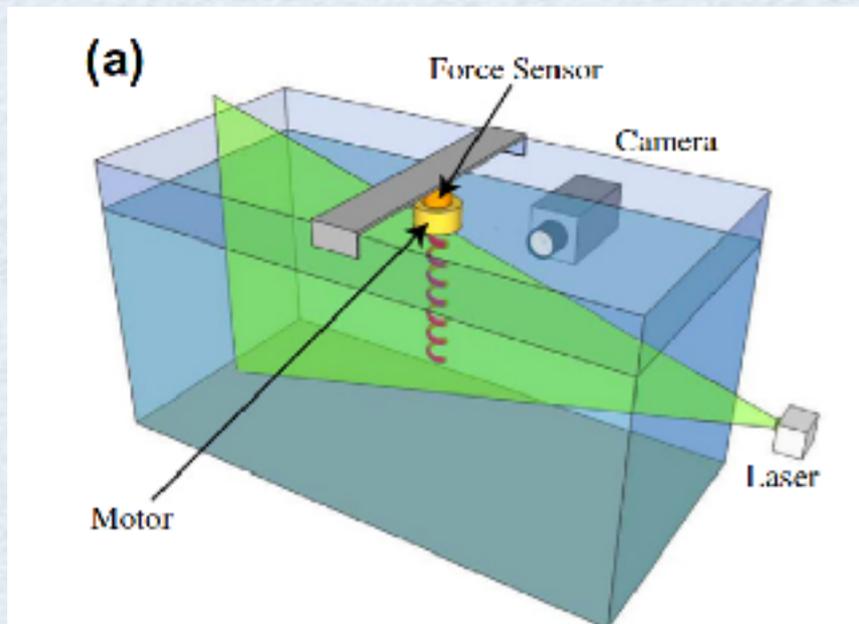
- Solve for the forces on the points of the helix that will give the prescribed velocity.
- Use these forces to find the fluid velocity at any point



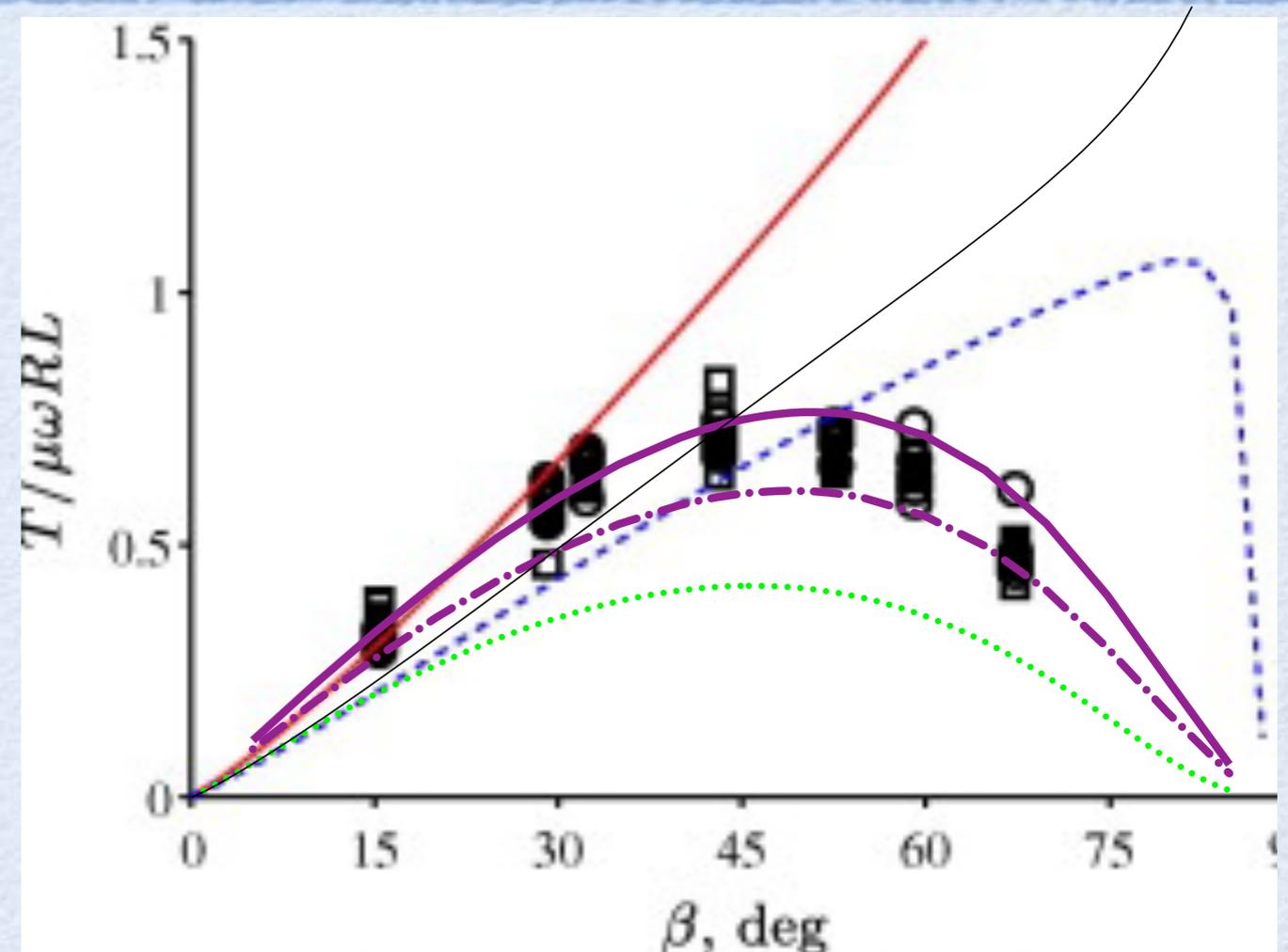
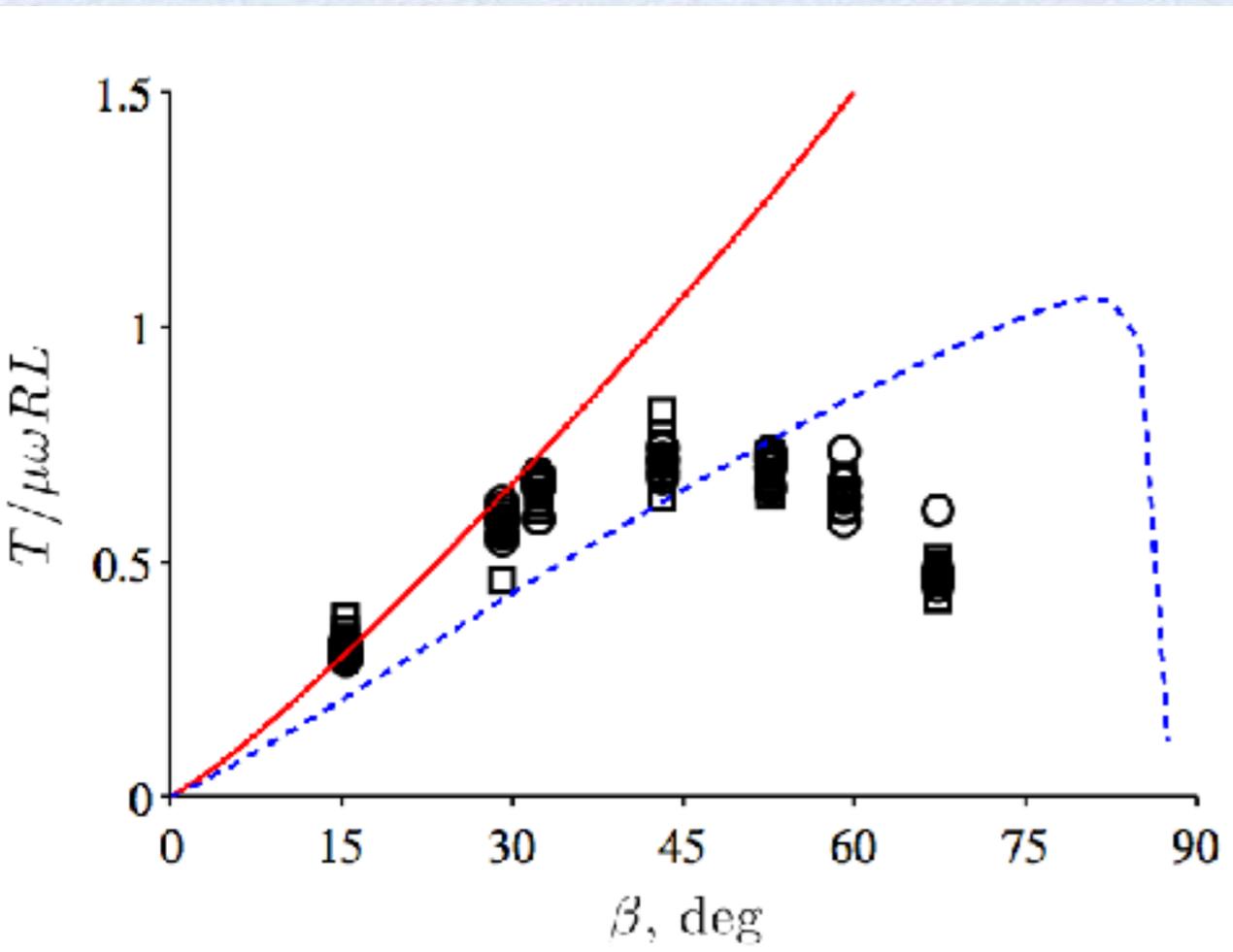


# Experiment

# Simulation



# Normalized thrust as functions of pitch angle



Zhong et al. (2013)

Resistive-force theory

red: Gray and Hancock

blue: Cox, Johnson and Brokaw

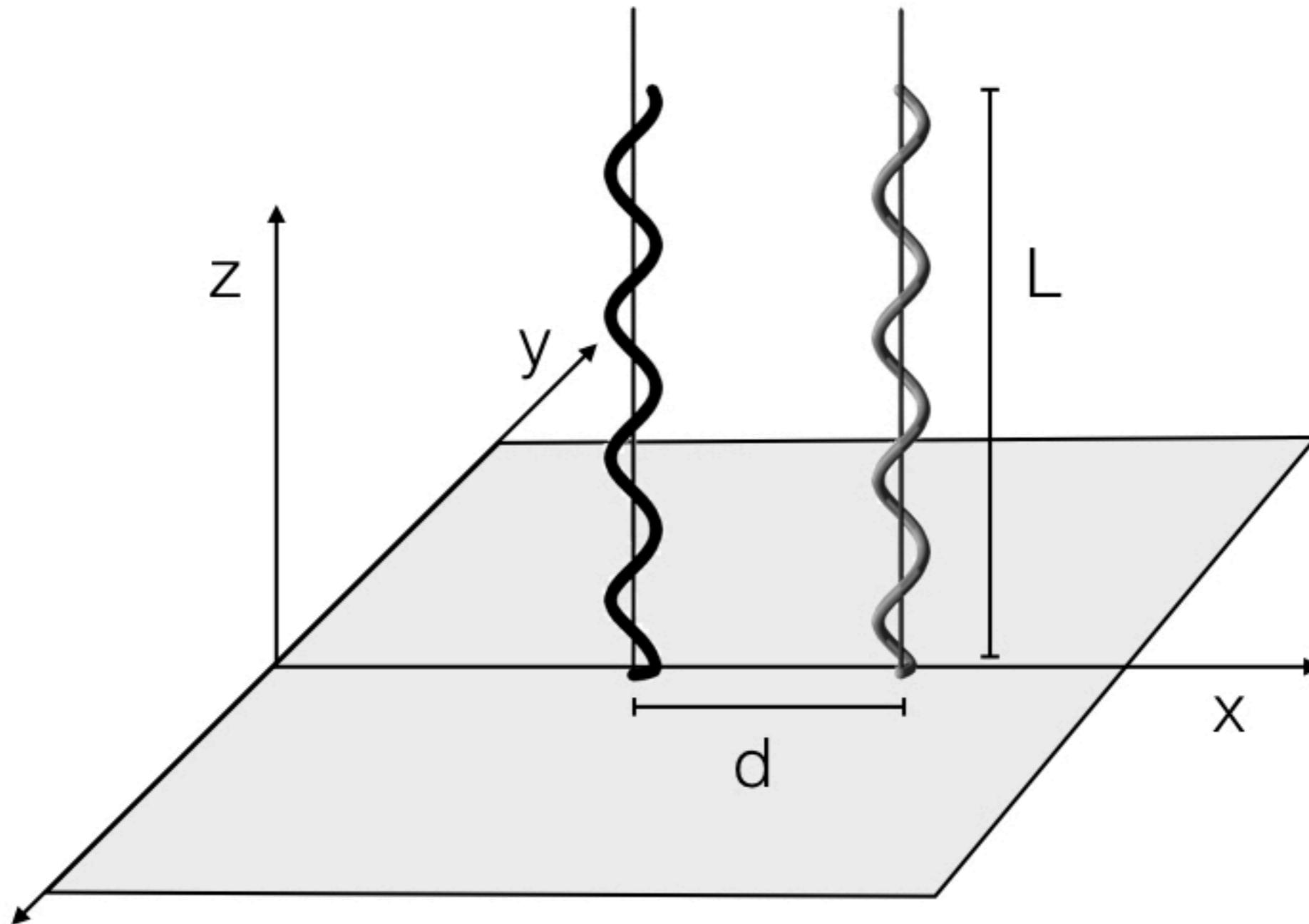
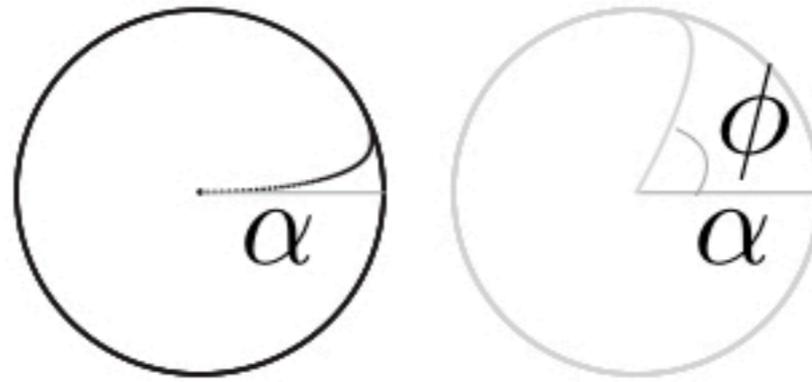
Resistive-force theory

black: Lighthill

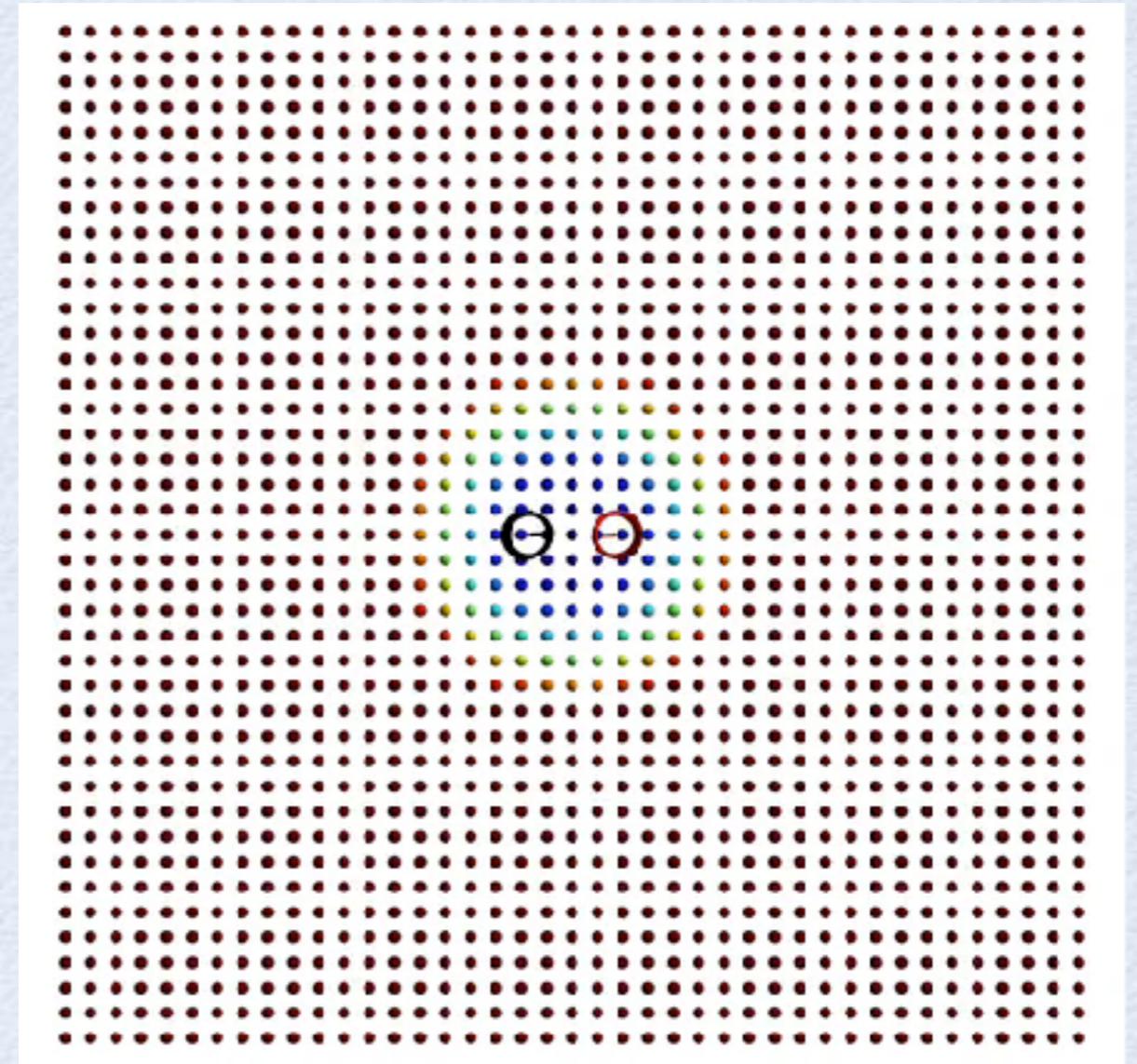
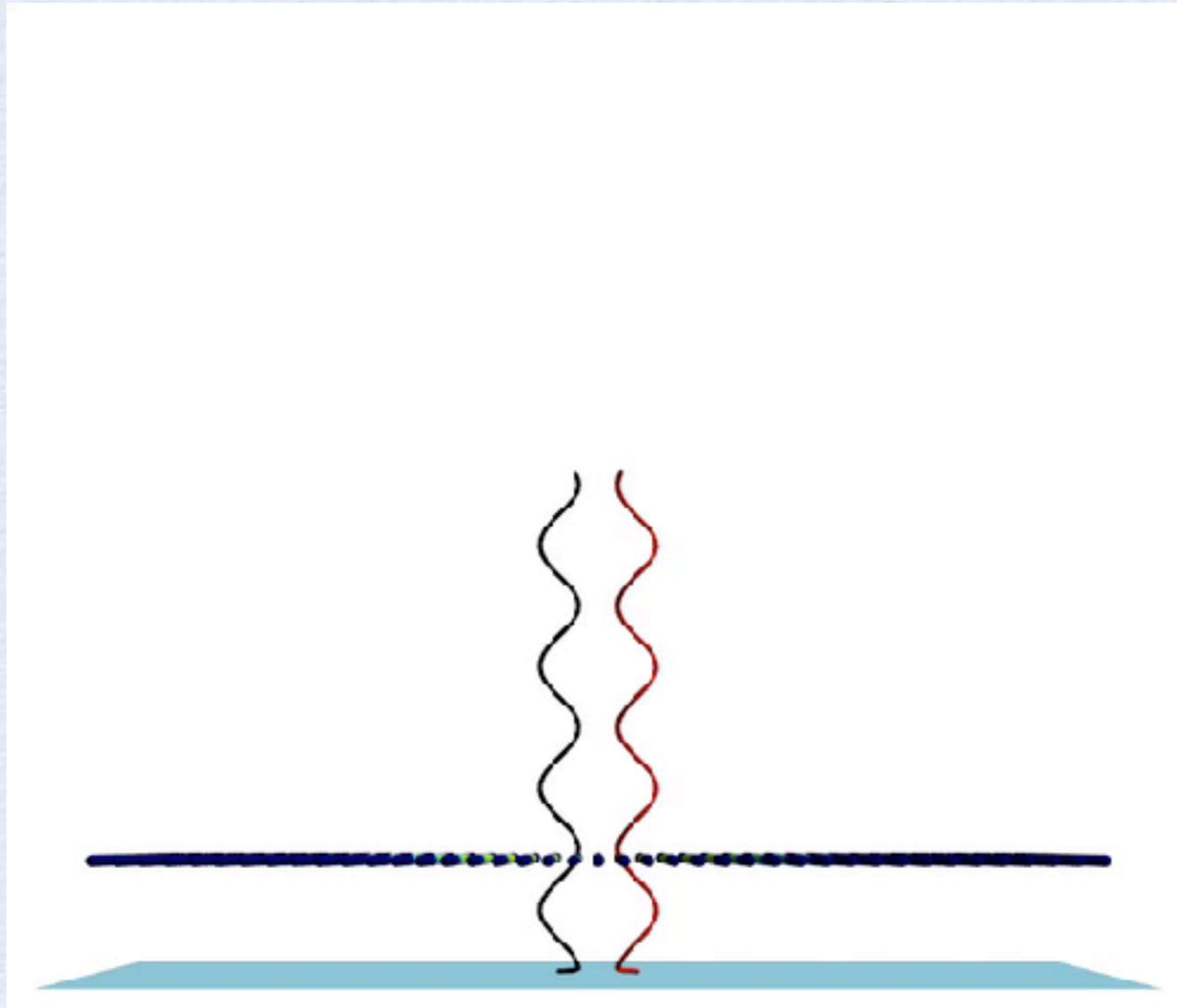
Regularized Stokeslet Method:

purple: with wall green: no wall effect

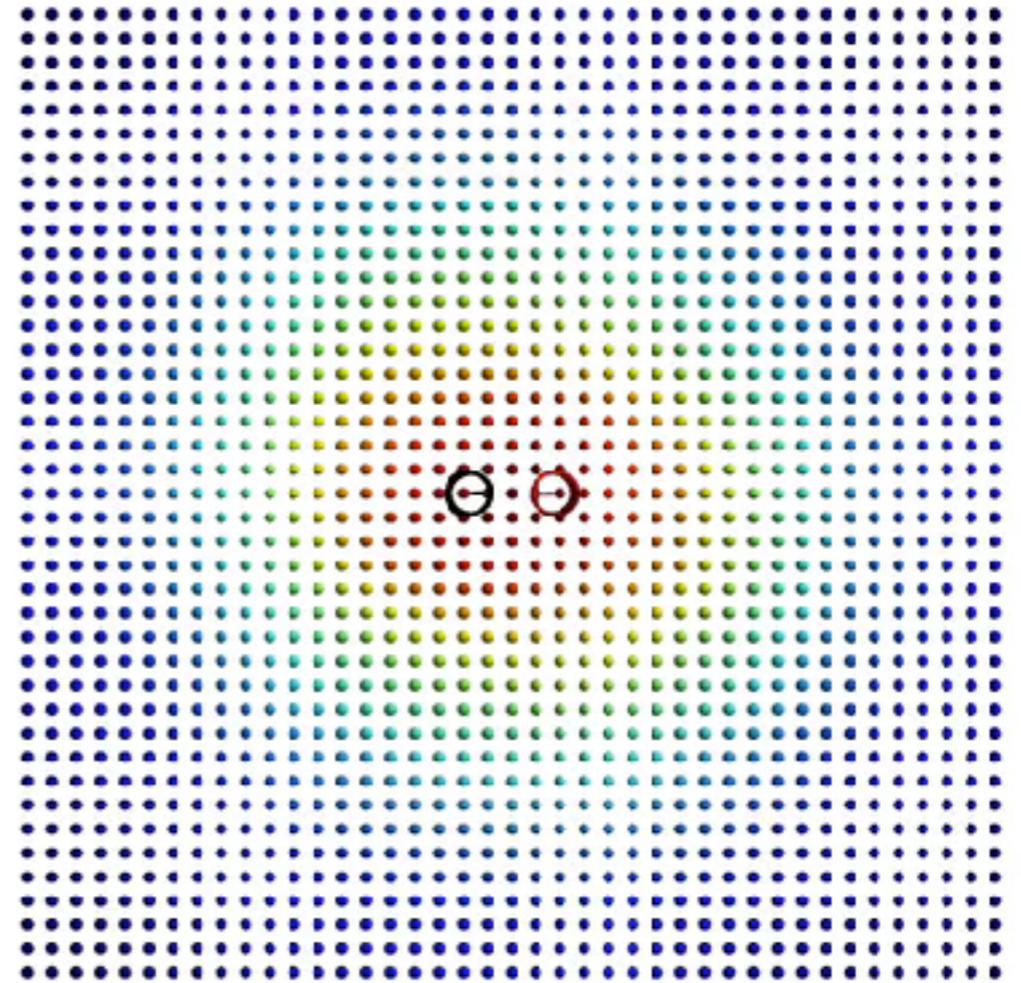
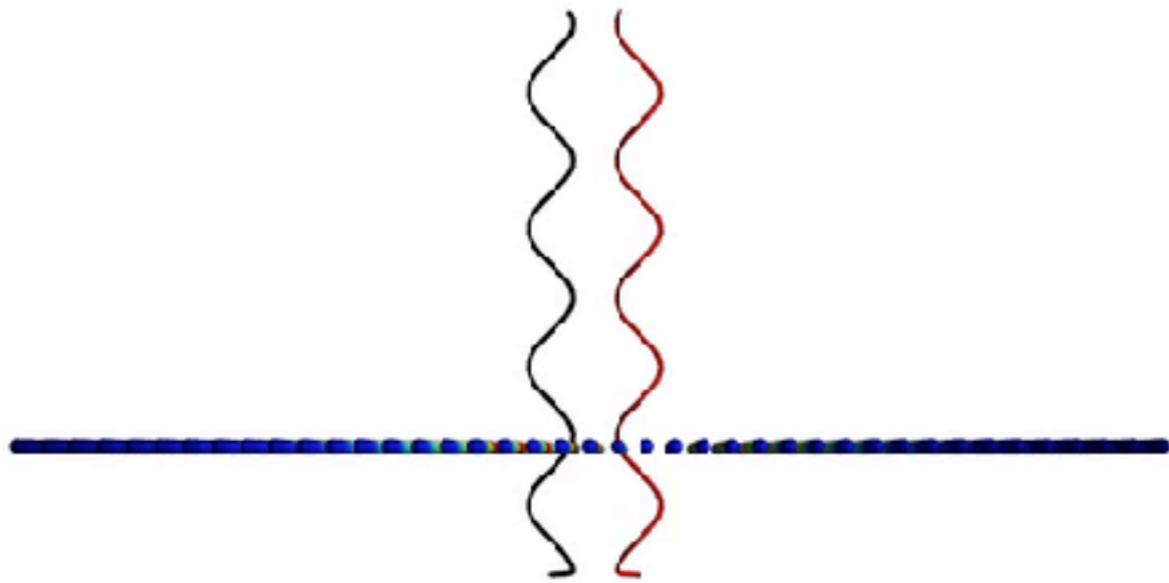
Top view:



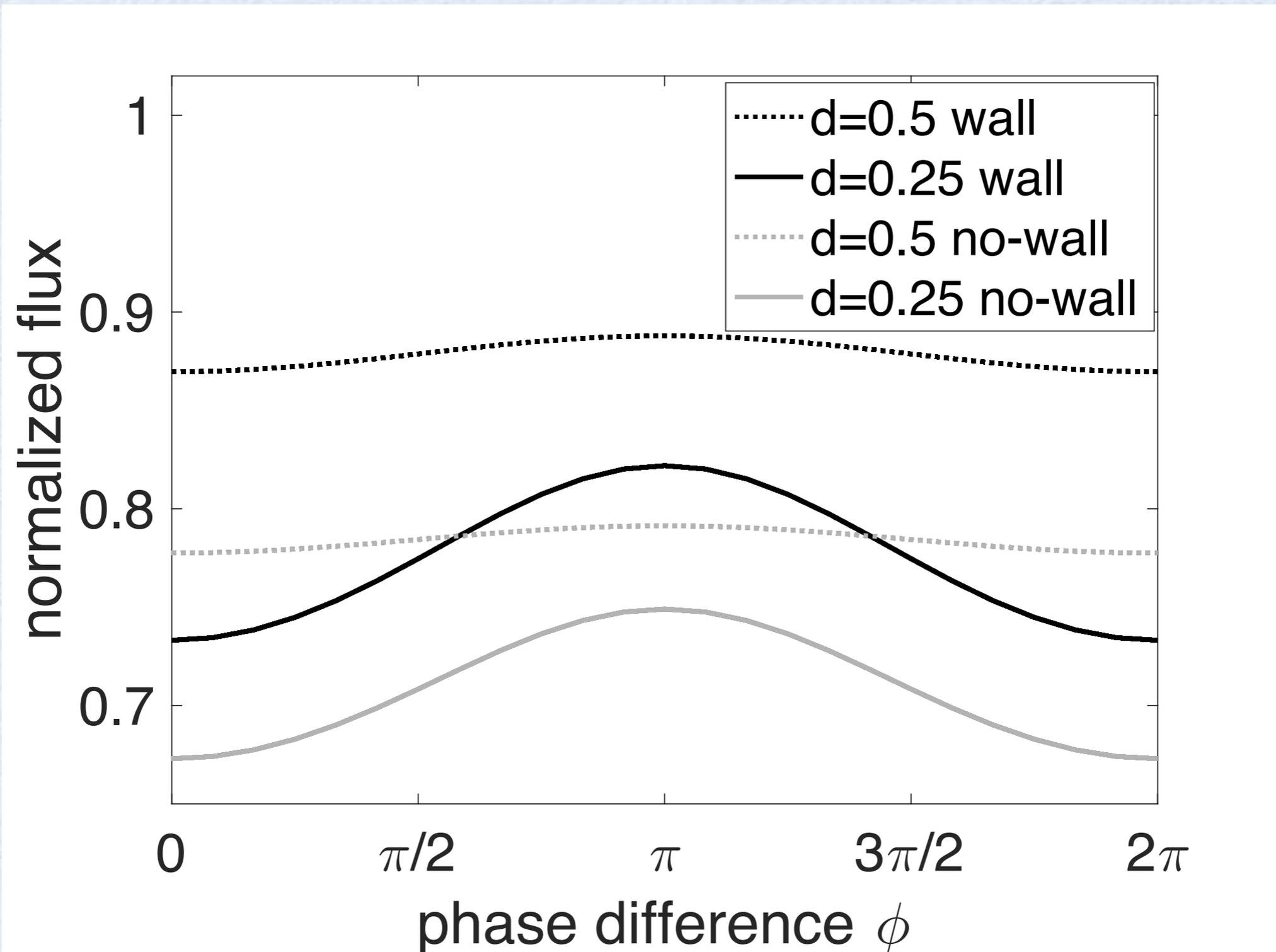
# Fluid particle



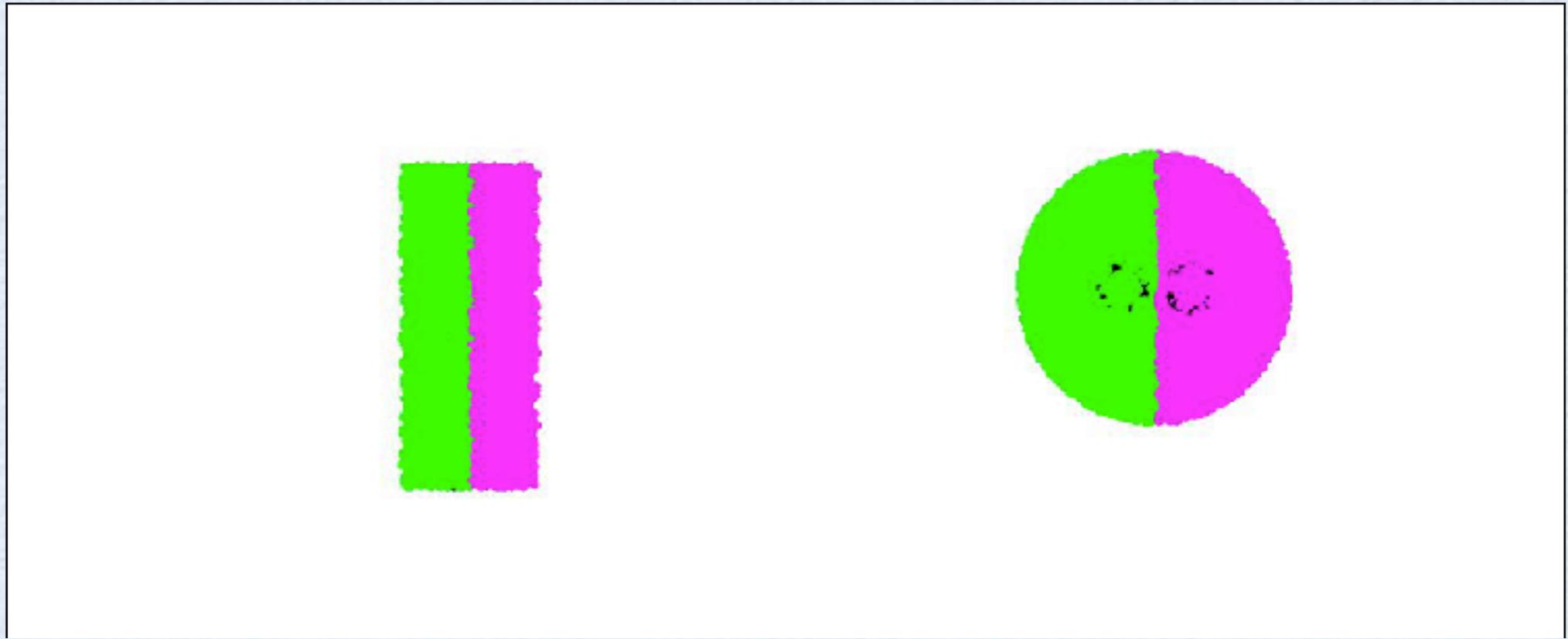
# No wall



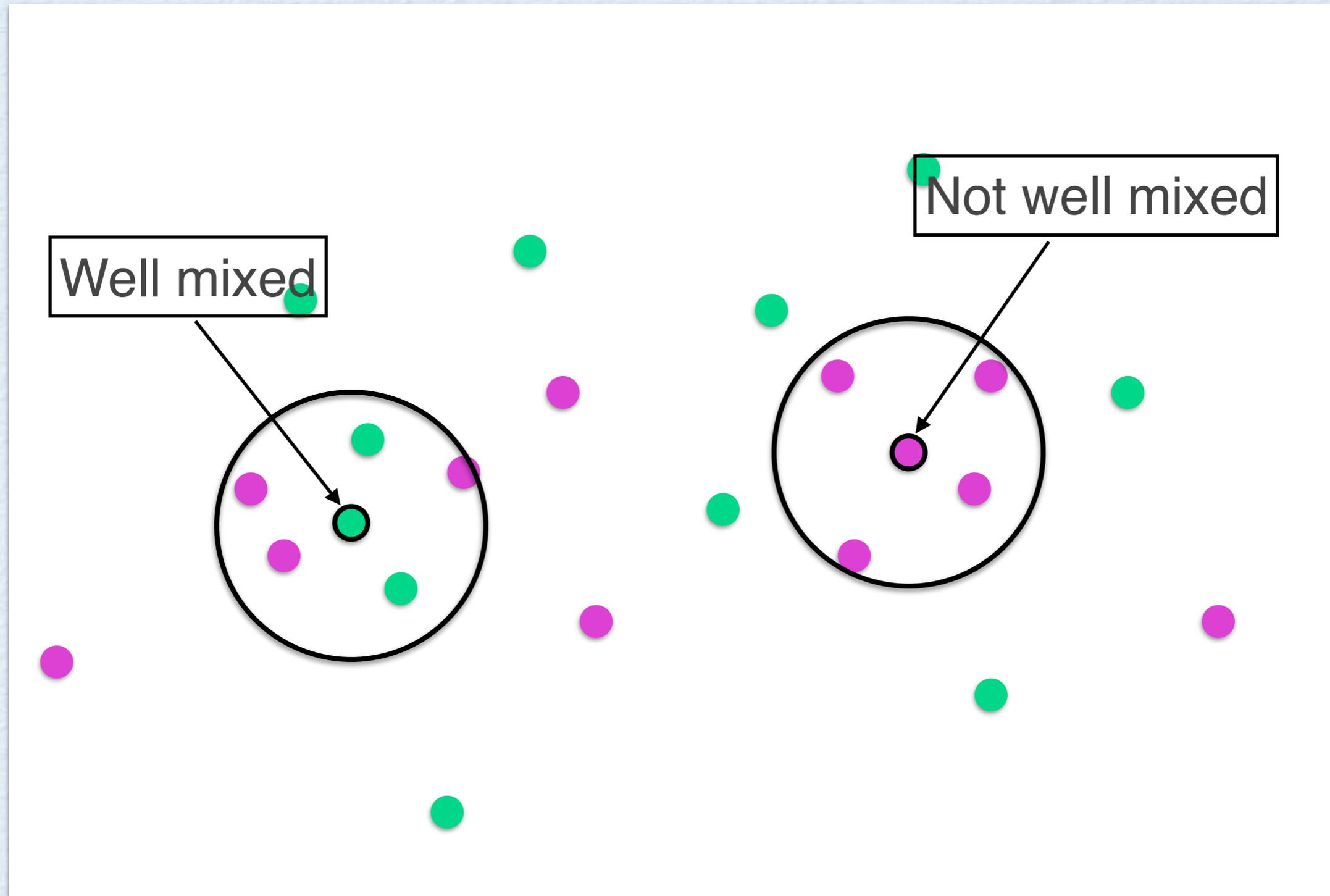
# Flux through a filter window



# Particle Mixing

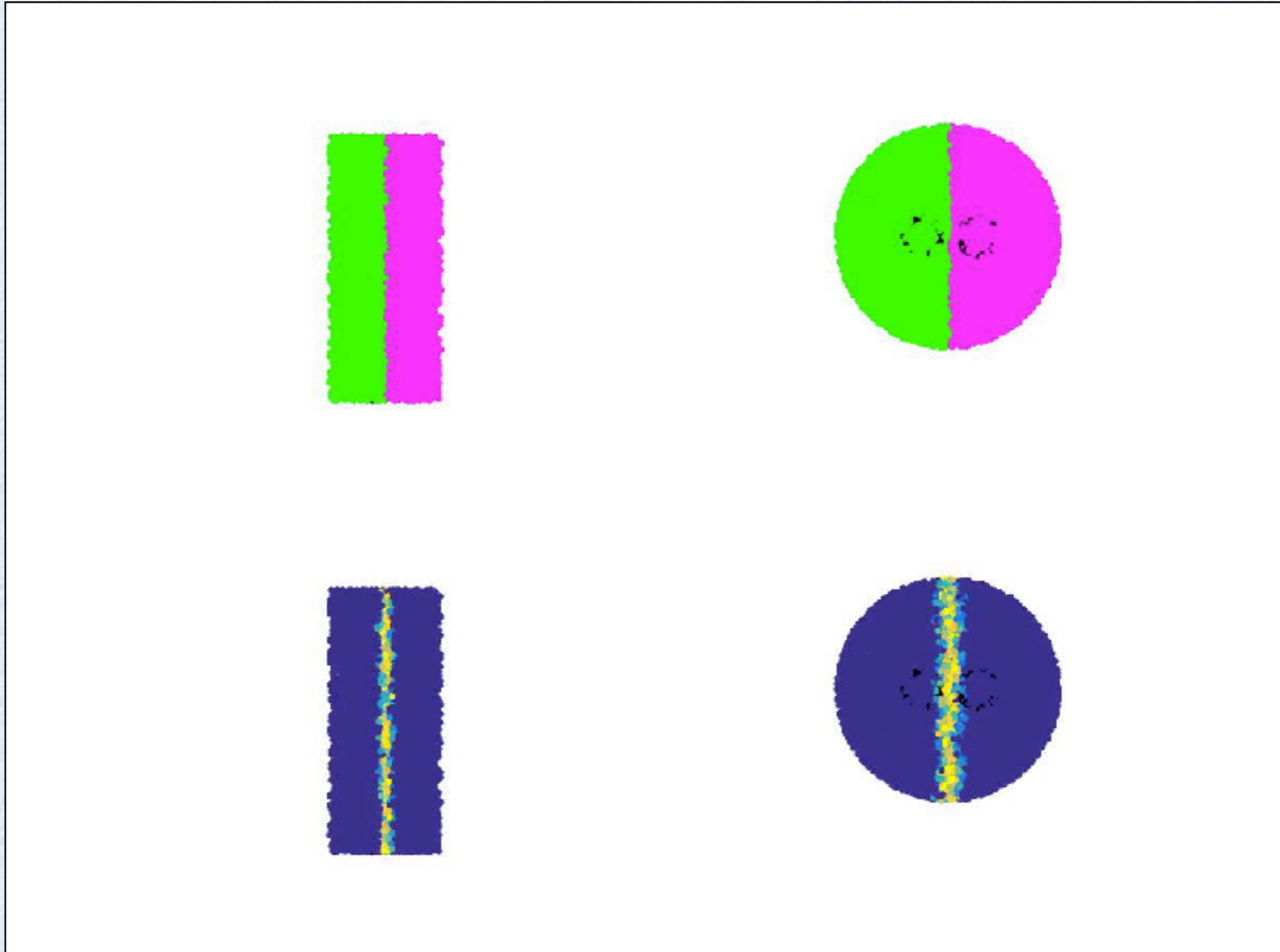


# Mixing Measure

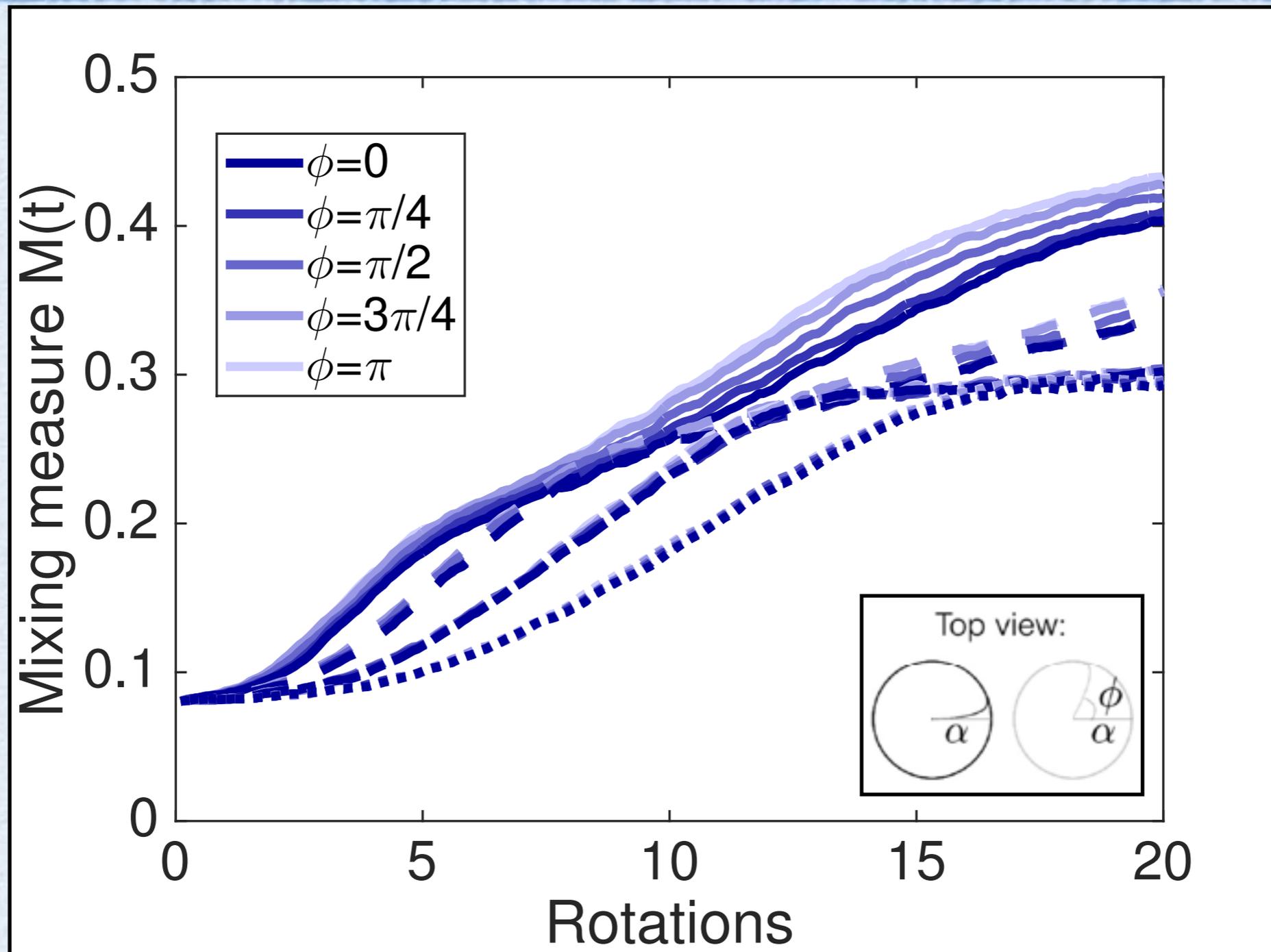


M. Robinson, P. Cleary, and J. Monaghan, AIChE journal 54, 1987 (2008)

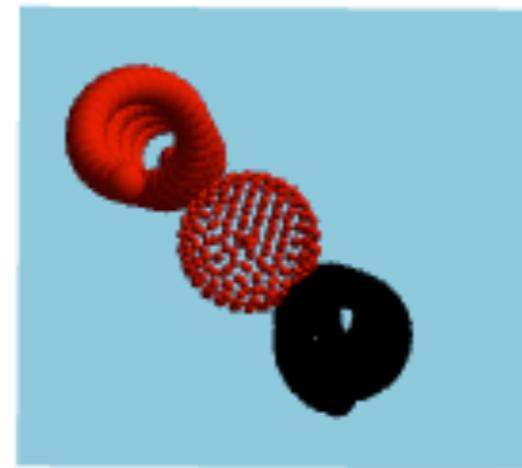
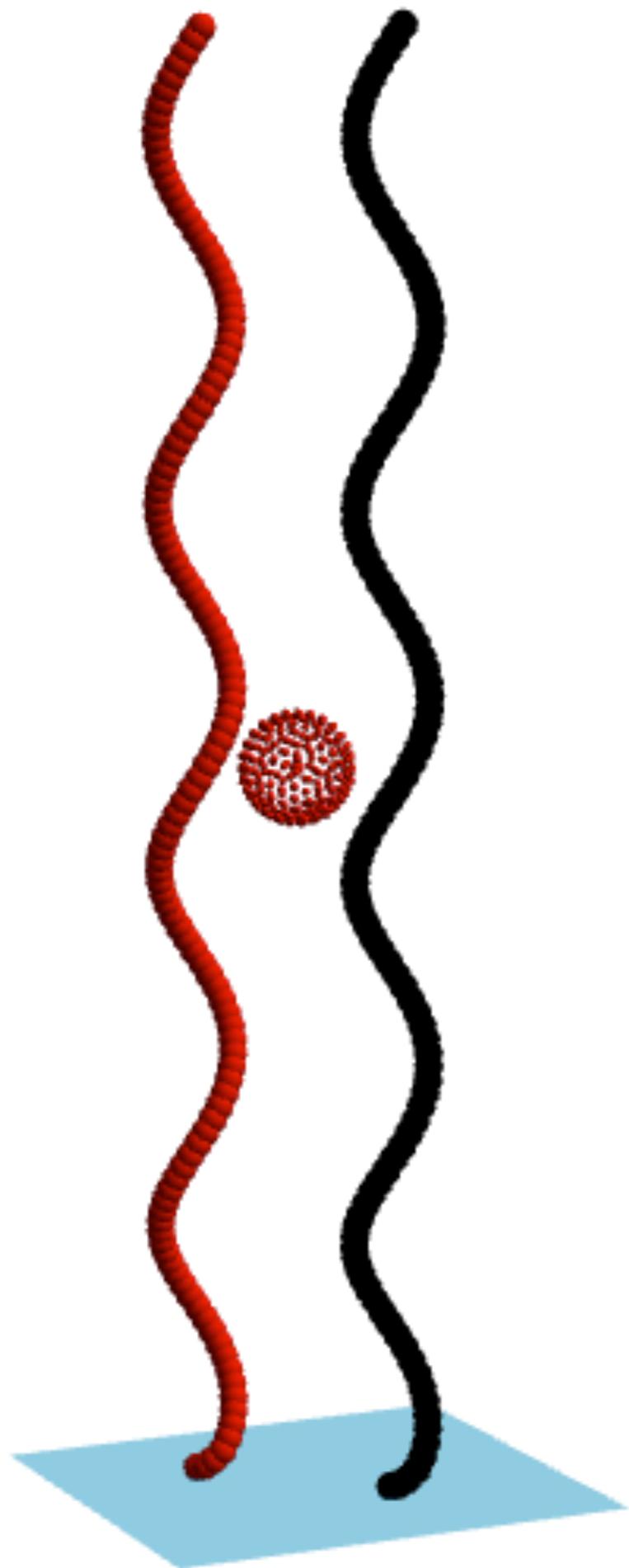
# Particle Mixing



# Mixing Measure



Line style denotes helical spacing  $d = 3\alpha$  (—),  $4\alpha$  (---),  $5\alpha$  (-·-),  $6\alpha$  (···)



# Summary and future work

- Develop a model of a collection of (rotating) helical flagella emanating from a planar wall
- Couple the flagella with elastic particles

## We examined:

- Mixing and pumping ability of fluid near flagella
- Flow structure around the rotating flagella
- Interesting dynamics induced by multiple rotating helices

Are two helices twice as effective as one helix?

## Future work

- Biologically calibrate parameters
- Flow through channels of bacterial carpets
- Lagrangian coherent structure

# Acknowledge

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**Thank you!**

where discussions of this work first began.